BUCHER automation

User Manual



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JetControl 440EXT

Controller

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Translation of the german original User Manual

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1 Introduction

1.1 Information on this document

This document forms an integral part of the product and must be read and understood prior to using it. It contains important and safety-related information for the proper use of the product as intended.

Target Groups

This document is intended for specialists with appropriate qualifications.
Only competent and trained personnel are allowed to put this device into operation.
During the whole product life cycle, safe handling and operation of the device must be ensured. In the case of missing or inadequate technical knowledge or knowledge of this document any liability is excluded.

Availability of Information

Make sure this document is kept at the ready in the vicinity of the product throughout its service life.
For information on new revisions of this document, visit the download area on our website. This document is not subject to any updating service.

Start | www.bucherautomation.com

For further information refer to the following information products:

– Online help for the JetSym software
  Functions of software products with application examples
– Application-oriented manuals
  Product-independent documentation
– Version updates
  Information about changes to the software products and operating system of your device

ⓘ Info

Further information

For further information on the noise immunity of a system, please refer to the Application Note 016 *EMC-Compatible Installation of the Electric Cabinet* available for download on www.bucherautomation.com.

ⓘ Info

EtherCAT®

EtherCAT® is a registered trademark and patented technology, licensed by Beckhoff Automation GmbH, Germany.

1.2 Typographical conventions

This manual uses different typographical effects to support you in finding and classifying information. Below, there is an example of a step-by-step instruction:

✓ This symbol indicates requirements which have to be met before executing the following action.

► This sign or a numbering at the beginning of a paragraph marks an action instruction that must be executed by the user. Execute the instructions one after the other.

⇨ The target after a list of instructions indicates reactions to, or results of these actions.

ⓘ Info

Further information and practical tips

In the info box you will find helpful information and practical tips about your product.

2 Safety

2.1 General Information

The product corresponds to the current state of science and technology when placed on the market.
In addition to this user manual, the laws, regulations and directives of the country of operation or the EU apply to the operation of the product. The operator is responsible for compliance with the relevant accident prevention regulations and generally recognized safety rules.

2.2 Purpose

2.2.1 Intended use

This device has been designed to control machinery, such as conveyors, production machines, and handling machines.

Operate the device only in accordance with the intended conditions of use and within the limits set forth in the technical specifications.
Intended use of the product includes its operation in accordance with this manual.

SELV

The operating voltage of this device is classified as Safety Extra Low Voltage and is, therefore, not subject to the EU Low Voltage Directive. The device may only be operated from a SELV source.

2.2.2 Usage other than intended

This device must not be used in technical systems which to a high degree have to be fail-safe.

Machinery Directive

This device is no safety-related part as per Machinery Directive 2006/42/EC, and must, therefore, not be used for safety-relevant applications. This device is NOT intended for the purpose of personal safety, and must, therefore, not be used to protect persons.

2.3 Warnings used in this document

⚠ DANGER



High risk

Indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury.

⚠ WARNING



Medium risk

Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.

⚠ CAUTION



Low risk

Indicates a hazardous situation which, if not avoided, could result in minor or moderate injury.

NOTICE



Material damage

Indicates a situation which, if not avoided, could result in malfunctions or material damage.

3 Product Description

The JC-440EXT is a modular control system in the upper performance range. Thanks to its high performance it can be used in all areas of industrial automation.

Besides traditional control functions, the JC-440EXT with its optional motion control functions also lets you program servo drives as point-to-point axes, axis groups and complex path controls.

Thanks to the flexible option model, the range of functions can also be extended at a later date.

3.1 System overview

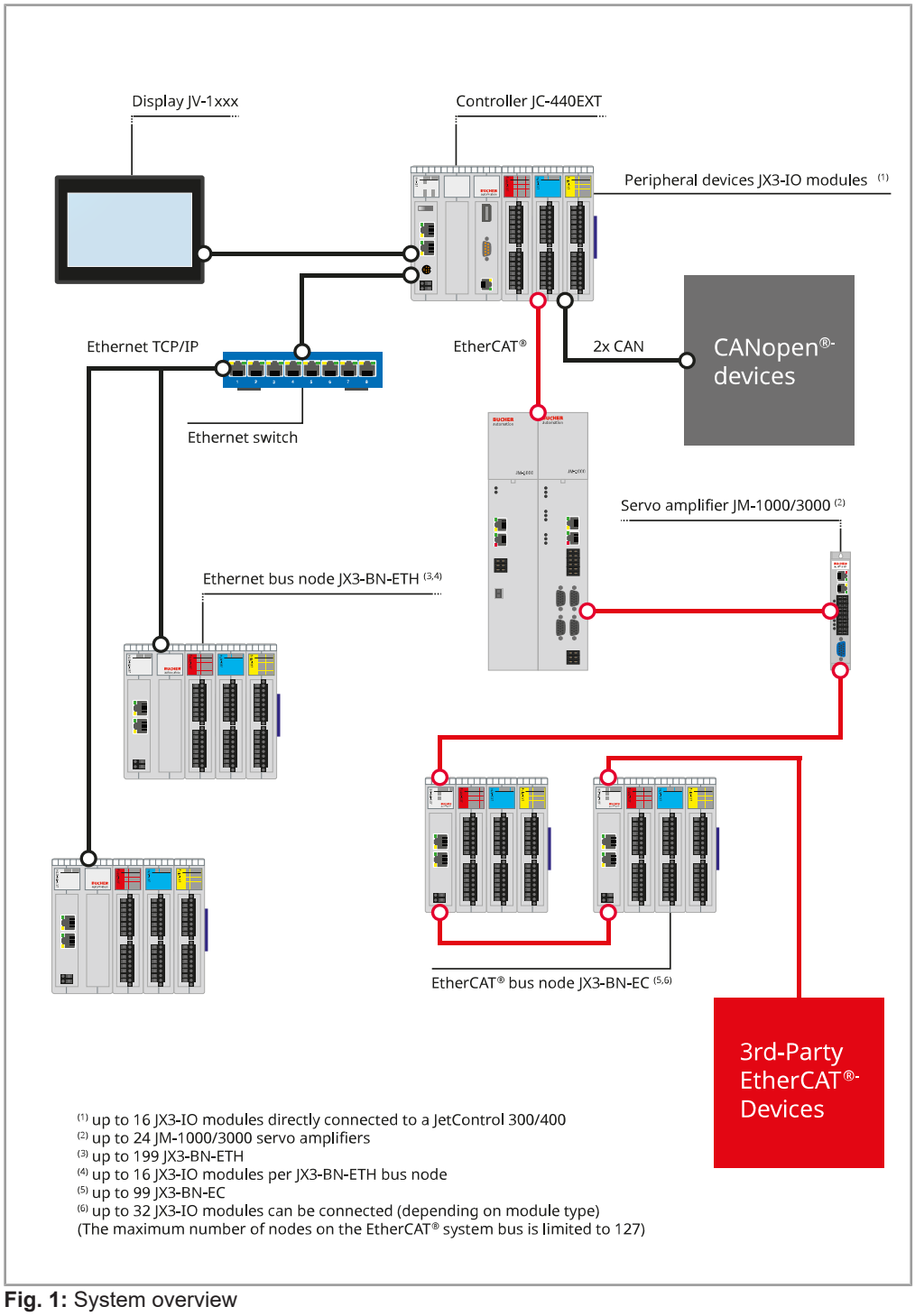


Fig. 1: System overview

3.2 Design

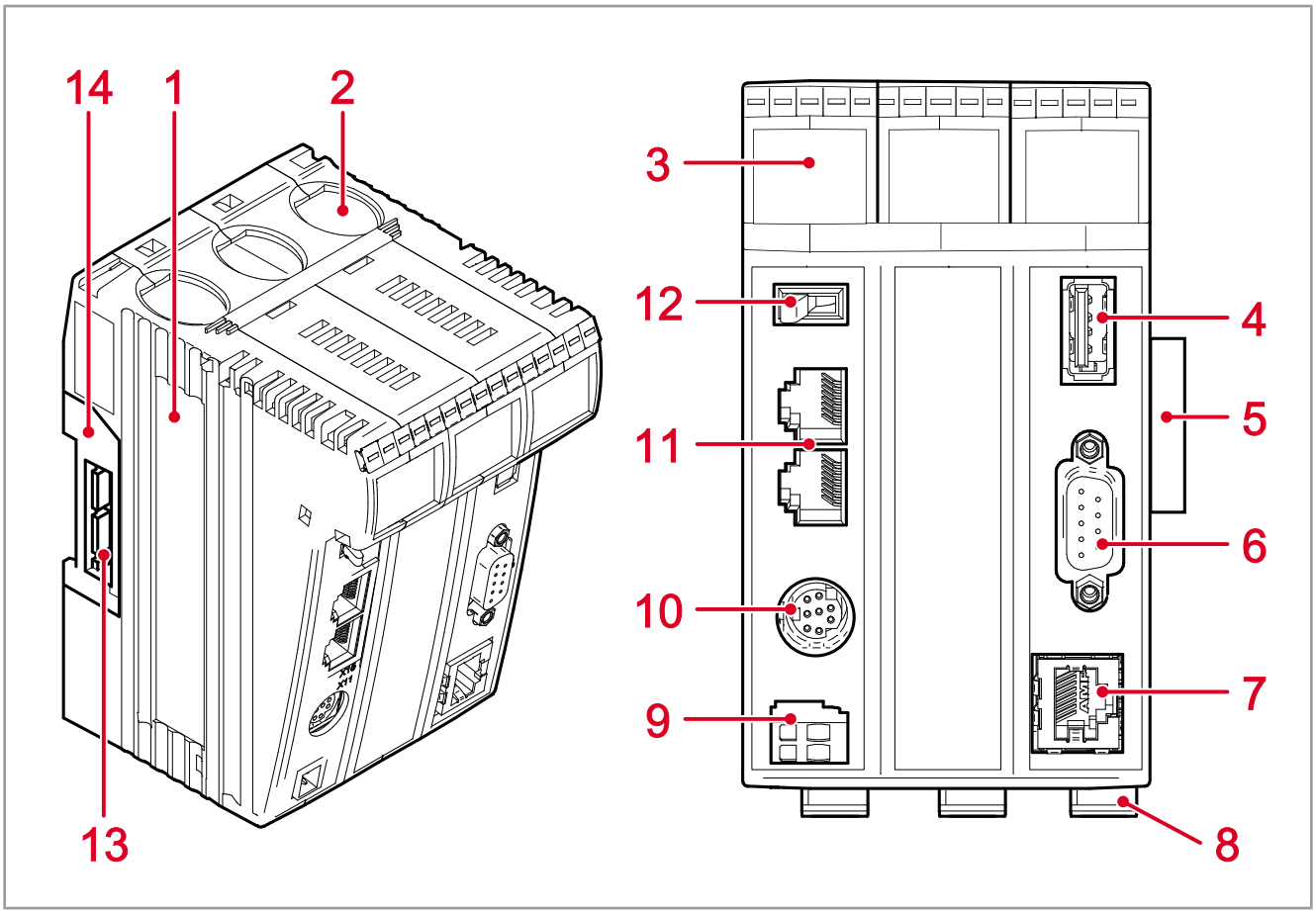


Fig. 2: Design

1	Position of the nameplate [▶ 14]
2	Latch
3	Status indication [▶ 12]
4	Port X61: USB port [▶ 38]
5	X119 connector: Interface to JX3-IO modules
6	Port X19: CAN bus interface [▶ 36]
7	Port X16: EtherCAT port [▶ 35]
8	DIN rail release latch
9	Terminal X10: Power supply [▶ 32]
10	Port X11: Serial port [▶ 33]
11	Ports X14, X15: Ethernet port [▶ 35]
12	Selector S11: Mode selector [▶ 31]
13	Port X118: Connects to expansions
14	Backplane module with DIP switches

3.3 Product Features

– Supports up to 24 servo axes including path and technology functions (options)*
– Up to 256 local I/Os (allows for expansion to > 65,000 I/Os)
– 32 MB STX program/data memory
– 480,000 bytes non-volatile memory
– 1 x Ethernet port with integrated switch
– EtherCAT® (option)*
– 2 x CANopen
– 1 x serial interface
– 1 x USB 2.0 (for storage media)
– Web server
– Email client (option)*
– Modbus/TCP (option)*
– OPC UA server (option)*
– MQTT (option)*
– STX high-level language programming to the IEC 61131-3 standard
– Multitasking
– File handling
– String processing

*See also Option model [▶ 83]

3.4 Status indication

Status indication LEDs indicate the communication status of the device as well as the status of the power supply.

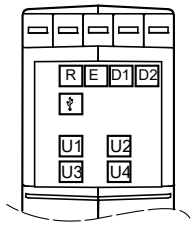


Fig. 3: Status indication

LED	Description
R	State of operating system
E	General error
D1	Special states
D2	State of boot loader
USB	State of the USB port
U1 … U4	Application-specific programming is possible

3.4.1 Diagnostics capabilities by means of status indication

Color and status of the LEDs are an excellent source of information for analyzing various states. In the JetSym programming tool, diagnostics can be performed in the Hardware Manager or via the Setup pane by entering the corresponding register number.

LED	Status	Color	Description
R	OFF	---	No power supply or defective.
	Blinking at 1 Hz	Green	Either the controller is still booting up, or it does not execute the application program.
	Blinking at 4 Hz	Green	Reset or fatal error.
	ON	Green	Application program is being executed.
E	OFF	---	No error occurred.
	Blinking at 1 Hz	Red	There is no valid OS.
	Blinking at 4 Hz	Red	Reset, fatal error, or checking the network consistency.
	ON	Red	Error; refer to error register.
D1	OFF	---	Normal operating condition.
	Blinking at 1 Hz	Red	Automatic IP configuration; AutoCopy function is completed, or first half of start delay is being executed.
	Blinking at 4 Hz	Red	Reset; fatal error, or second half of start delay is being executed.
	ON	Red	**autocopy.ini** file is being executed.
D2	OFF	---	Boot loader is not running.
	Blinking at 1 Hz	Red	Boot loader: Automatic IP configuration.
	Blinking at 4 Hz	Red	Reset or fatal error.
	ON	Red	Boot loader is being executed.

3.4.2 LED states during the boot process

If the following requirements are met, the controller boots without error:

– Mode selector S11 must be in RUN position.
– There is a valid OS.
– There must be a valid application program.

The LED flashing patterns indicate the different stages of the boot process.

R	E	D1	D2	State
Step 1				**Reset**
Green	Red	Red	Red	Reset
4 Hz	4 Hz	4 Hz	4 Hz	
Step 2				**Operating system**
Green	-	-	Red	The device initializes the OS.
1 Hz	OFF	OFF	ON	

R	E	D1	D2	State
Step 3				**Parser**
Green	-	-	-	The OS reads the settings of the DIP switch on the backplane module and checks whether an Ethernet switch exists.
1 Hz	OFF	OFF	OFF	
Step 4				**Interfaces and programs**
Green	Red	-	-	The OS initializes real-time clock, Ethernet interface and file system.
1 Hz	ON	OFF	OFF	
Step 5				**Application program**
Green	Red	Red	-	The OS initializes the modules on the system bus, as well as software features (Web, Modbus/TCP, etc.). Then it loads the application program.
1 Hz	ON	ON	OFF	
Step 6				**Operating state**
Green	-	-	-	The operating state is displayed
1 Hz	OFF	OFF	OFF	Logic voltage supply is OK; application program has been stopped
ON	OFF	OFF	OFF	Logic voltage supply is OK; application program is running

Tab. 1: LED states during the boot process

3.5 Nameplate

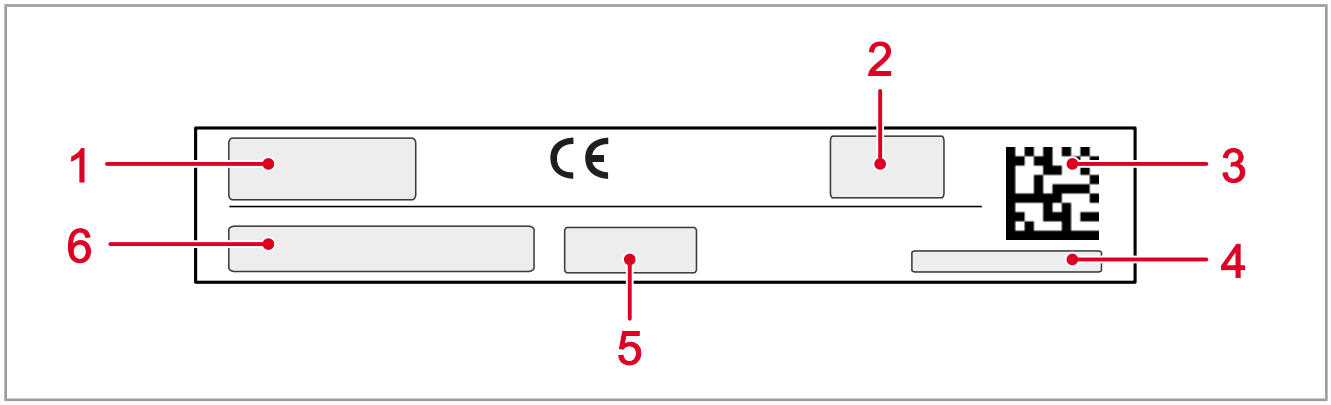


Fig. 4: Sample nameplate

1	Company logo
2	Power supply specifications
3	DataMatrix code
4	Serial number
5	Hardware revision
6	Item name

ⓘ Info

Data matrix code

The DataMatrix code on the name plate takes you to an Internet page where the controller options and license files can be downloaded.

3.6 Scope of delivery

Scope of delivery	Item number	Quantity
JC-440EXT *base model, no options, scalable with* JCF options	10001740	1
OR		
JC-440EXT *configured with* JCF options	depending on configuration	1
OR		
JC-440EXT-MAX *fully equipped, incl. all* JCF options currently available	10002789	1
AND		
Male connector in spring-cage technology, 2-pin	60870409	1
Terminal labels	60870411	10
Keying pins	60870410	1
Product Documentation Note	60888123	1

4 Technical Specifications

This chapter contains information on both electrical and mechanical data as well as on operating data of the JC-440EXT device.

4.1 Dimensions

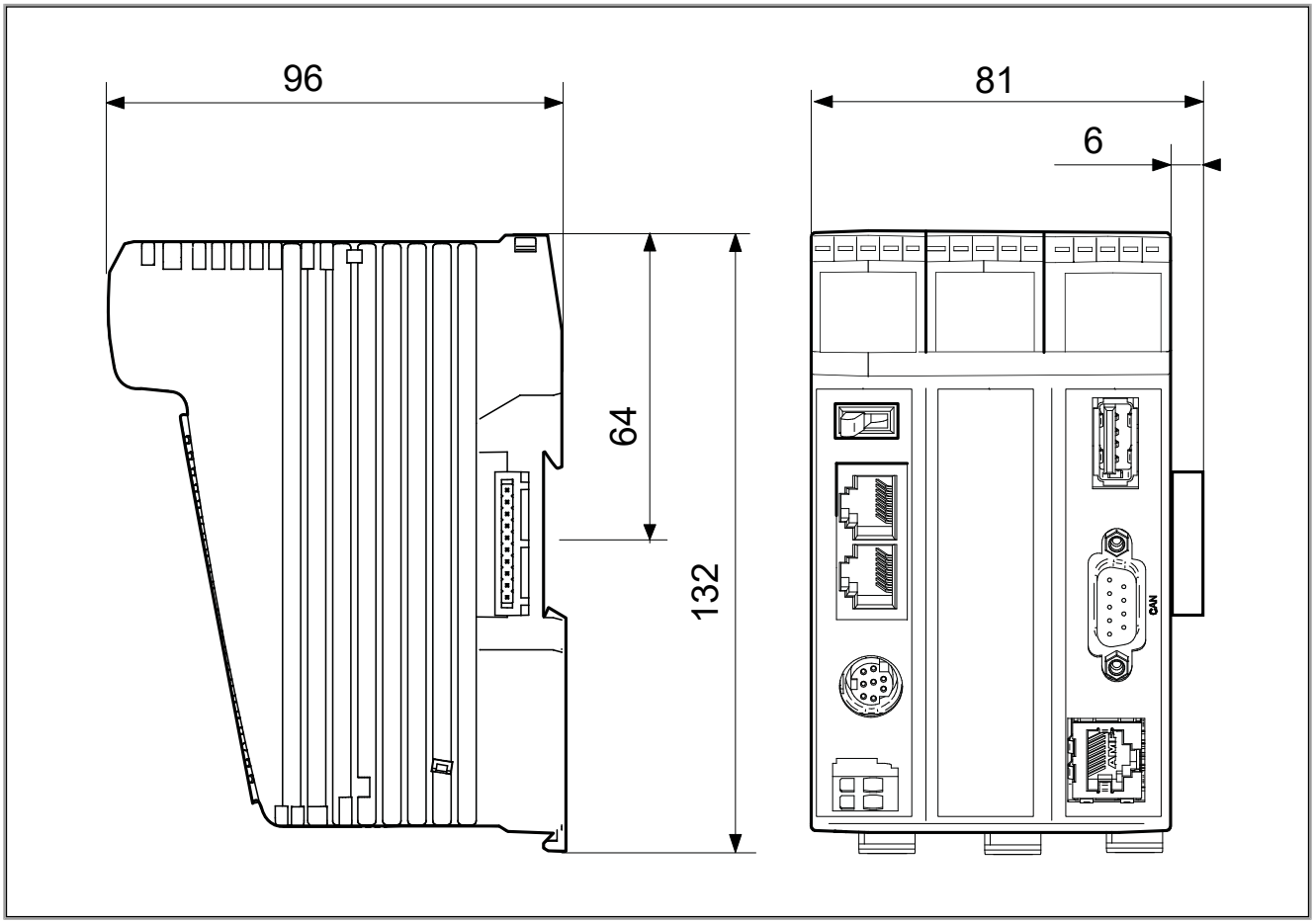


Fig. 5: Dimension in mm

Info

CAD data

For CAD data go to www.bucherautomation.com and navigate to the product page *JC-440EXT > Downloads*.

4.2 Mechanical Specifications

Parameter	Description	Standards
Mounting orientation	Vertically mounted on DIN rail	
Weight	365 g	
Enclosure specifications		
Material	Plastic	
Maximum height of fall		
with shipping packaging	1 m	DIN EN 61131-2 DIN EN 60068-2-31
with product packaging	0.3 m	
Vibration resistance		
Frequency sweeps	1 octave/minute, sinusoidal	DIN EN 61131-2 DIN EN 60068-2-6
Constant amplitude	3.5 mm	5 Hz ≤ f ≤ 9 Hz
Constant acceleration	1 g	9 Hz ≤ f ≤ 150 Hz
Number and direction	10 sweeps for all 3 spatial axes	
Shock resistance		
Type of shock	Half-sine wave	DIN EN 61131-2 DIN EN 60068-2-27
Intensity and duration	15 g for 11 ms	
Number and direction	3 shocks in the directions of all 3 spatial axes	
Degree of protection		
Degree of protection	IP20	DIN EN 60529

Tab. 2: Mechanical specifications

4.3 Electrical properties

Power supply (terminal X10)

Parameter	Description
Supply voltage	DC 24 V
Permissible voltage range	-15 % … +20 %
Reach	Power supply for the controller and a maximum of 8 connected expansion modules, as well as for one HMI
Input current	
Without HMI	2.1 A max
With HMI	2.3 A max
Power consumption	
Without HMI	50 W max
With HMI	55 W max

Tab. 3: Power supply (terminal X10)

Serial interface (port X11)

Parameter	Description
Terminal type	MiniDIN, shielded
Total of pins	8
Electrical isolation	None
Number of interfaces	1
Interface standards	RS-232/RS-422/RS-485-2
Baud rates	1,200 ... 115,200 baud
Bits per character	5, 6, 7, 8
Number of stop bits	1, 2
Parity	Even, odd, none
Max. line length	< 30 m

Tab. 4: Serial interface (port X11)

Ethernet ports (X14, X15)

Parameter	Description
Terminal type	RJ45 jack
Port count	2
	Interconnected via internal switch
Bit rate	10 Mbit/s, 100 Mbit/s (Cat 5e)
Auto-crossover	Yes

Tab. 5: Ethernet ports (X14, X15)

EtherCAT® port (X16)

Parameter	Description
Terminal type	RJ45 jack
Port count	1
Bit rate	100 MBit/s (Cat 5e)
Auto-crossover	Yes

Tab. 6: EtherCAT® port (X16)

CAN bus interface (X19)

Parameter	Description
Terminal type	Female Sub-D connector
Total of pins	9
Electrical isolation	None

Tab. 7: CAN bus interface (X19)

USB port (X61)

Parameter	Description
Memory type	Standard USB flash drive
Memory size	2 GB ... 64 GB
Drive format	FAT (-12, -16, -32)
USB version	1.1 and 2.0

Tab. 8: USB port (X61)

Memory configurations

Parameter	Description
Non-volatile memory for variables	480,000 bytes
	corresponds to 120,000 application registers (32-bit)
STX program memory	32 MB
	volatile variable memory included
Flash disk	32 MB

Tab. 9: Memory configurations

Electrical safety

Parameter	Description	Standards
Class of protection	III	DIN EN 61131-2
Dielectric test voltage	Functional ground is internally connected to the device ground	
Protective connection	0	
Overvoltage category	II	

Tab. 10: Electrical safety

4.3.1 System power supply

The controller supplies the local system bus with logic and power supply voltage.

These two types of voltage are for supplying the connected expansion modules.

System bus

Parameter	Description
Bus type	JX3 system bus
Logic voltage	
Supply voltage	DC +5 V
Permissible voltage range	-15 % ... +10 %
Additional voltage	
Supply voltage	DC +24 V
Permissible voltage range	-15 % ... +20 %

Tab. 11: System bus

Connected JX3 IO modules

Parameter	Description
Logic voltage	
Current consumption	I_{5V} = max. 1,200 mA
Power consumption	6 W max.
Additional voltage	
Current consumption	$I_{24\ V}$ = max. 750 mA
Power consumption	18 W max.

Tab. 12: JX3 IO modules on the system bus

4.4 Real-time clock

Parameter	Description	
Power reserve (if the controller was previously switched on for at least 1 hour)	Minimum	1 week
	Typically	2 weeks
Deviation	maximum	1 minute per month

Tab. 13: Real-time clock

4.5 Environmental Conditions

Parameter	Description	Standards
Operating temperature	0 °C … +50 °C	DIN EN 61131-2
Storage temperature	-40 °C … +70 °C	DIN EN 60068-2-1
Humidity	10 % … 95 %, non-condensing	DIN EN 60068-2-2
Max. operating altitude	2,000 m above sea level	DIN EN 61131-2
Corrosion immunity and chemical resistance	No special protection against corrosion. Ambient air must be free from higher concentrations of acids, alkaline solutions, corrosive agents, salts, metal vapors and other corrosive or electroconductive contaminants.	
Degree of pollution – Electronics	Level 2	DIN EN 61131-2
	Usually, the pollution is non-conductive. However, temporary conductivity due to condensation may occur.	

Tab. 14: Environmental conditions

4.6 EMC Values

4.6.1 Housing

Emitted interference

Parameter	Values	Standards
Frequency band	**30 MHz … 230 MHz**	DIN EN 61000-6-3 DIN EN 61131-2 DIN EN 55011
Limit value	30 dB (µV/m) at 10 m distance	
Frequency band	**230 MHz … 1,000 MHz**	
Limit value	37 dB (µV/m) at 10 m distance	
	Class B	

Tab. 15: Emitted interference

Immunity to interference

Parameter	Values	Standards
Magnetic field with mains frequency		
Frequency	50 Hz	DIN EN 61131-2 DIN EN 61000-6-2 DIN EN 61000-4-8
Magnetic field	30 A/m	
RF field, amplitude-modulated		
Frequency band	80 MHz … 1 GHz	DIN EN 61131-2 DIN EN 61000-6-2 DIN EN 61000-4-3
	1.4 GHz ... 2.0 GHz 3 V/m	
	2.0 GHz … 2.7 GHz 1 V/m	
Test field strength	10 V/m	
	AM 80 % with 1 kHz	
	Criterion A	
ESD		
Discharge through air: Test peak voltage	8 kV	DIN EN 61131-2 DIN EN 61000-6-2 DIN EN 61000-4-2
Discharge through air Test peak voltage	4 kV	
	Criterion A	

Tab. 16: Immunity to interference

4.6.2 Shielded data and I/O lines

Immunity to interference

Parameter	Values	Standards
RF field, asymmetric, amplitude modulated		
Frequency band	0.15 MHz … 80 MHz	DIN EN 61131-2 DIN EN 61000-6-2 DIN EN 61000-4-6
Test voltage	10 V	
	AM 80 % at 1 kHz	
Source impedance	150 Ω	
	Criterion A	
Bursts		
Test voltage	1 kV	DIN EN 61000-6-2 DIN EN 61000-6-2 DIN EN 61000-4-4
	tr/tn 5/50 ns	
Repetition frequency	5 kHz	
	Criterion A	
Surge voltages, asymmetric, line to earth		
Common-mode interference	tr/th 1.2/50 µs	DIN EN 61131-2 DIN EN 61000-6-2 DIN EN 61000-4-5
	1 kV	

Tab. 17: Immunity of shielded data and I/O lines

4.6.3 DC power supply inputs and outputs

Immunity to interference

Parameter	Values	Standards
Radio frequency, asymmetric, amplitude-modulated		
Frequency band	0.15 MHz … 80 MHz	DIN EN 61131-2 DIN EN 61000-6-2 DIN EN 61000-4-6
Test voltage	10 V	
	AM 80 % with 1 kHz	
Source impedance	150 Ω	
	Criterion A	
Bursts		
Test voltage	2 kV	DIN EN 61131-2 DIN EN 61000-6-2 DIN EN 61000-4-4
	tr/tn 5/50 ns	
Repetition frequency	5 kHz	
	Criterion A	
Surge voltages, symmetric, line to cable		
Series-mode interference	tr/th 1.2/50 µs	DIN EN 61131-2 DIN EN 61000-6-2 DIN EN 61000-4-5
	0.5 kV	
Surge voltages, asymmetric, line to earth		
Common-mode interference	tr/th 1.2/50 µs	DIN EN 61131-2 DIN EN 61000-6-2 DIN EN 61000-4-5
	0.5 kV	

Tab. 18: DC power supply inputs and outputs

5 Mechanical Installation

This chapter describes how to install and remove the JC-440EXT.

NOTICE



Damaged devices

Damaged devices may cause considerable physical damage.

- ► Check the device for external damage and faulty connections.
- ► Ensure to install only fully functional devices.

5.1 Installing Device on DIN Rail

NOTICE



Unsuitable expansion modules at X118 and X119 can damage the device

Connecting unsuitable expansion modules to the X118 and X119 connections can lead to the destruction of the controller and the expansion modules.

- ► **Only** connect suitable JX3 expansion modules to X119 (right-hand side of the controller), **no** communication modules or other modules.
- ► Do **not** connect **any** JX3 expansion modules or controllers to X118 (left-hand side of the controller).

NOTICE



Functional impairment caused by unfavorable installation

- ► Install the device only in vertical position on the DIN rail (DIN EN 60715).
- ► Keep a minimum distance of 30 mm to surrounding parts.

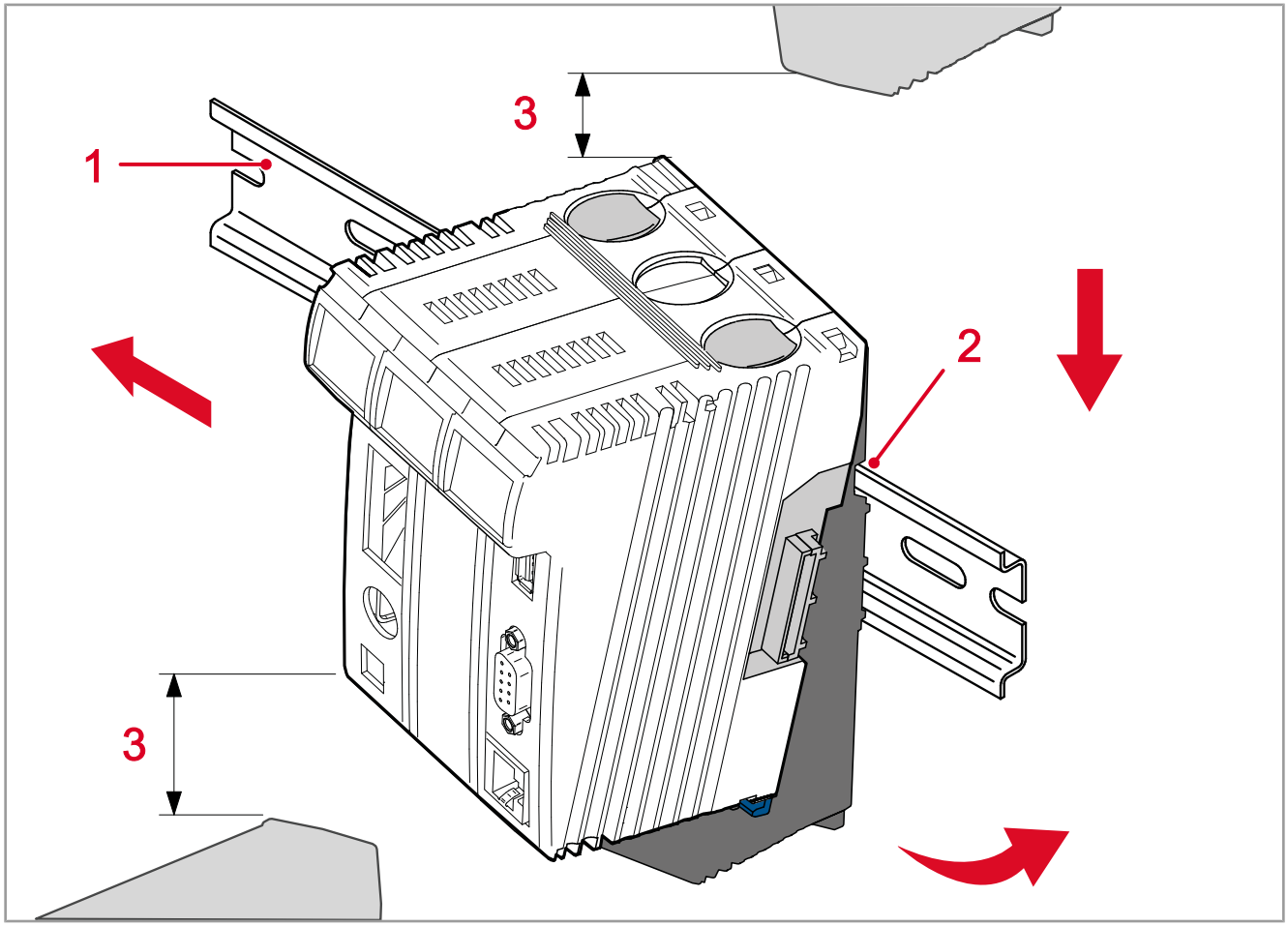


Fig. 6: Installing the device on the DIN rail

1	DIN rail
2	Upper latch
3	Minimum distance to surrounding parts (30 mm min.)

1. Disconnect the system from the power supply.
2. Place the upper latch (2) in an angled position on the DIN rail (1).
3. Snap the lower latch of the device onto the DIN rail.
4. Slide the device on the DIN rail to its intended position.

5.2 Removing Device from DIN Rail

Applying force to the release latch disengages the device from the DIN rail.

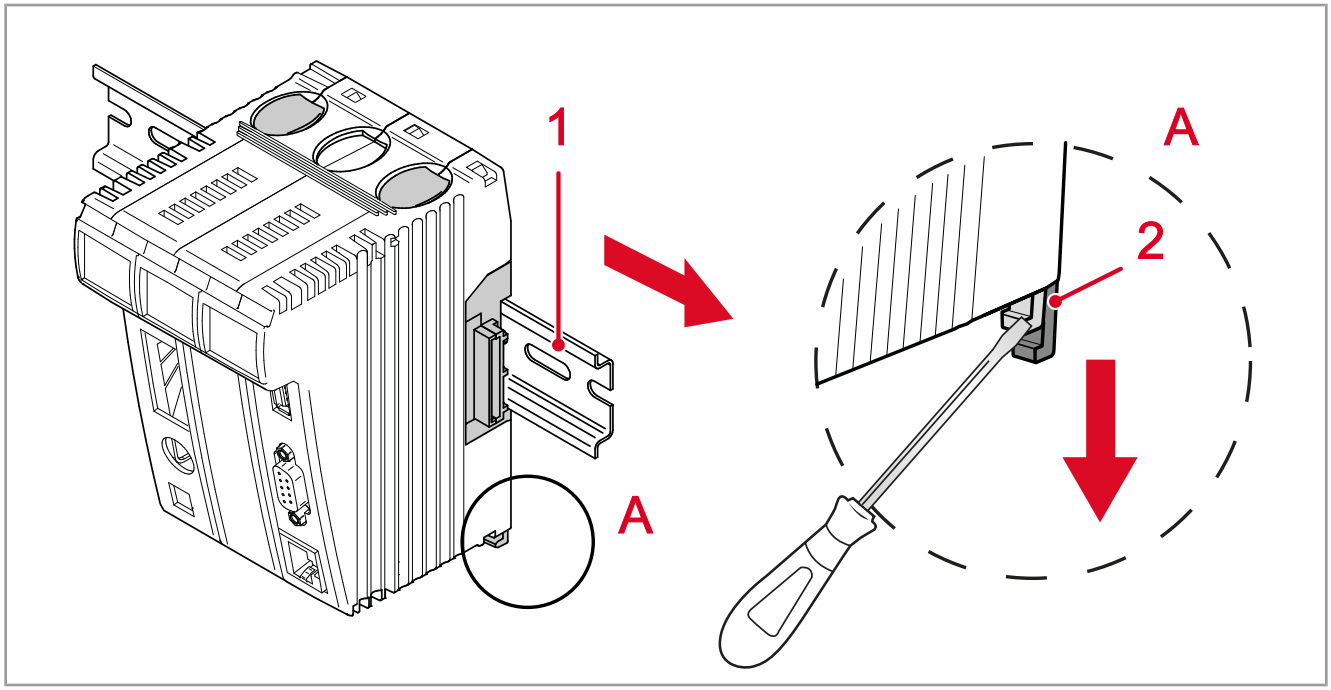


Fig. 7: Removing the device from the DIN rail

1	DIN rail
2	DIN rail release latch
A	Detail view

1. Disconnect the system from the power supply.
2. Pull the device off the overall assembly.
3. Pry the release latch (2) downwards and pull the device off the DIN rail (1).

5.3 Dismounting Enclosure from Backplane Module

Pressing down on the upper and the lower backplane latches of the device allows you to remove the enclosure from the backplane module.

NOTICE

Mechanical damage and reduced EMC noise immunity

If devices are replaced, degree of protection IP20 is not ensured. Touching the EMC clip may lead to mechanical damage to the device and reduced EMC noise immunity.

► Do not touch any electronic components once the enclosure has been removed from the backplane module.

The following information is retained on the backplane module:

- IP address
- Subnet mask
- Gateway
- DNS server
- Controller name
- File name for the AutoCopy function
- IP port numbers for the debug server and the IP server

Switching Between Controller Models

Any controller of the JetControl 400 series can be replaced by another controller model of this series.

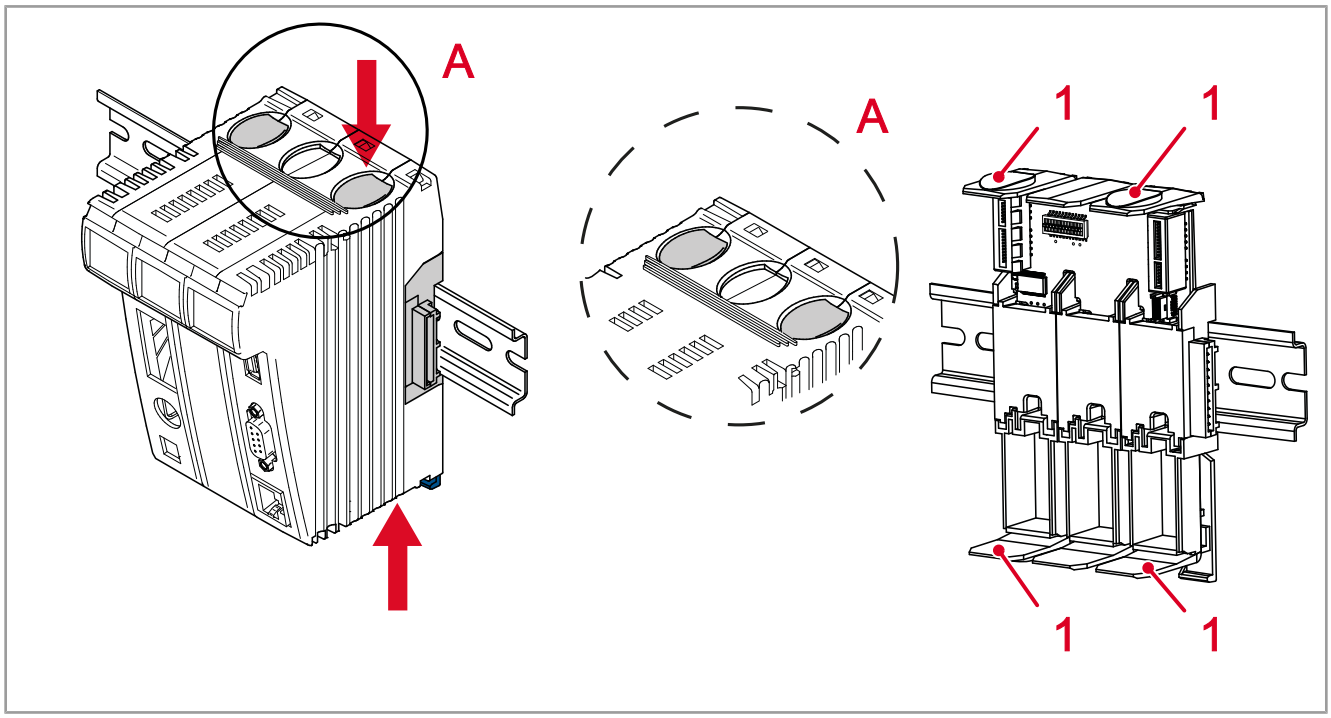


Fig. 8: Removing the enclosure from the backplane module

A	Detail view
1	Latch

1. Disconnect the system from the power supply.
2. Simultaneously, press and hold the upper and lower latches (1) of the device.
3. With the latches pressed down pull the enclosure away from DIN rail.

6 Electrical Connection

NOTICE



Damages to material or functional impairment

Improper implementation of the wiring harness may cause mechanical stress.

- ► Protect the cables from bending, twisting or chafing.
- ► Install strain reliefs for the connecting cables.

NOTICE



Unsuitable expansion modules at X118 and X119 can damage the device

Connecting unsuitable expansion modules to the X118 and X119 connections can lead to the destruction of the controller and the expansion modules.

- ► **Only** connect suitable JX3 expansion modules to X119 (right-hand side of the controller), **no** communication modules or other modules.
- ► Do **not** connect **any** JX3 expansion modules or controllers to X118 (left-hand side of the controller).

6.1 Improving EMC Noise Immunity

A system's immunity to noise is determined by its weakest component. Key factors are correct connections, lines and proper shielding. Take note of the measures described in this section.

ⓘ Info

Further information

For further information on the noise immunity of a system, please refer to the Application Note 016 *EMC-Compatible Installation of the Electric Cabinet* available for download on www.bucherautomation.com.

DIN rail

- – Attach the JC-440EXT device to a DIN rail to EN 60715 with the dimensions 35 x 7.5 mm.
- – The DIN rail must be electrically conducting and grounded by either of the following two ways:
  - – Directly
  - – Via rear panel of the electric cabinet

Application Note 016

Follow the instructions given in Application Note 016 *EMC-Compatible Installation of the Electric Cabinet*.

The following instructions are excerpts from Application Note 016:

- – Keep signal and power lines **separated from each other** at all times. Bucher Automation AG recommends that there be a minimum distance of 20 cm. Cables and lines should cross each other at an angle of 90°.

- Shield the following cables and lines:
  - Analog lines
  - Data lines
  - Motor cables coming from inverter drives (servo output stage, frequency converter)
  - Lines between components and interference suppressor filter, where the suppressor filter is located not immediately adjacent to the component.
- Place the shield **on both sides**.
- Keep unshielded wire ends of shielded cables as short as possible.
- Span the shield **entirely** across the isolation. For **wide-area grounding**, clamp it down tightly with an extensively earthed strain relief.

Use of Connectors

- Clamp the shield down **entirely** using the shielding clamp of the metalized connector enclosure (impedance shielding), or the EMC-compliant gland bushing. For **wide-area** grounding, clamp it down tightly using a strain relief.
- Only use metalized connectors, e.g. Sub-D with metalized enclosure. Make sure that the strain relief is directly connected with the enclosure.

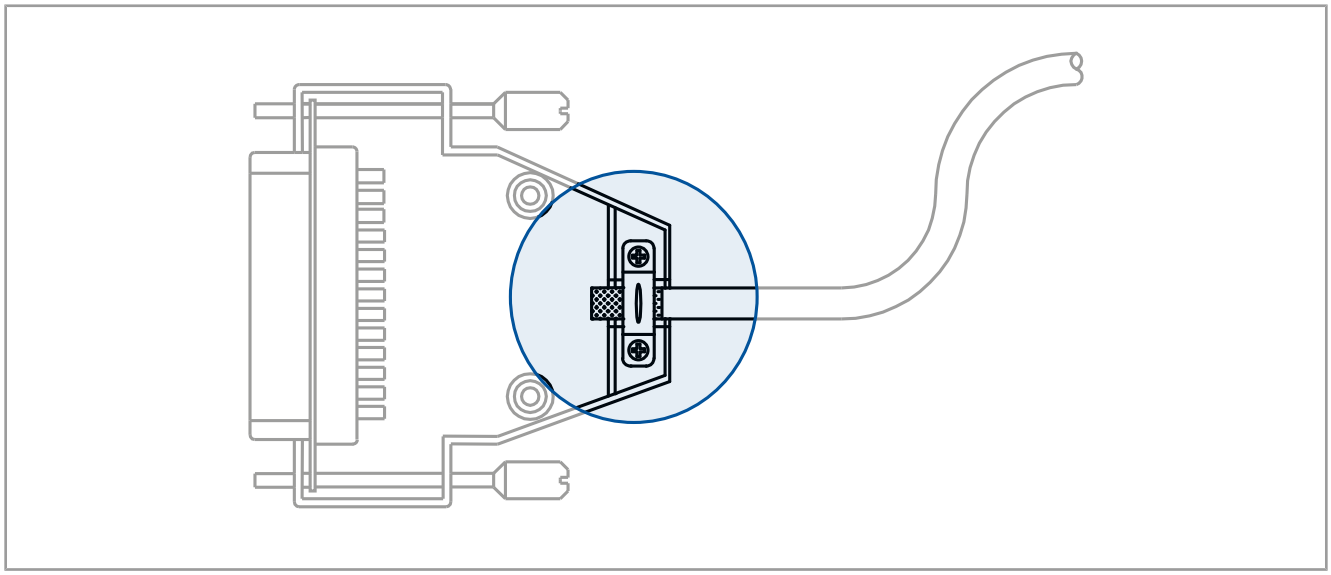


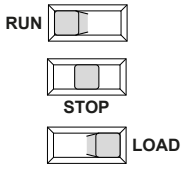
Fig. 9: Strain relief on the Sub-D enclosure

6.2 Interfaces

6.2.1 Selector switch S11 - Mode selector

The position of mode selector S11 is identified while the controller is booting up. The post-boot behavior of the controller depends on the mode selector position. Any changes made to the mode selector while the controller is running will have no effect on the operating mode.

Switch position



Operating mode	Description
RUN	The controller launches the application program.
STOP	The controller does not launch the application program.
LOAD	The controller does not launch the application program. The controller executes the AutoCopy function. Upon completion of the AutoCopy function, the controller requires rebooting.

Tab. 19: S11 mode switch positions

Functions of the mode selector

In checking the position of mode selector S11 the JC-440EXT proceeds in the following way:

Step	Description	
1	Power supply of the controller is at terminal X10.	
2	The boot loader of the controller checks the position of selector S11.	
	If ...	**... then ...**
	... mode selector S11 = *RUN* or *STOP*,	... the OS is launched; → proceed with step 4
	... selector S11 = *LOAD* position, and a USB flash drive has been inserted,	... the OS is launched; → proceed with step 3
	... selector S11 = *LOAD* position, and no USB flash drive has not been inserted,	... the boot loader waits until an OS update is carried out.
3	The controller loads the file **autocopy.ini**.	
	If ...	**... then ...**
	... the file could be loaded,	... the instructions contained in it are executed.
	... the file could not be loaded,	... the instructions cannot be executed.
4	The controller checks the position of selector S11.	
	If ...	**... then ...**
	... mode selector S11 = *RUN*,	... the application program is launched.
	... mode selector S11 = *STOP*,	... the application program does not start.
5	**If ...**	**... then ...**
	... the position of mode selector S11 is changed once the controller has been turned on,	... this has no effect on the functioning of the controller.

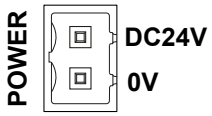
6.2.2 Terminal X10 - Power supply

Ports and interfaces

X10 lets you connect the following devices:

– Voltage supply for the JC-440EXT controller
– Voltage supply of the connected JX3 IO modules provided they are not supplied by a separate power supply module.
– Voltage supply of an HMI (LCD xxx) of the Bucher Automation AG connected to X11

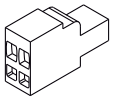
Pinning



Pin	Description
DC24V	Supply voltage
0 V	Reference potential (GND)

2-pin connector, spring-cage technology

The controller comes with a 2-pin spring-clamp connector.



Category	Description	Standards
Connector		
Designation	BU_02_E_BLZF_GE_RM3.5	
Connector technology	Spring-cage connection	
Type	2-pin, 3.5 mm pitch	
Connectible conductors		
Outer diameter of the isolation	2.90 mm max	
AWG	16 … 28	
Clamping range	0.13 … 1.5 mm²	
Stripping length	10 mm	
Specification without wire end ferrules		
Solid conductor	H05(07) V-U	
	0.2 … 1.5 mm²	
Flexible conductor	H05(07) V-K	
	0.2 … 1.5 mm²	
Specification with wire end ferrules		
Wire end ferrule without sleeve	0.2 … 1.5 mm²	DIN 46228/1
Wire end ferrule with sleeve	0.2 … 1.5 mm²	DIN 46228/4
Crimping tool	PZ 4, PZ 6 ROTO, PZ 6/5	DIN 46228

Tab. 20: Connector specification, 2-pin connector, spring-cage technology

6.2.3 Port X11 – Serial interface

Ports and interfaces

Port X11 lets you connect the following devices:

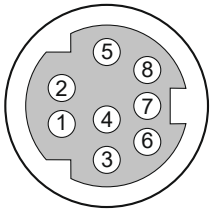
– PC
– Bucher Automation AG HMIs
– Any device with R-232/422/485 interface

ⓘ Info

Limitations

– While the device supports several different hardware drivers, only one hardware interface is available. This means: If communication takes place for example via RS-422, the system cannot communicate simultaneous and independently via RS-232.
– The maximum cable length is < 30 m.

Pinning



Pin	Signal	Description
1	RDA	RS-422; receive data inverted
2	GND	Reference potential
3	RDB	RS-422; receive data not inverted
4	RxD	RS-232; receive data
5	SDB	RS-422; transmit data not inverted RS-485; Transmit/receive data not inverted
6	DC24V	HMI supply voltage
7	SDA	RS-422; transmit data inverted RS-485; Transmit/receive data inverted
8	TxD	RS-232; transmit data

Cable for connector X11

To connect devices to port X11, you can order cables separately as accessories [▸ 140].

Schematic diagram of port X11

Position	Part	Function with RS-422	Function with RS-485
1	Receiver	Receives data	Unused
2	Receiver/transmitter	Transmits data	Receives and transmits data
3	Serial line	Twisted line of the serial interface	
4	R_T	Terminating resistor	

Terminating resistor

Connect a terminating resistor to both serial lines in the following cases:

– Long lines
– High baud rates

Select a terminating resistor which corresponds to the impedance of the line used.

Connecting alphanumeric displays and HMIs

The serial interface (port X11) of the JC-440EXT lets you connect HMIs by Bucher Automation.

ⓘ Info

Further information

For in-depth information, see the *Controlling Alphanumeric HMIs (LCD) and Printers* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

6.2.4 Ports X14, X15 - Ethernet

Ports and interfaces

Ports X14 and X15 let you connect the following devices:

- Ethernet port for connection of:
  - a PC
  - a HMI
  - an Ethernet bus node or COM module
  - any device with Ethernet TCP/IP interface (10/100 Mbits)

Pinning

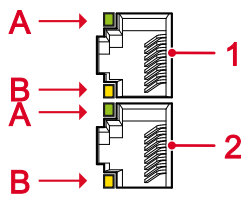


Fig. 10: Ports X14, X15

Position	Socket	LED	Color	Description
1	X14	A	Green	LINK: There is a connection to the network
		B	Yellow	ACT: Data transmission
2	X15	A	Green	LINK: There is a connection to the network
		B	Yellow	ACT: Data transmission

Cables for ports X14, X15

To connect devices to ports X14 and X15, you can order cables separately as accessories [▶ 140].

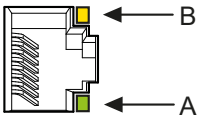
6.2.5 Port X16 - EtherCAT®

Ports and interfaces

The following devices connect to port X16:

- JM-1000, JM-3000, JX3-BN-EC
- One EtherCAT® slave device with 100 Mbit EtherCAT® port

Pinning



Socket	Signal	LED	Color	Description
X16	BUS OUT	A	Green	ACT: Data transmission
		B	Yellow	LINK: There is a connection to the network

Cable for connector X16

To connect devices to port X16, you can order cables separately as accessories [▶ 140].

6.2.6 Port X19 - CAN Bus

Ports and interfaces

Port X19 lets you connect the following devices:

– CANopen modules on CAN bus 1 or 2 (CANopen STX API)

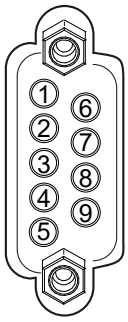
Info

Further information

For in-depth information, see the *CANopen STX API* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

Pinning



Pin	Signal	Description
1	Reserved	Do not connect
2	CAN-L	Data signal for CAN bus 1
3	GND	Reference potential
4	Reserved	Do not connect
5	Unused	
6	CAN-L_2	Data signal for CAN bus 2
7	CAN-H	Data signal for CAN bus 1
8	CAN-H_2	Data signal for CAN bus 2
9	Unused	

CAN bus cable

To connect devices to the CAN bus, you can order cables separately as accessories [▶ 139].

Y-cable (splitter cable)

Info

Y-cable (splitter cable)

To use both CAN buses, connect a Y-cable (splitter cable) to port X19. Y-cables are available separately as an Accessory [▶ 139].

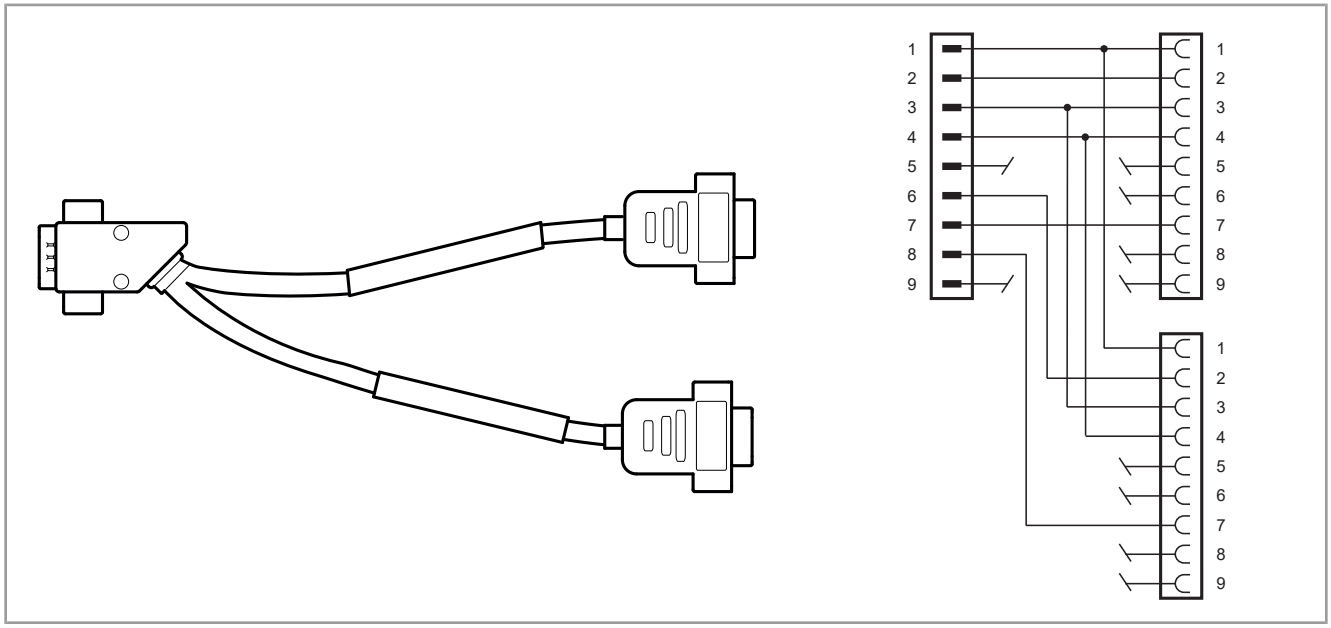


Fig. 11: Y-cable (splitter cable) for the CAN bus interface

Position	Component	Description
A	Male sub-D connector, 9-pin	For connection to BUS OUT
B	Female Sub-D connector, 9-pin	For connection to BUS IN (CAN 1)
C	Female Sub-D connector, 9-pin	For connection to BUS IN (CAN 2)

Male Sub-D Connector (A)

The 9-pin Sub-D connector of the Y-cable has the following pin assignment:

Pin	Signal	Description
1	Reserved	Do not connect
2	CAN-L	Data signal CAN 1
3	GND (Ground)	Reference potential
4	Reserved	Do not connect
6	CAN-L_2	Data signal CAN 2
7	CAN H	Data signal CAN 1
8	CAN-H_2	Data signal CAN 2

Female Sub-D Connector (B)

The female 9-pin Sub-D connector (CAN 1) of the Y-cable has the following pin assignment:

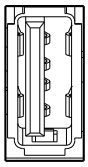
Pin	Signal	Description
1	Reserved	Do not connect
2	CAN-L	Data signal CAN 1
3	GND (Ground)	Reference potential
4	Reserved	Do not connect
7	CAN H	Data signal CAN 1

Female Sub-D Connector (C)

The female 9-pin Sub-D connector (CAN 2) of the Y-cable has the following pin assignment:

Pin	Signal	Description
1	Reserved	Do not connect
2	CAN-L_2	Data signal CAN 2
3	GND (Ground)	Reference potential
4	Reserved	Do not connect
7	CAN-H_2	Data signal CAN 2

6.2.7 Port X61 - USB



The following devices connect to port X61:

– Standard USB flash drives

The controller actively uses data stored on the USB flash drive serving as a file system extension.

– The “USB” status LED flashes to indicate that the flash drive was plugged in correctly.

– The “USB“ status LED goes off when the flash drive is removed.

ⓘ Info

Electromagnetic interferences

Plug the USB flash drive directly into port X61. For EMC reasons, USB extension cables are not allowed.

ⓘ Info

Loss of data

Make sure the USB flash drive is not accessed, while you are removing it. First, close all files which are stored to the USB flash drive.

USB flash drives

You can order USB flash drives separately as accessories [▶ 141] from Bucher Automation AG.

6.3 Commissioning

Configuration

Commissioning the device is based on the following configuration:

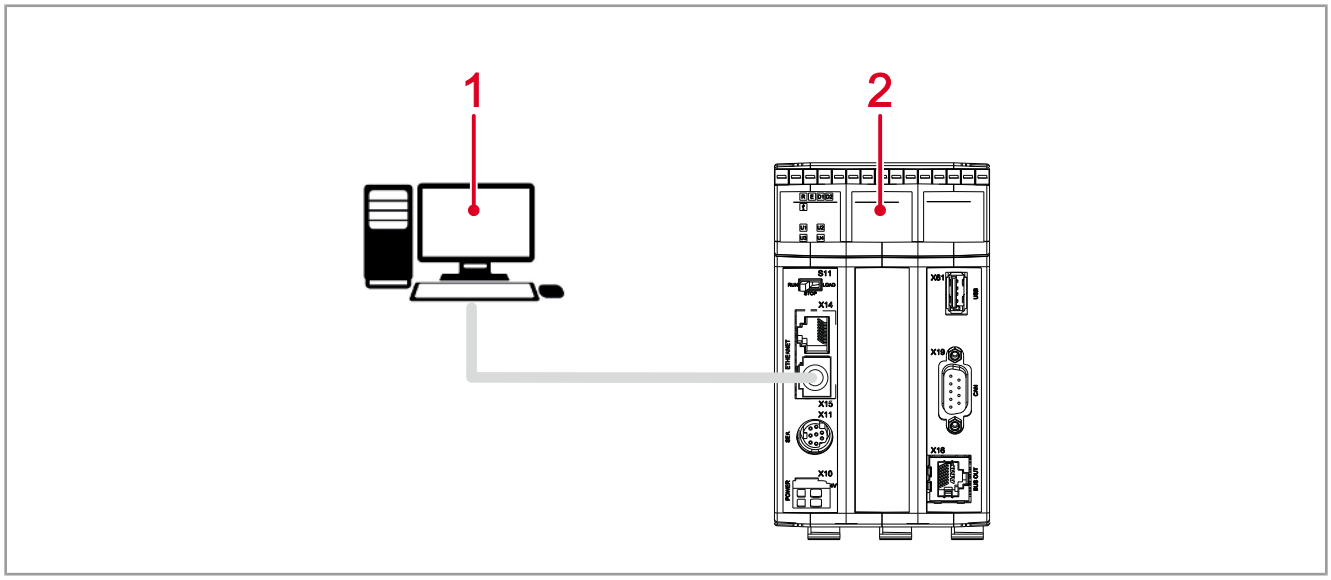


Fig. 12: Configuration

1	PC with programming system
2	Controller

Ethernet connection with the controller

The IP address factory setting of the JC-440EXT controller is 192.168.1.1. Configure the Ethernet interface of your PC to communicate with the controller via this IP address. In this example, a valid IP address of the PC is 192.168.1.20. It is import for both devices to share the same subnet.

ⓘ Info

Behavior after power-up

The position of switch S11 (mode selector) on the controller must be chosen depending on the application. If the mode selector is in STOP position when the controller is powered up, the application program will not launch.

Commissioning

To commission of the JC-440EXT controller proceed as follows:

✓ You are using an Ethernet patch cable 1:1 or crossover, of the following category:
Cat 5e at 10 ... 100 MBit/s or Cat 6 at 1,000 MBit/s

1. Select the position of S11 mode selector according to your application.
2. Connect controller and PC by means of the Ethernet patch cable.
3. Power-up the controller.
   ⇨ The controller steps through the boot process.
   ⇨ The LED flashes green if the mode selector is in the RUN position and the controller runs a valid application program.
4. Launch the JetSym application program.

⇨ Now, you can configure the controller.

7 Identification and Configuration

7.1 Identification

This chapter describes how to identify the JC-440EXT device:

– Determining the hardware revision
– Retrieving Electronic Data Sheet (EDS) information. The EDS holds numerous non-volatile production-relevant data.
– Determining the OS version of the device and its software components

7.1.1 Electronic Data Sheet (EDS)

Each JC-440EXT features an Electronic Data Sheet (EDS). Numerous production-relevant data are permanently stored in the EDS. The EDS data can be read out via files in the file system of the controller or via special registers.

EDS file "eds.ini"

EDS data can be retrieved via the **eds.ini** file.

Properties

– You can access this file through the file system of the controller.
– For an FTP connection, the user needs administrator rights (*admin* user) or system rights (*system* user).
– The EDS file of the controller is located in the **System** folder.
– This file is read-only.
– Formatting the flash drive has no effect on the file.

File structure

The EDS file is a text file with its entries grouped into several sections.

Example

This is an example of an EDS file for a JC-440EXT:

```
;JC-440EXT-AXS_012-TEC-PAT-EC.. Electronic Data Sheet (Definition:
JC-440_01)

[IDENTIFICATION]
Version = 2
Code = 1102
Name = JC-440EXT-AXS_012-TEC-PAT-EC..
PcbRev = 00
PcbOpt = 05
OSVersionMin = 0.0.0.0
BLVersionMin = 0.0.0.0
```

```
[PRODUCTION]
Version = 0
SerNum = 20190325070900
Day = 26
Month = 3
Year = 2019
TestNum = 4
TestRev = 1.3.1.26

[FEATURES]
Version = 7
MAC-Addr = 00:50:CB:02:FC:F5
Serial = 1
Switch = 1
STX = 1
NVRegs = 120000
JX3-Bus = 1
CAN = 1
UserLeds = 1
RTC = 1
USB = 1
USBLed = 1
```

[IDENTIFICATION] section

The general hardware configuration can be retrieved from the [IDENTIFICATION] section.

Name	Example	Function
Version	2	Version of this section
Code	1102	JC-440EXT module code
Name	JC-440EXT-AXS_012-TEC-PAT-EC..	Corresponds to the information on the nameplate
PcbRev	00	PCB revision
PcbOpt	05	PCB option
OSVersionMin	0.0.0.0	The product is available as of this OS version
BLVersionMin	0.0.0.0	The product is available as of this bootloader version.

Tab. 21: [IDENTIFICATION] section

[PRODUCTION] section

The serial number and production date can be retrieved from the [PRODUCTION] section.

Name	Example	Function
Version	0	Version of this section
SerNum	20190325070900	Corresponds to the information on the nameplate
Day	26	Production date: Day
Month	3	Production date: Month
Year	2019	Production date: Year

Name	Example	Function
TestNum	4	Internal usage
TestRev	1.3.1.26	Internal usage

Tab. 22: [PRODUCTION] section

[FEATURES] section

In the [FEATURES] section, special properties of the controller are specified. The OS of the controller will ignore properties which have not been entered in the file.

Name	Example	Function
Version	7	Version of this section
MAC-Addr	00:50:CB:02:FC:F5	MAC address of the EtherCAT® interface
Serial	1	The serial interface is available
Switch	1	RUN/STOP/LOAD mode selector is available
STX	1	Runtime environment for the application program is available
NVRegs	120000	Total of non-volatile registers
JX3 bus	1	Bus interface for JX3 modules is available
CAN	1	CAN bus interface is available
UserLEDs	1	LEDs U1 through U4 are supported
RTC	1	A real-time clock is available
USB	1	Slot for the USB flash drive is available
USBLed	1	LED for the USB flash drive is available

Tab. 23: [FEATURES] section

EDS registers

EDS registers let you retrieve entries made in the Electronic Data Sheet (EDS). These registers mirror 1:1 the contents of the EDS file. They are to be read only (ro).

Register numbers

The basic register number is dependent on the controller. The register number is calculated by adding the number of the module register (MR) to the number of the basic register.

Device	Basic register number	Register numbers
JC-440EXT	100000	100500 ... 100827

Tab. 24: Register numbers of the EDS

Registers - Overview

The following table lists the EDS registers of a controller, as well as their connection to the entries in the EDS file **/System/eds.ini**. You can use this register array to display the EDS of the controller or of a JX3 module. To do this, you must select the controller or the desired JX3 module via module registers 500 and 501. Data of the selected EDS can be retrieved from MR 600 and the following.

Registers	Section in eds.ini	Name in eds.ini	Description
MR 500	-	-	Functional group 0: CPU 1: JX3 modules
MR 501	-	-	Module number (if MR 500 > 0)
MR 600	IDENTIFICATION	Version	Version of this section
MR 601		Code	Module code
MR 602 … MR 612		Name	Module name or controller name
MR 613		PcbRev	PCB revision
MR 614		PcbOpt	PCB option
MR 700	PRODUCTION	Version	Version of this section
MR 701 … MR 707		SerNum	Serial number
MR 708		Day	Production date: Day
MR 709		Month	Production date: Month
MR 710		Year	Production date: Year
MR 711		TestNum	Internal usage
MR 712		TestRev	Internal usage

Registers	Section in eds.ini	Name in eds.ini	Description
MR 800	FEATURES	Version	Version of this section
MR 801		MAC-Addr	MAC address - EtherCAT® (Bucher Automation)
MR 802		MAC-Addr	MAC address - EtherCAT® (device)
MR 803		Serial	Serial port
MR 804		Switch	Mode selector RUN/STOP/LOAD
MR 805		STX	Runtime environment for the application program
MR 806		NVRegs	Number of non-volatile registers
MR 807		JX3 bus	Bus connection for JX3 modules
MR 808		CAN	CAN-bus
MR 810		MotionControl	MC software
MR 811		Axes	Number of supported axis modules
MR 812		Web	Web server and e-mail client
MR 813		Modbus/TCP	Modbus/TCP client and server
MR 816		UserLEDs	User-defined LEDs
MR 817		RTC	Real-time clock
MR 825		USB	Plug-in connector for the USB flash drive
MR 826		USBLed	LED of the USB flash drive

Tab. 25: Overview of EDS registers

7.1.2 Version registers

The operating system provides several registers which can be used to read out the hardware revision or OS version of the device and its components.
You will need this information when contacting the Bucher Automation AG support hotline in case of a problem.

Hardware revisions

The device has special registers, the content of which lets you identify the hardware.

Registers - Overview

The registers listed below let you retrieve the hardware revisions:

Registers	Description
108020	Hardware revision of the backplane module
108021	Hardware revision - CPU board
200170	Controller model

Tab. 26: Register overview - Hardware revisions

Operating system version

The device features special registers containing unique OS version numbers.

Software version numbers

The software version number of the device is a 4-digit value.

1 . **2** . **3** . **4**

Digits	Description
1	Major or main version number
2	Minor or secondary version number
3	Branch or intermediate version number
4	Build version number

Tab. 27: Software version number format

Released version

A released version is identified by both the branch and build values being 0.

Register overview

The operating system versions can be read from the registers listed below:

Registers	Description
200169	Operating system version
210001	Version of the execution unit for the STX application program
100002000	Hardware revision of the JX3 system bus
100002072	Software version of the JX3 system bus driver

Tab. 28: Registers - Overview

7.2 IP configuration

This chapter describes the IP configuration for the controller. The following parameters can be set:

– IP address of the controller
– Subnet mask
– IP address of the default gateway
– IP address of the DNS server
– Controller name
– IP port number for the JetSym debugger
– Basic port number for communication via JetIP
– Name of the AutoCopy command file

7.2.1 Factory settings

Prior to shipment of the JC-440EXT controller, various parameters are set to a default value. These parameters can be changed by the user.

Factory settings

Parameter	Value
IP address of the controller	192.168.1.1
Subnet mask	255.255.255.0
IP address of the default gateway	0.0.0.0
IP address of DNS server	0.0.0.0
Controller name	JC-440EXT
IP port number for debugger	52000
IP port number for JetIP	50000
Name for AutoCopy command file	/USB/autocopy.ini
DIP switch sliders	DIP switch slider 1 = ON All other DIP switch sliders = OFF
User's password *admin*	admin
User's password *system*	system

Tab. 29: Factory settings

7.2.2 Determining the IP address of the controller using JetIPScan

Introduction

The JetIPScan tool lets you determine the IP address, subnet mask and the IP address of the default gateway of the JC-440EXT.

Info

Downloading JetIPScan

You can download the JetIPScan software at www.bucherautomation.com.

Contents of the ZIP file

The zip file **jetipscan_1-11-00.zip** contains the following files:

– The program JetIPScan_V_1-11-00.exe
– The help jetipscan_01_help_en.png
– The batch file read_IP_via_JETIPSCAN.bat to determine the IP address
– The batch file write_IP_via_JETIPSCAN_10_150.bat to set IP address 192.168.10.150 for the controller

The batch files launch the program JetIPScan.

The files are unzipped to the folder **jetipscan_1-11-00**.

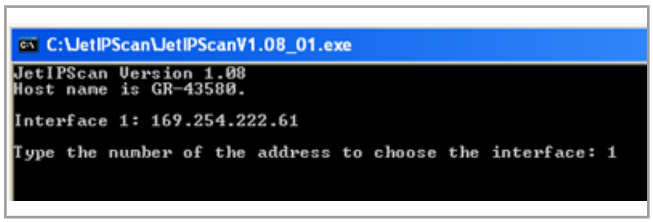
Determining the IP address

To determine the IP address of the JC-440EXT, proceed as follows:

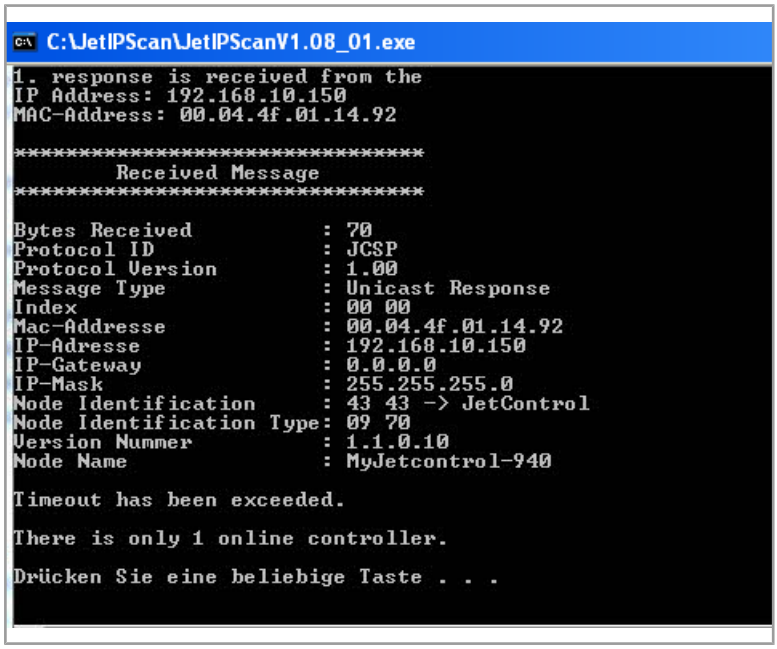
✓ An Ethernet connection exists between the PC and the JC-440EXT.

1. Launch the JetIPScan program on your PC, for example via batch file **read_IP_via_JETIPSCAN.bat**.
2. Write a batch file. The content of the batch file is **JetIPScan_V_1-11-00.exe -R**.
3. Execute the batch file.

   ⇨ JetIPScan is launched and shows all IP addresses, which are presently active on your PC.
4. Select the interface (IP address) of the device whose IP address you want to determine.



⇨ Among others, JetIPScan shows the IP address of the JC-440EXT.



7.2.3 Configuration memory

During the boot phase, the JC-440EXT reads the parameters for initializing the IP interface from the **config.ini** configuration file which is physically part of the configuration memory. The configuration memory is located in a remanent memory (EEPROM) on the backplane module.

According to the contents of the configuration file, the controller writes values into configuration registers and then initializes the IP interface.

The user can access the data stored in the configuration memory in the following ways:

– Read and change data via the **config.ini** file in the system directory using FTP

– The user can read out or change data via configuration registers. When saving, a new configuration file is created from the data.

ⓘ Info

When does this take effect?

The controller reads out data located in the configuration memory only during the boot process. If you make changes to the configuration memory, reboot the controller. Only this way, these changes will take effect.

Default values

Prior to processing data from the configuration memory, JC-440EXT checks them for plausibility. If the entries are not valid or do not exist, the controller uses the following default values:

Parameter	Default value
IP address of the controller	192.168.10.15
Subnet mask	255.255.255.0
IP address of the default gateway	0.0.0.0
IP address of DNS server	0.0.0.0
Controller name	JC-440EXT
Suffix type of the name	0
IP port number for debugger	52000
IP port number for JetIP	50000
Name for AutoCopy command file	/USB/autocopy.ini

Tab. 30: Configuration memory - Default values

Storage location/controller replacement

The configuration memory is located on the backplane module. Owing to this approach, configuration data will be preserved when the function module is replaced.

7.2.4 Configuration file "config.ini"

The configuration file **config.ini** lets you access the configuration memory of the JC-440EXT. This file has been stored to the EEPROM in the backplane module.

Properties

You can access this file through the file system of the JC-440EXT.

– When using an FTP connection, the user must have administrator or system rights.
– This file is located in the folder **System**.
– You cannot delete the file, but only overwrite it.
– Formatting the Flash disk drive leaves the file unchanged.

File structure

The configuration file is a text file the entries of which are grouped into several sections. The JC-440EXT replaces missing IP configuration parameters with their default values.

Example

This is an example of a configuration file **config.ini**:

```
;JC-440EXT System Configuration
;Copyright (c) 2020 by Bucher Automation AG

[IP]
Address = 192.168. 50. 1
SubnetMask = 255.255.255. 0
DefGateway = 192.168. 50. 11
DNSServer = 192.168. 1. 44

[HOSTNAME]
SuffixType = 0
Name = JC-440EXT

[PORTS]
JetIPBase = 50000
JVMDebug = 52000

[FILES]
AutoCopyIni = /USB/autocopy.ini
```

Section [IP]

In the [IP] section the required IP addresses and the subnet mask are specified.

Address

Property	Description	
In the given example	192.168.50.1	
Function	IP address The settings of the DIP switch on the backplane module can overwrite the least significant byte.	
Allowed values	> 1.0.0.0	< 223.255.255.255
Illegal values	Network address, broadcast address	
In the event of an illegal value	All 4 values will be reset to default.	

Tab. 31: Address

SubnetMask

Property	Description
In the given example	255.255.255.0
Feature	Specifies the subnet mask
Allowed values	≥ 128.0.0.0
Illegal values	1 and 0 mixed
In the event of an illegal value	All 4 values will be reset to default.

Tab. 32: SubnetMask

DefGateWay

Property	Description	
In the given example	192.168.50.1	
Feature	IP address of the gateway to other subnets; equals 0.0.0.0, if no other nodes are available via the address/subnet mask.	
Allowed values	≥ 0.0.0.0	< 223.255.255.255
Illegal values	– Network address – Broadcast address – If no other nodes are available via the address/subnet mask – The Address value	
In the event of an illegal value	Will be set to 0.0.0.0	

Tab. 33: DefGateWay

DNSServer

Property	Description	
In the given example	192.168.1.44	
Feature	IP address of the server for the Domain Name System	
Allowed values	≥ 0.0.0.0	< 223.255.255.255
In the event of an illegal value	Will be set to 0.0.0.0	

Tab. 34: DNSServer

Section [HOSTNAME]

The [HOSTNAME] section contains the name of the JC-440EXT. If desired, the controller automatically generates an individual name. Hostname is not currently used.

SuffixType

Property	Description	
In the given example	0	
Function	The type of the automatically generated suffix that is attached to the controller name	
Allowed values	0	No suffix
	1	Low-order byte of the IP address in decimal notation
	2	Low-order byte of the IP address in hexadecimal notation
In the event of an illegal value	0	

Tab. 35: SuffixType

Name

Property	Description	
In the given example	JC-440EXT	
Function	Specifies the controller name	
Allowed values	First character	'A' ... 'Z', 'a' ... 'z'
	Next characters	'A' ... 'Z', 'a' ... 'z', '0' ... '9', '-'
In the event of an illegal value	JC-440EXT	

Tab. 36: Name

Section [PORTS]

In section [PORTS] the IP port numbers of data and debug servers are specified. The IP port numbers must be consistent with, for example, the port numbers set in JetSym.

JetIPBase

Property	Description
In the given example	50000
Function	IP port for OS update and communication between devices
Allowed values	1024 ... 65535
In the event of an illegal value	50000

Tab. 37: JetIPBase

JVMDebug

Property	Description
In the given example	52000
Function	IP port for debugger/setup in JetSym
Allowed values	1024 ... 65535
In the event of an illegal value	52000

Tab. 38: JVMDebug

Section [FILES]

In section [FILES] the name of the command file for the AutoCopy function is specified.

AutoCopyIni

Property	Description
In the given example	/USB/autocopy.ini
Function	Command file for the AutoCopy function
Allowed values	Allowed path and file name
In the event of an illegal value	/USB/autocopy.ini

Tab. 39: AutoCopyIni

Changing the IP configuration via the configuration file

You can change the IP configuration directly in the **config.ini** configuration file.
To do this, carry out the following steps:

1. Create on your PC a configuration file named **config.ini** using a text editor and make the corresponding entries.
2. Open an FTP connection between the PC and the JC-440EXT.
3. Choose a user login with administrator or system rights.
   Default login information:
   User: admin, Password: admin
   User: system; Password: system
4. Open the *System* folder of the JC-440EXT.
5. Copy the **config.ini** configuration file you created into the *system* folder.
6. Clear the FTP connection.
7. Reboot.

⇨ The new configuration is active.

Configuration registers let you also make changes to the IP configuration.

7.2.5 Configuration registers

Configuration registers grant you read or write access to the parameters of the IP configuration. The configuration registers have 2 register areas that may differ in content.

Register numbers

The basic register numbers of both ranges are dependent on the device. The register number is calculated by adding the number of the module register (MR) to the number of the basic register.

Device	Data range	Basic register number	Register numbers
JC-440EXT	Configuration memory	101100	101100 ... 101165
	Parameters used	101200	101200 ... 101265

Tab. 40: Register numbers of the configuration registers

Register areas

– Registers R 101100 ... R 101165 contain the data which the controller has determined from the contents of the configuration file during the boot phase. The user has read-only access to this data.
– Registers R 101200 ... R 101265 contain the data which are actually used to initialize the IP interface. The user has read and write access to this data.

The data of the two register areas may differ for the following reasons:

– Parameters of the IP interface can be changed at runtime. This affects the value of the registers R 101200 ... R 101202.
– The position of the DIP switch affects the actual IP address and thus the value of R 101200.

Registers - Overview

Registers	Section in config.ini	Name in config.ini	Description
MR 0	IP	Address	IP address of the controller
MR 1		SubnetMask	Specifies the subnet mask
MR 2		DefGateWay	IP address of the gateway to other subnets
MR 3		DNSServer	IP address of the server for the Domain Name System
MR 32	HOSTNAME	SuffixType	The type of the automatically generated suffix that is attached to the controller name
MR 33 … MR 51		Name	Specifies the controller name
MR 64	PORTS	JetIPBase	IP port number for OS updates and communication between controllers
MR 65		JVMDebug	IP port number for debugger/setup in JetSym
MR 80	FILES	AutoCopyIni	Name for AutoCopy command file

Tab. 41: Overview of configuration registers

7.2.6 Setting the IP address

To communicate via Ethernet, you must set a unique IP address on the controller.

Replacing the controller

The IP address is stored in the configuration memory on the backplane module. If you plug another controller of the same controller series onto the backplane module, the following configuration data are retained:

– IP address of the controller
– Subnet mask
– IP address of the default gateway
– IP address of DNS server
– Controller name
– Suffix type of the name
– IP port number for debugger
– IP port number for JetIP
– Name for AutoCopy command file

Configuration options

You can configure the IP address in the following ways:

– Setting the default IP address
– Configuration via file **config.ini**
– Configuration via **config.ini** file and DIP switch
– Configuration via the configuration registers (remanent)
– Configuration during runtime via special registers (not remanent)
– Configuration via JetIPScan program (remanent)

Changing the IP address

1. Switch off the power supply to the device.
2. Remove the controller enclosure from the backplane module.
3. Make the corresponding DIP switch settings.
4. Reattach the controller enclosure to the backplane module.

⇨ After the restart, the device can be reached at the new IP address.

Setting the default IP address

The default IP address is 192.168.10.15 You can reset the IP address to its default value at any time.

DIP switch slider settings

To set the default IP address 192.168.10.15, position the DIP switch sliders (1 … 12 = OFF) as shown below:

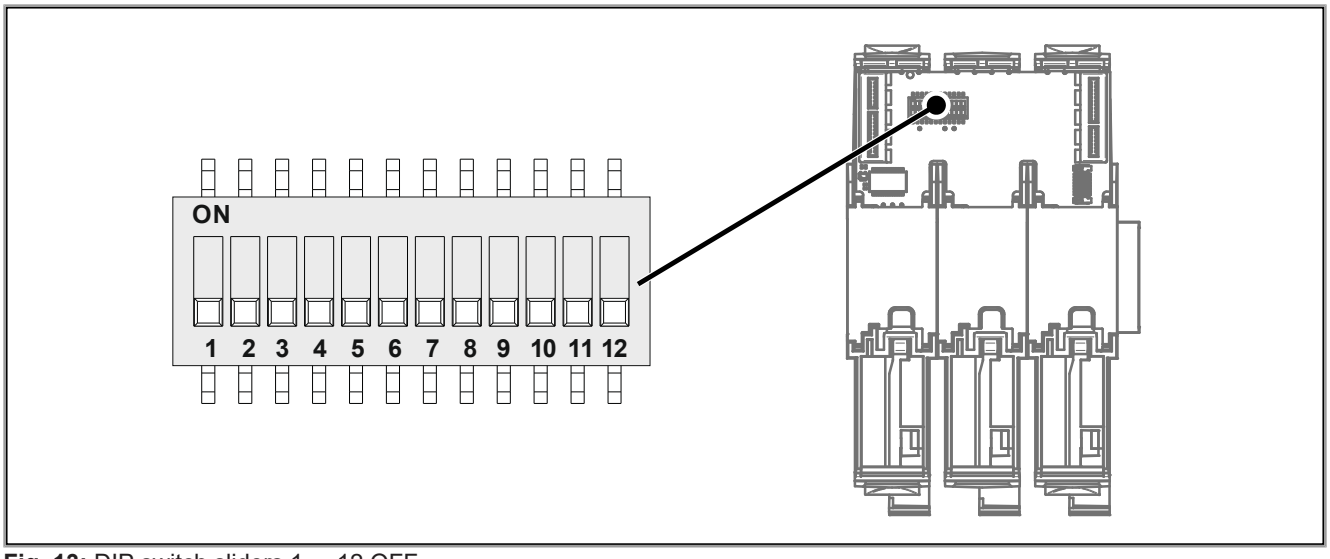


Fig. 13: DIP switch sliders 1 ... 12 OFF

Changing the IP address of the controller

Introduction

The JetIPScan tool lets you change the IP address, subnet mask and the IP address of the default gateway of the JC-440EXT.

Info

Downloading JetIPScan

You can download the JetIPScan software at www.bucherautomation.com.

Contents of the ZIP file

The zip file **jetipscan_1-11-00.zip** contains the following files:

- The program JetIPScan_V_1-11-00.exe
- The help jetipscan_01_help_en.png
- The batch file read_IP_via_JETIPSCAN.bat to determine the IP address
- The batch file write_IP_via_JETIPSCAN_10_150.bat to set IP address 192.168.10.150 for the controller

The batch files launch the program JetIPScan.

The files are unzipped to the folder **jetipscan_1-11-00**.

Possible commands of the software JetIPScan

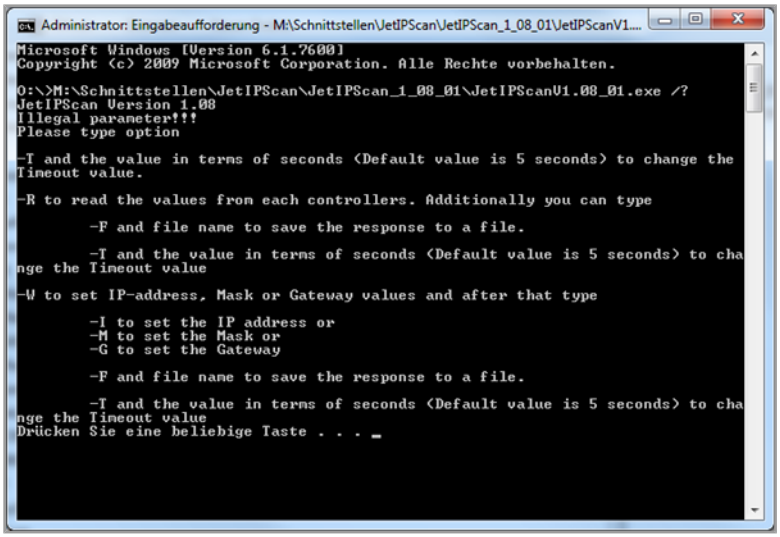


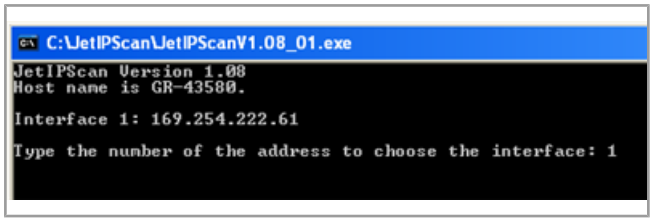
Fig. 14: JetIPScan - command options

Changing the IP address

✓ An Ethernet connection exists between the PC and the JC-440EXT.

1. Then start the JetIPScan tool on your PC, e. g. by means of the batch file **write_IP_via_JETIPSCAN_10_150.bat**.
2. Write a batch file. The content of the batch file is **JetIPScan_V_1-11-00.exe -W -I 192.168.10.150**.
3. Execute the batch file.

   ⇨ JetIPScan is launched and shows all IP addresses, which are presently active on your PC.
4. Select the interface (IP address) of the device whose IP address you want to change.



   ⇨ JetIPScan shows all the devices found.
5. To make changes to the IP address of a device, select the respective device from the list.

   ⇨ JetIPScan changes the IP address of the JC-440EXT to 192.168.10.150.

Changing the subnet mask

1. Write a batch file. The content of the batch file is, for example, **JetIPScan_V_1-11-00.exe -W -M 250.255.248.0**.
2. Execute the batch file.
3. JetIPScan is launched and shows all interfaces, which are presently active on your PC.
4. For all further steps, please refer to the instruction **Changing the IP address**.

Changing the Default Gateway

1. Write a batch file. The content of the batch file is, for example, **JetIPScan_V_1-11-00.exe -W -G 192.168.4.1**.
2. Execute the batch file.

   ⇨ JetIPScan is launched and shows all interfaces, which are presently active on your PC.
3. For all further steps, please refer to the instruction **Changing the IP address**.

Setting the IP address via configuration file

Setting the IP address

The IP address can be set via the **config.ini** configuration file.

```
[IP]
Address = aaa.bbb.ccc.ddd
...
```

Element	Description
`Address`	Enter the IP address into this line.
`aaa`	1. byte of IP address
`bbb`	2. byte of IP address
`ccc`	3. byte of IP address
`ddd`	4. byte of IP address

Tab. 42: Elements of the IP address

DIP switch slider settings

To enable the JC-440EXT controller to read the IP address from the **config.ini** file, position the DIP switch sliders (1 … 8 = ON) as shown below:

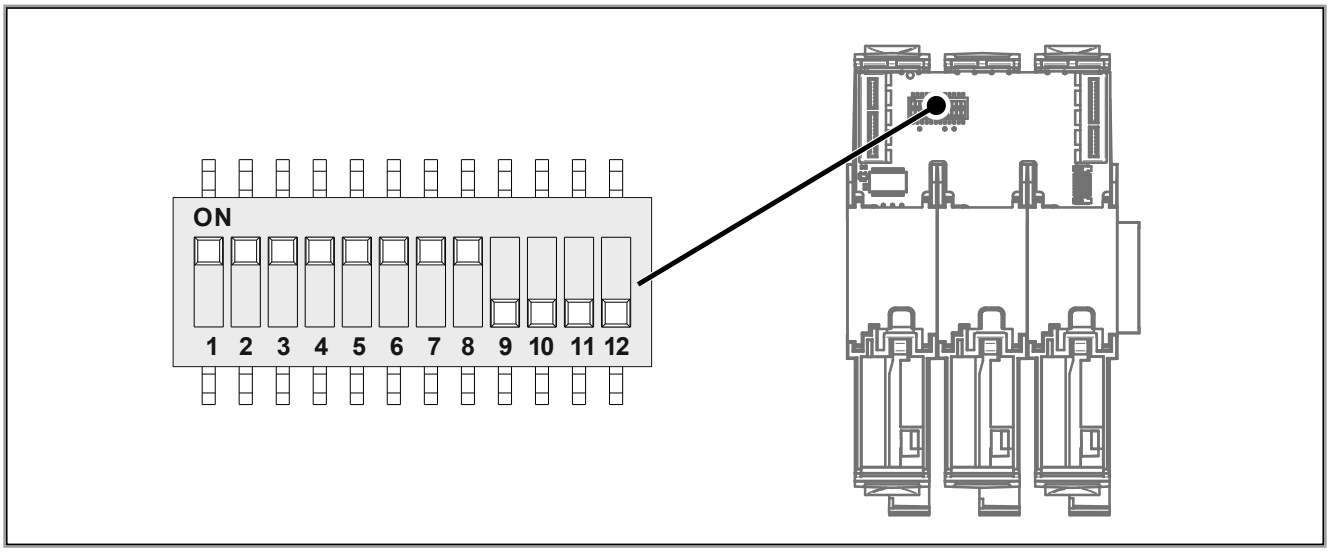


Fig. 15: DIP switch sliders 1 ... 8 ON

Transferring the configuration file

1. Establish an FTP connection between PC and JC-440EXT.
2. Choose a user login with administrator or system rights.
   Default login information:
   User: *admin*; Password: *admin*
   User: *system*; Password: *system*
3. Open the **System** folder of the JC-440EXT.
4. Copy the **config.ini** file to the **System** folder.

5. Clear the FTP connection.
6. Reboot.

Setting the IP address via configuration file and DIP switch

You can set the IP address by combining the settings in the **config.ini** configuration file and the DIP switch sliders on the backplane module. This method uses contents of the **config.ini** file to populate the upper 3 bytes of the IP address, and the setting of the DIP switch slider 1 … 8 for the lower byte.

Setting the IP address

Set the upper 3 bytes of the IP address via the **config.ini** file.

```
[IP]
Address = aaa.bbb.ccc.1
...
```

Element	Description
`Address`	Line where to enter the upper 3 bytes of the IP address
`aaa`	First byte of IP address
`bbb`	Second byte of IP address
`ccc`	Third byte of IP address
`ddd`	Dummy entry; must be **1**

Tab. 43: IP address elements

DIP switch slider settings

To enable the JC-440EXT controller to read the IP address from the **config.ini** file and the respective switch elements, position the DIP switch sliders as shown below:

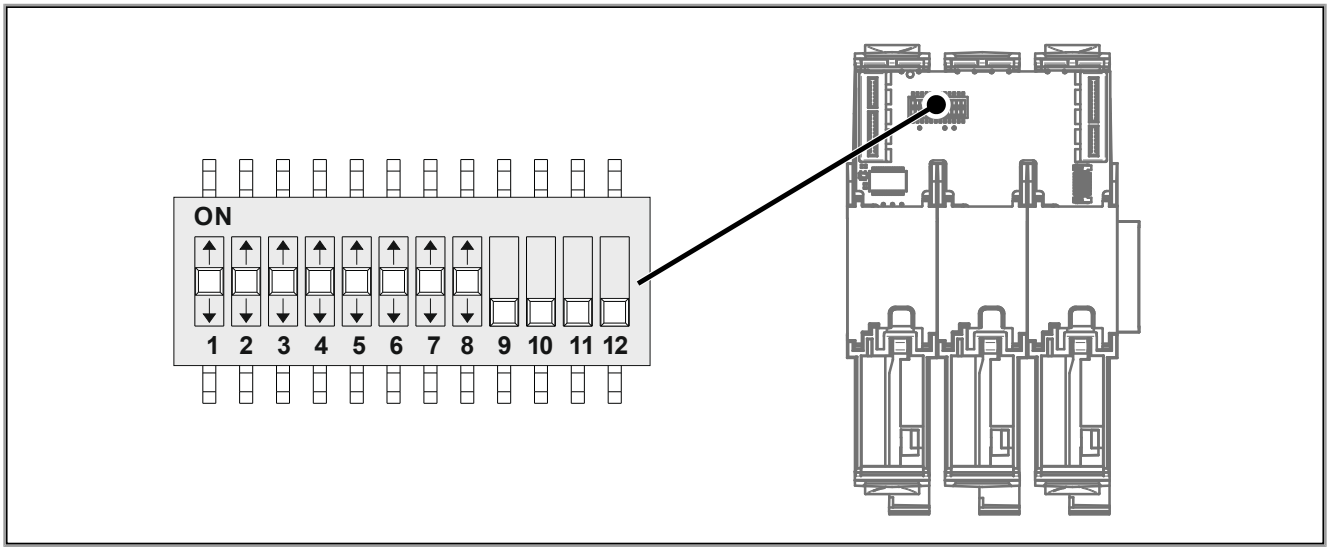


Fig. 16: DIP switch sliders 1 ... 8 arbitrarily

DIP switch									IP address
1	**2**	**3**	**4**	**5**	**6**	**7**	**8**	**9 … 12**	
OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	Default IP address
ON	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	aaa.bbb.ccc.1
OFF	**ON**	OFF	OFF	OFF	OFF	OFF	OFF	OFF	aaa.bbb.ccc.2
ON	**ON**	OFF	OFF	OFF	OFF	OFF	OFF	OFF	aaa.bbb.ccc.3
...	…	…	…	…	…	…	…	…	…
OFF	**ON**	**ON**	**ON**	**ON**	**ON**	**ON**	**ON**	OFF	aaa.bbb.ccc.254
ON	**ON**	**ON**	**ON**	**ON**	**ON**	**ON**	**ON**	OFF	from config.ini

Transferring the configuration file

1. Establish an FTP connection between PC and JC-440EXT.
2. Choose a user login with administrator or system rights.
   Default login information:
   User: *admin*; Password: *admin*
   User: *system*; Password: *system*
3. Open the **System** folder of the JC-440EXT.
4. Copy the **config.ini** file to the **System** folder.
5. Clear the FTP connection.
6. Reboot.

Setting the IP address via non-volatile registers

The IP interface is initialized by the settings in the configuration memory during the boot phase. You can change the following settings via registers. The values are then stored to the remanent memory:

– IP address of the controller
– Subnet mask
– IP address of the default gateway
– IP address of DNS server
– Host name and suffix type
– Port numbers for JetIP and JetSym debugger
– Name for AutoCopy command file

Registers - Overview

Register (range)	Description
101200	IP address
101201	Subnet mask
101202	IP address of the default gateway
101203	IP address of DNS server
101232	Host name suffix type
101233 … 101251	Host name
101264	Port number for JetIP
101265	Port number for STX debugger
101280 … 101298	Name for AutoCopy command file
101299	Saving the settings (0x77566152)

Tab. 44: Overview over the configuration memory registers

NOTICE



Limitation of the write cycles

The EEPROM data on the backplane module allow for 100,000 write cycles.

► Read a value first.
► Compare the value.
► Write only if you actually want to change the value.

Setting the configuration values to be non-volatile

To change the configuration values to become non-volatile, proceed as follows:

1. Enter the desired configuration data into one or several registers in the range 101200 … 101298.
2. To have the controller apply the values, you must enter a password.
   For this, enter value 2002149714 (0x77566152) into register 101299.
3. Wait for the controller to write value 0 into MR 101299.

   ⇨ The save process is now completed.
4. Boot the controller.

⇨ The settings are completed. Communication is possible again.

ⓘ Info

Influence of the DIP switches on the IP address

The position of the DIP switch sliders has an influence on the actual IP address (see Configuration registers [▶ 53]).

Effect

By writing to register 101299, the controller executes the following:

– The controller creates a configuration file out of the values.
– It saves the configuration file to the backplane module as **/System/config.ini**.
– If you have entered comments and formatting details into this file, the comments and formatting details will be lost during this process.

Setting the IP address during runtime

The IP interface is initialized by the settings in the configuration memory during the boot phase. Registers let you make changes to the settings listed below. These changes will then be saved to a volatile memory:

– IP address of the controller
– Subnet mask
– IP address of the default gateway

ⓘ Info

Important note

The settings made during runtime do not overwrite the parameters in the configuration memory. When de-energizing the controller, your settings will be lost.

To set the IP address and the subnet mask, proceed as follows:

✓ While settings are being made, no communication via IP interface is allowed. Otherwise, this would lead to a loss of data.
✓ The values entered must be valid. This can be ensured, e.g. by including a validity check in the application program.
If you set the parameters at runtime, no check takes place.

1. Enter the value 0.0.0.0 into R 104533.
2. Enter the value 0.0.0.0 into R 104532.

3. Enter the desired IP address into R 104531.
4. Enter the desired subnet mask into R 104532.
5. Enter the desired IP address of the default gateway into R 104533.

⇨ The settings are completed. Communication is possible again.

IP address in the GNN operating mode

In GNN (Global Network Number) mode , the JC-440EXT controller functions as a network node within a greater control network. The controller acquires its IP address during boot-up from the **config.ini** configuration file. Next, the main controller, which is the NetConsistency master, commands the network node to log in with its GNN. After accepting the network node, the main controller compares the set IP configuration with the actual IP configuration of the network node. If a difference results, the main controller makes the corresponding changes in the set IP configuration in the network node.

Setting the IP address

The IP address can be set via the **config.ini** configuration file.

```
[IP]
Address = aaa.bbb.ccc.ddd
...
```

Element	Description
`Address`	Enter the IP address into this line.
`aaa`	1. byte of IP address
`bbb`	2. byte of IP address
`ccc`	3. byte of IP address
`ddd`	4. byte of IP address

Tab. 45: Elements of the IP address

DIP switch slider settings

To enable GNN mode, move DIP switch slider 9 to **ON**.
This enables the JC-440EXT controller to read the IP address from the **config.ini** file, and the GNN from the lower 8 positions of the DIP switches sliders. The DIP switch sliders are binary-coded.

– Valid values for the GNN: 1 ... 199.

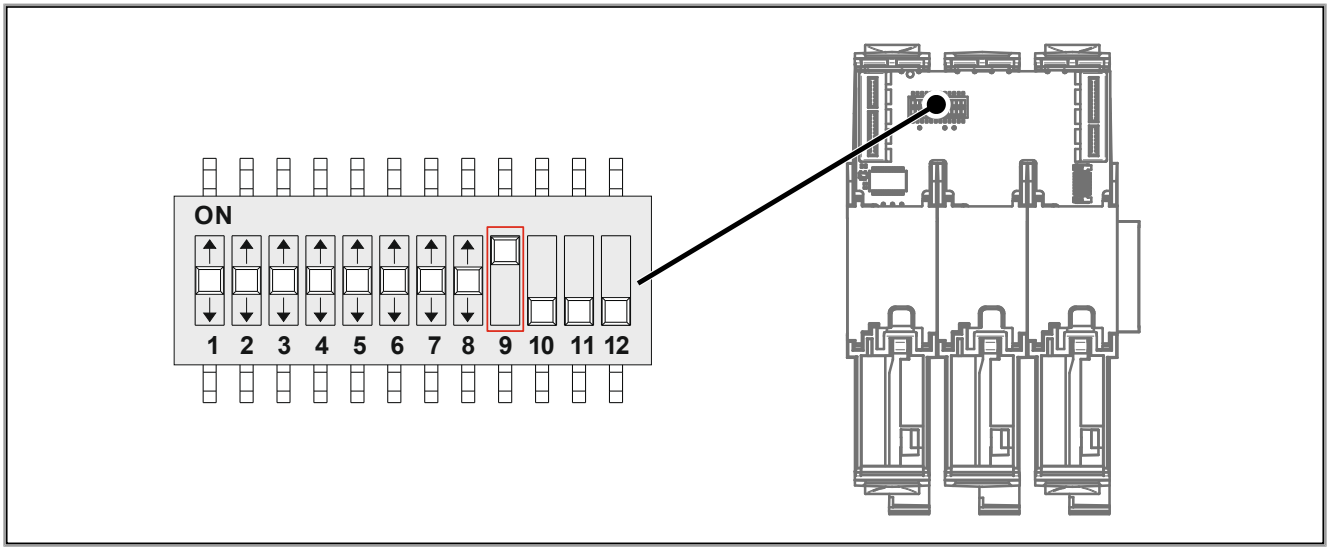


Fig. 17: DIP switch GNN

DIP switch										GNN
1	**2**	**3**	**4**	**5**	**6**	**7**	**8**	**9**	**10 … 12**	
OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	**ON**	OFF	Invalid
ON	OFF	OFF	OFF	OFF	OFF	OFF	OFF	**ON**	OFF	1
OFF	**ON**	OFF	OFF	OFF	OFF	OFF	OFF	**ON**	OFF	2
ON	**ON**	OFF	OFF	OFF	OFF	OFF	OFF	**ON**	OFF	3
...	…	…	…	…	…	…	…	…	…	
ON	**ON**	**ON**	OFF	OFF	OFF	**ON**	**ON**	**ON**	OFF	199
...	…	…	…	…	…	…	…	…	…	
ON	**ON**	**ON**	**ON**	**ON**	**ON**	**ON**	**ON**	**ON**	OFF	Invalid

7.2.7 Using names for IP addresses

You can also use names when specifying IP addresses of external communication partners, for example, when configuring the e-mail client. The controller resolves the names into IP addresses. A configuration file or the Domain Name System is used to resolve a name into its corresponding IP address. Names can be resolved to IP addresses during the boot process, or during runtime of the controller.

Name resolution

Names are resolved to IP addresses in the following way:

Step	Description
1	In the boot phase, the IP address of the DNS server is read from the configuration memory.
2	In the boot phase, the **/etc/hosts** file is read. Then, the controller creates a translation table with the names and IP addresses found in this file.
3	After the boot process the controller detects a name instead of an IP address.

Step	Description	
4	Based on this translation table, the controller tries to resolve the name into a related IP address.	
	If …	**… then …**
	... the controller could resolve the name, ...	... proceed with step 6.
	... the controller could not resolve the name, ...	... proceed with step 5.
5	The controller tries to resolve the name into a related IP address by sending a request to the DNS server.	
	If …	**… then …**
	... the controller has resolved the name,	... it enters the name and IP address into the translation table; → proceed with step 6.
	... the controller has not resolved the name,	... the controller aborts the function, e.g. the system function for sending an e-mail, and issues an error message.
6	The controller uses the found IP address for further communication.	

Tab. 46: Name resolution

Configuration File "hosts"

The **hosts** configuration file holds the static assignment between names and IP addresses. During the boot phase, the JC-440EXT reads the file once.

– File format: Text
– Location: */etc*
– File name: **hosts**

Domain Name System (DNS)

If a name cannot be found in the **/etc/hosts** file, the JC-440EXT tries to resolve the IP address by DNS server request. During the boot process the JC-440EXT reads the IP address of the DNS server from the configuration memory.

7.3 Operating system

We are continuously striving to enhance the operating systems of our products. Enhancing means adding new features, and upgrading existing functions. Current OS files are available for download from our website on the pages of the respective product.

ⓘ Info

Further information

More information on this subject is available on our website.

Start | www.bucherautomation.com

7.3.1 Operating system update of the controller

This chapter describes how to carry out an operating system update on the JC-440EXT controller. You have got several options for transferring the OS file to the controller:

– Using the programming tool JetSym
– Via an FTP connection
– From a USB flash drive
– From within the application program

Operating system update using the programming tool

The JetSym programming tool offers an convenient way of transferring an OS file to the JC-440EXT controller.

Performing the update

✓ The mode selector of the controller is in **RUN** or **STOP** position before controller boot-up.
✓ An OS file for the JC-440EXT controller is available.
✓ A UDP/IP and a TCP/IP connection between programming tool and JC-440EXT controller is possible.
✓ The number of the IP port is set in the configuration memory as IP basic port number for JetIP communication.
✓ The OS is running.
✓ The controller keeps running throughout the update.

1. In the JetSym **Build** menu, select **Update OS...**

   ⇨ The file selection dialog opens.
2. Select the new OS file here.

   ⇨ JetSym opens a confirmation dialog.
3. Launch the OS upload by clicking the button **Yes**.
4. Wait until the update process is completed.
5. Set the mode selector to **STOP** or **RUN** position.
6. To activate the transferred OS, re-boot the controller.

Updating the operating system by means of FTP

Using an FTP client an OS file can be transferred to the JC-440EXT controller.

Performing the update

- ✓ Before the controller is switched on, the mode selector of the controller is in the **RUN** or **STOP** position.
- ✓ An OS file for the JC-440EXT controller is available.
- ✓ An FTP connection to the controller is possible.
- ✓ The login parameters for a user with administrator or system rights are at hand.
- ✓ The OS is running.
- ✓ Make sure the controller remains energized during the operating system update.

1. Open an FTP connection to the JC-440EXT.
2. Log in with administrator or system rights.
3. Navigate to the directory */System/OS*.
4. Transfer the OS file.
5. Wait until the update process is completed.
6. Clear the FTP connection.
7. Set the mode selector to **STOP** or **RUN**.
8. To activate the transferred OS, re-boot the controller.

OS update from a USB flash drive

An automatic OS update of the controller from the USB flash drive can be carried out using the AutoCopy function.

ⓘ Info

Further information

For in-depth information, see the *File System* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

Updating the OS from within the application program

The file functions included in the STX language allow for a program-controlled OS update of a JC-440EXT from within an OS file.

Performing the update

- ✓ An OS file is available in the JC-440EXT file system.
- ✓ The operating system and the application program must be running.
- ✓ Make sure the controller remains energized during the operating system update.

1. Copy the OS file to a file of any name and of the extension ***.os** in the directory */System/OS*.
2. To activate the updated OS, for example by writing to the system command register, re-boot the controller.

STX program

```
Var
    SourceName:          String;
    DestinationName:      String;
    UpdateIt:              Bool;
End_Var;

//*****************************************************
// Name: OSupdate
// 1. Enable tracing in JetSym
// 2. Sett the name of the source file in 'SourceName'
// 3. Sett the flag 'UpdateIt'
//*****************************************************

Task OSupdate Autorun
    Var
        ResCopy: Int;
    End_Var;

    DestinationName := '/System/OS/OperatingSystem.os';
    Loop
        UpdateIt := False;
        When UpdateIt Continue;
        ResCopy := FileCopy(SourceName,
                            DestinationName);
        Trace('Result : ' + IntToStr(ResCopy) + '$n');
    End_Loop;
End_Task;
```

7.4 File System

The file system lets you access files located on the internal flash disk or an USB flash drive. Some files may be protected against read/write access or deletion. This is normal behavior. Some of these files are virtual files, such as firmware images, or protected files, such as EDS files.

NOTICE



Malfunctions caused by missing or damaged system files

Careless working with system files can result in malfunctions of the device.

► Do not delete or move any system files.

File categories

The files of the file system are categorized as follows:

– System directories or system files used by the operating system
– Files accessible to the user

System directories

The user is not allowed to delete system directories. System directories even survive formatting.

Directory	Description
/System	– System configuration – System information
/USB	– Root directory of the USB flash drive

Tab. 47: System directories

Formatting and checking of data

The JC-440EXT is only able to format the flash disk. Formatiing or checking the USB flash drive is not possible.

ⓘ Info

Further information

For in-depth information, see the *File System* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

7.4.1 Properties

The following properties apply to the internal flash disk and USB flash drive:

– 8 files max. to be opened simultaneously
– Separate directory names by a slash "/", not by a backslash "\".
– When the controller creates a file, the file contains date and time assigned by the controller.
– Date, time, and file size are not available for all system files.

Flash disk - Properties

Size

The following disk space is available to the user:

– 32 MB

Features

The internal flash disk drive has got the following properties:

– Up to 7 directory levels and 1 file level are allowed.
– Differentiation between upper and lower case.
– Directory and file names with a length of up to 63 characters are possible.
– All characters except "/" and ".." are permitted for directory and file names.
– User/access administration for a maximum number of 31 locks and 33 users.

USB flash drive - Properties

Capacity

The available capacity depends on the USB flash drive being used. Tested capacity:

– 2 ... 64 GB

Properties

The USB flash drive has got the following properties:

– The USB flash drive must be compatible with FAT 12, FAT 16, or FAT 32.
– No case sensitivity.
– Directory and file names with a maximum of 63 characters each are possible.
– The following characters are not permitted in directory and file names: "/", "\", ":", "*", "?", "<", ">" and "|"
– The number of directory levels depends on the formatting.
– There is no user/access administration.

Guarantee

Bucher Automation AG only assumes a guarantee for USB flash drives optionally available from Bucher Automation AG. Refer to the Accessories [▶ 141] section for matching USB flash drives.

8 Programming

Programming of the JC-440EXT is performed using the JetSym programming tool.

8.1 Abbreviations, module register properties and formats

Abbreviations

The abbreviations used in this document are listed in the table below:

Abbreviation	Description
R 100	Register 100
MR 150	Module register 150

Tab. 48: Abbreviations

Module register properties

Each module register is characterized by certain properties. Most properties are identical for many module registers. In the following description, module register properties are mentioned only if a property deviates from the default properties listed below.

Property	Standard design
Access	Read/write
Value after reset	0 or undefined (e.g. revision/version number)
Takes effect	Immediately
Write access	Always
Data type	Integer

Tab. 49: Module register properties

Numerical formats

The numerical formats used in this document are listed in the table below:

Notation	Format of numerical values
100	Decimal
0x100	Hexadecimal
0b100	Binary

Tab. 50: Numerical formats

8.2 Storage options - Overview

The controller JC-440EXT features several types of program and data memories. This memory is located directly in the CPU or in separate memory or I/O modules.

There is volatile and non-volatile memory:

– Volatile memory loses its content at switching off.
– Non-volatile memory keeps its content even when the power supply is off.

8.2.1 Memory for non-volatile application program variables

Non-volatile variables let you store data which must be maintained when the JC-440EXT is de-energized.

Properties

– Global variables which are assigned to permanent registers (%RL)
– Variables are stored in a compact way.
– Size: 480,000 bytes
– Register numbers: 1000000 ... 1119999 (identical with %VL area)

Types of access

– Via JetSym
– From HMIs
– From within the application program

JetSym STX program

The following program example increments 4 non-volatile variables every second. The working range of the counters is between 0 and 255 (variable type: byte). For these 4 variables the 4 bytes of register 1000010 are used.

```
Var
    Cnt1, Cnt2, Cnt3, Cnt4: Byte At %RL 1000010;
End_Var;

Task Count4 Autorun
    Loop
        Inc(Cnt1);
        Inc(Cnt2, 2);
        Inc(Cnt3, 5);
        Inc(Cnt4, 10);
        Delay(T#1s);
    End_Loop;
End_Task;
```

Setup pane

The JetSym setup pane shows the content of the variable. As all 4 counters are typed byte, the counter will overflow after a relatively short period of time.

	Name	Nummer	Inhalt		Typ
1	Cnt1	1000010	209	1	
2	Cnt2	1000010	162	2	
3	Cnt3	1000010	21	3	
4	Cnt4	1000010	42	4	
5					
6					

Number	Element	Description
1	Current content of the variable Cnt1	The content of the variable is incremented by 1 every second.
2	Current content of the variable Cnt2	The content of the variable is incremented by 2 every second.
3	Current content of the variable Cnt3	The content of the variable is incremented by 5 every second.
4	Current content of the variable Cnt4	The content of the variable is incremented by 10 every second.

8.2.2 Registers on I/O modules

These registers are located on modules connected to the JX3 system bus.

Properties

- Global variables with dedicated addresses (%VL)
- The type is depending on the module.
- Register numbers on the JX3 system bus: 100020000 ... 100179999
- Register numbers of remote devices connected to the JX3-BN-ETH: 1nnn020000 ... 1nnn179999 (nnn = GNN)
- Register numbers of remote devices connected to the JX3-BN-EC: 12nn020000 … 12nn339999 (nn = ENN)

Access

- Via JetSym
- Via email client
- Via browser (via HTTP server)
- Via HMIs
- From within the application program
- From another JC controller using the NET_COPY command

8.2.3 Memory for non-volatile registers on the backplane module

These registers can be used to store data that need to be maintained in the event that the electronic component of the controller requires replacement.

For example this applies to the register storing the station number which is permanently assigned to a specific part of the facility.

Properties

- Global variables with dedicated addresses (%VL)
- Integer registers
- Slow access: Milliseconds
- Limited number of write/erase cycles: Approx. 10,000
- Number of registers: 128
- Register numbers: 108100 ... 108227

Access

- Via JetSym
- Via email client
- Via browser (via HTTP server)
- Via HMIs
- From within the application program
- From another JC controller using the NET_COPY command

JetSym STX program

The following program example displays the station number the user has stored on the JX3 backplane module on the HMI when the program is launched:

```
Var
    StationNo: Int At %VL 108100;
End_Var;

Task DisplayStation Autorun
    DisplayText(0, 1, '_Station : ');
    DisplayValue(0, 0, StationNo);
    Loop
        // ...
    End_Loop;
End_Task;
```

8.2.4 Inputs and outputs

Inputs and outputs are 1-bit variables. This means they can either have the value TRUE or FALSE. Inputs and outputs are addressed in immediate read/write cycles.

Properties of virtual inputs/outputs

– Global variables assigned to permanent addresses (%IX, %QX)
– Used for RemoteScan via Modbus/TCP
– Quantity: 16000
– I/O numbers: 20001 ... 36000

Properties of digital inputs/outputs

– Global variables assigned to permanent addresses (%IX, %QX)
– Located on modules connected to the JX3 system bus
– I/O numbers on the JX3 system bus: 100000201 ... 100001716
– I/O numbers of remote devices connected to a JX3-BN-ETH: 1nnn010201 ... 1nnn011716 (nnn = GNN)
– I/O numbers of remote devices connected to a JX3-BN-EC: 12nn000201 … 12nn003316 (nn = ENN)

Types of access

– By JetSym
– By the email client
– Via a browser (via the HTTP server)
– From HMIs
– From within the application program

8.2.5 Flag

Flags are one-bit operands. This means they can be either TRUE or FALSE.

Properties of user flags

– Global variables with dedicated addresses (%MX)
– Non-volatile
– Quantity: 256
– Flag numbers: 0 ... 255

Properties of overlaid user flags

– Global variables with dedicated addresses (%MX)
– Non-volatile
– Overlaid by registers 1000000 ... 1000055
– Quantity: 1792
– Flag numbers: 256 ... 2047

Properties of special flags

– Global variables with dedicated addresses (%MX)
– When the operating system is launched, special flags are initialized using their default values
– Quantity: 256
– Flag numbers: 2048 ... 2303

Types of access

– By JetSym
– By the email client
– Via a browser (via the HTTP server)
– From HMIs
– From within the application program

JetSym STX program

The following program example increments or decrements the "Counter" variable when pressing the F1 or F2 HMI key. These two keys are mapped to the corresponding flags. As long as the key is pressed, the corresponding LED in this key is enabled.

```
Var
    CountUp: Bool At %MX 2201;
    CountDown: Bool At %MX 2202;
    LedUp: Bool At %MX 2224;
    LedDown: Bool At %MX 2225;
    Counter: Int;
End_Var;

Task FlagCount Autorun
    Loop
        When CountUp Or CountDown Continue;
        If CountUp Then
            LedUp := True;
            Inc(Counter);
            When Not CountUp Continue;
            LedUp := False;
        Else
            LedDown := True;
            Dec(Counter);
            When Not CountDown Continue;
            LedDown := False;
        End_If;
    End_Loop;
End_Task;
```

Setup pane

The JetSym setup pane displays the state of the special flags and the content of the Counter variable.

	Name	Nummer	Inhalt	Typ
1	CountUp	2201	1	
2	CountDown	2202	0	
3	LedUp	2224	1	
4	LedDown	2225	0	
5	Counter		10	
6				

1
2
3

Number	Element	Description
1	Present state of key flags	Key F1 is pressed, key F2 is not pressed.
2	Present state of LED flags	LED in key F1 is enabled, LED in key F2 is disabled.
3	Present state of Counter variable	The counter is incremented when F1 is pressed, and decremented when F2 is pressed.

8.3 Saving and loading an application program

When uploading the application program from JetSym to the device, this program is stored as a file to the internal flash disk by default.

If you want the device to save the application program to an SD card or USB flash drive, you must configure the storage location.

When restarting the application program via JetSym or after booting the device, the application program is loaded and executed via the file system. The user determines the program that is to be executed.

ⓘ Info

Further information

For in-depth information, see the *File System* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.4 Addressing I/O Expansion Modules

The JX3 I/O module connects to sensors and actuators. The data are either sent directly to the controller via the JX3 system bus or, if the JX3 modules are located remotely, via Ethernet bus nodes or EtherCAT® bus nodes.

Each JX3 I/O module provides 10,000 module registers.

These module registers are mapped to registers in the controller. The only way of writing and reading process, configuration and diagnostic data to and from an expansion module is via controller registers. Controller registers can be accessed in the application program of the controller, in a setup pane of JetSym or via a visualization application.

The number of a controller register or I/O being mapped to a module register depends on the following parameters:

- Controller model
- Type of connection between controller and expansion module
  - Local direct connection
  - Remote connection via Ethernet
  - Remote connection via EtherCAT®

– Position and number of expansion modules in the system
  The number of expansion modules that can be connected to a controller depends on the model of the expansion module. After max. 8 expansion modules, a power supply module must be inserted.

Example system overview

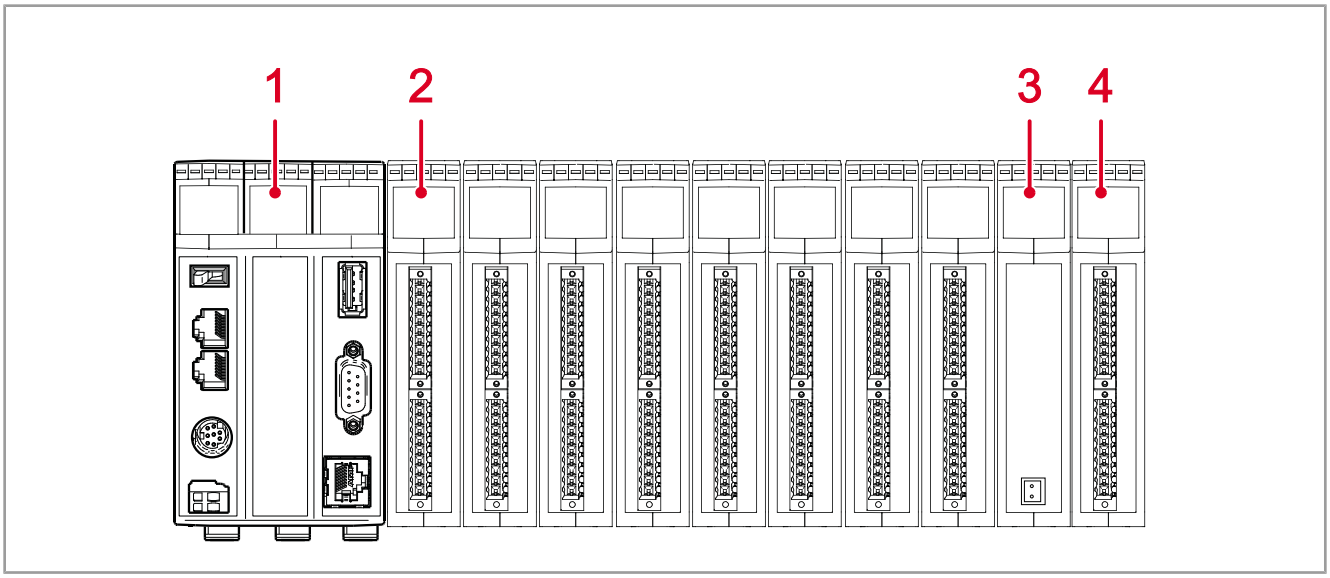


Fig. 18: Example: System overview of a controller together with various expansion modules

1	Controller
2	First expansion module
3	Power supply module
4	Further expansion modules

ⓘ Info

Number of connectible expansion modules

You can calculate the exact amount of connectible expansion modules by means of the system bus configurator, JX3-sysbus_configurator_xxx_e.

You can find the configurator as a download at www.bucherautomation.com under product page *JX3*-Modules > Downloads.

ⓘ Info

Further information

For in-depth information, see the *JX3 System* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.4.1 Numbering Registers and I/Os

Module registers – definition

Module registers are the data interface of the JX3 module. Use module registers to read process, configuration and diagnostics data from the JX3 module, or write such data to the JX3 module.

– The module register number within a module is unique.
– This unique register number lets you access a specific module register within the system.

Registers - Definition

There are several ways to access registers directly and indirectly:

– From an application program
– From the Setup pane of JetSym
– From a visualization application

The register number within the system is unique.

ⓘ Info

Further information

For in-depth information, see the *JX3 System* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

Expansion modules connected with a controller

Our products offer a host of features accessible to the user via registers. Each register is addressed by a unique number – the register number. Each digital input and output has a unique I/O number.

Register numbering system

Register numbers consist of a prefix, the module position in the system and the module register number. If the expansion modules are connected with the controller via JX3 system bus, the prefix is 100. In this case, the module register number is always a four-digit number.

100XXZZZZ

Fig. 19: Example: Register numbers

Digits	Description	Value range
100	Prefix	
XX	Position of the module in the system	02 … 17
ZZZZ	Module register number	0000 … 9999

I/O numbering system

I/O numbers provide direct access to the inputs or outputs of the module. These I/O numbers consist of a five-digit prefix, the module position in the system and the I/O number of the module. The I/O numbers always start with the constant prefix **10000**.

10000XXZZ

Fig. 20: Example: I/O numbers

Digits	Description	Value range
10000	Prefix	
XX	Position of the module in the system	02 … 17
ZZ	Module-specific I/O number	01 … 16

Expansion modules connected to an Ethernet bus node

The Ethernet bus node and the controller communicate via Ethernet system bus. When addressing expansion modules via Ethernet bus node, the Global Node Number (GNN) becomes part of the register number.

System overview

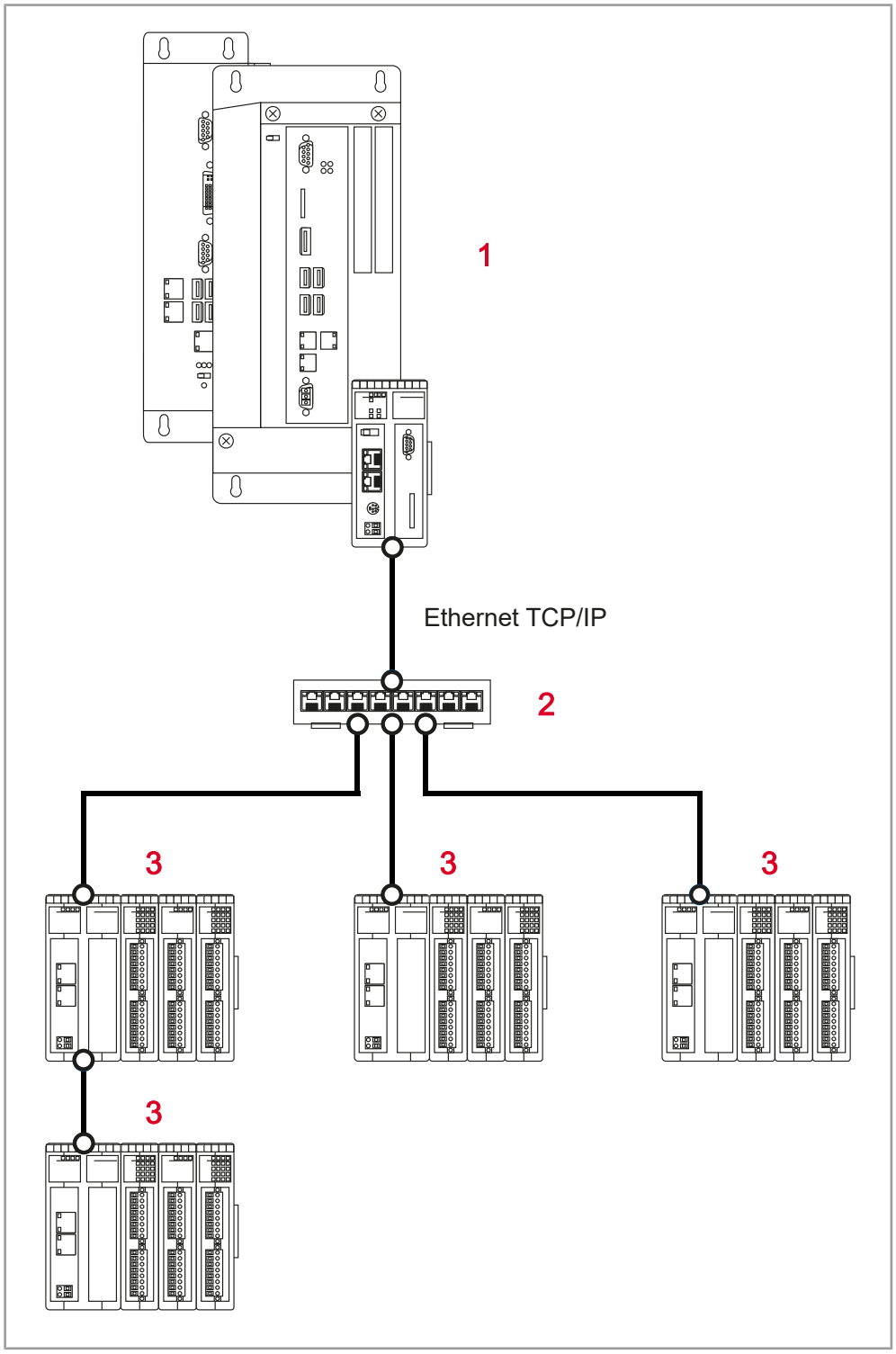


Fig. 21: System overview

1	Controller
2	Ethernet switch
3	Up to 64 Ethernet bus nodes per controller and up to 16 JX3-IO modules per Ethernet bus node

Definition of global node number

The Global Node Number (GNN) is used to identify Bucher Automation devices (e.g. controllers, bus nodes) within an Ethernet network:

– Within one network, each Bucher Automation device must have a unique GNN.
– The JetSym Hardware Manager automatically assigns the GNN during configuration.
– The value range of the GNN within a project is 000 ... 199.
– The GNN of the controller is always 000.

Register numbering system

Register numbers consist of a prefix, the GNN, the module position within the system and the module-specific register number.

1NNNXXZZZZ

Fig. 22: Example: Register numbers

Digits	Description	Value range
1	Prefix	
NNN	Bus node ID, GNN	001 … 199
XX	Position of the module within the station	02 … 17
ZZZZ	Module register number	0000 … 9999

I/O numbering system

I/O numbers provide direct access to the inputs or outputs of the module. The I/O numbers consist of prefix 1, the GNN, prefix 2, the module position in the system and the module-specific I/O number.

1NNN01XXZZ

Fig. 23: Example: I/O numbers

Digits	Description	Value range
1	Prefix 1	
NNN	Bus node ID, GNN	001 … 199
01	Prefix 2	
XX	Position of the module within the station	02 … 17
ZZ	Module-specific I/O number	01 … 16

ⓘ Info

Further information

For in-depth information, see the *Ethernet System Bus* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

Expansion modules connected to an EtherCAT® bus node

EtherCAT® bus node and controller communicate via EtherCAT® system bus. When addressing the expansion modules via EtherCAT® bus node, the EtherCAT® Node Number (ENN) becomes part of the register number. The ENN is used to identify controllers and EtherCAT® bus nodes within an EtherCAT® network. The ENN is automatically assigned by JetSym.

System overview

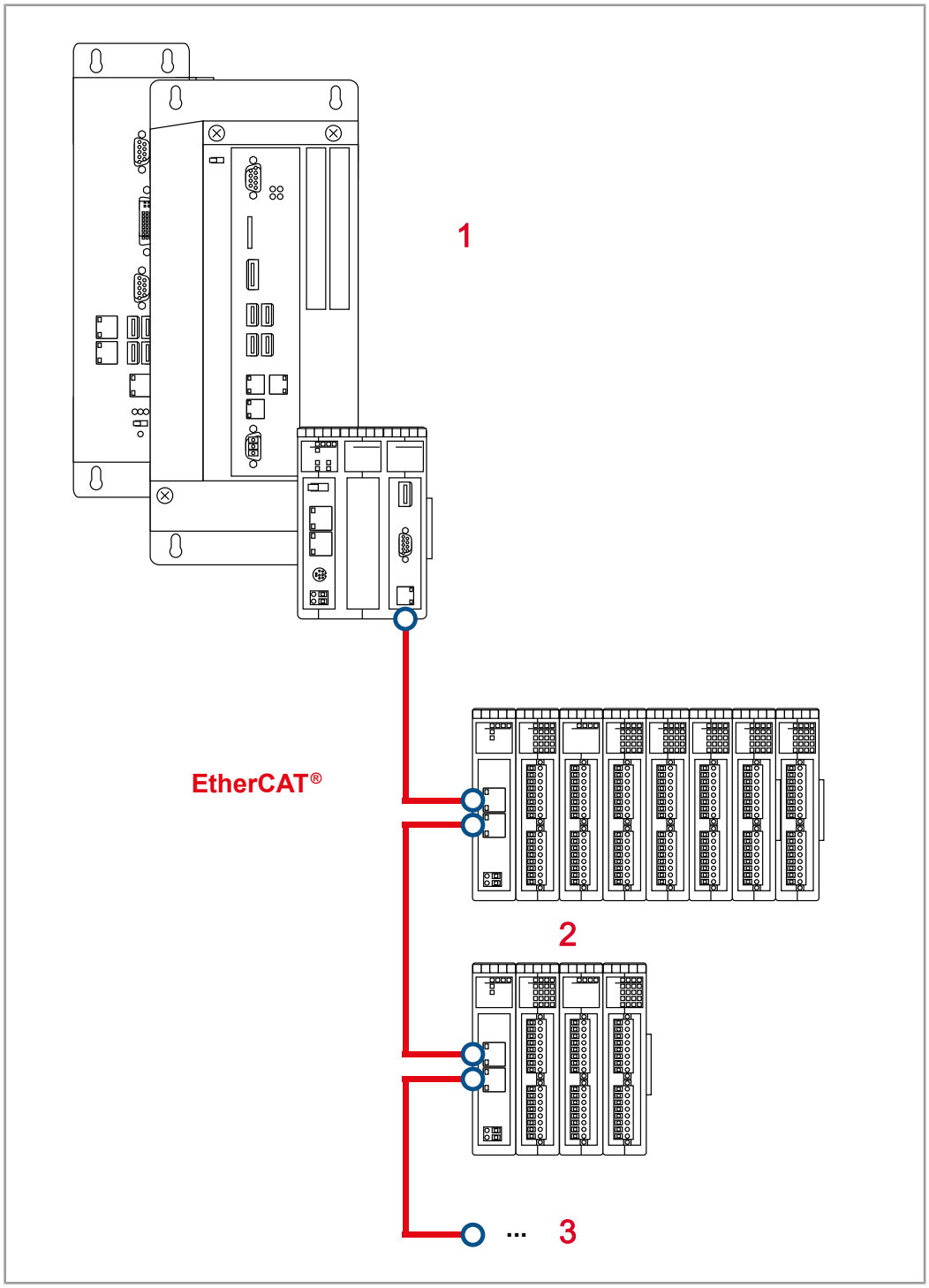


Fig. 24: System overview

1	EtherCAT® master
2	EtherCAT® bus node with up to 16 JX3 I/O modules
3	Up to 99 JX3-BN-EC

Register numbering system

The register numbers consist of a prefix, the ENN, the module position within the system and the module-specific register number.

12NNXXZZZZ

Fig. 25: Register numbers

Digits	Description	Value range
12	Prefix	
NN	Bus node ID, ENN	01 … 99
XX	Position of the module within the station	02 … 33
ZZZZ	Module register number	0000 … 9999

I/O numbering system

I/O numbers provide direct access to the inputs or outputs of the module. The I/O numbers consist of prefix 1, the ENN, prefix 2, the module position in the system and the module-specific I/O number.

12NN00XXZZ

Fig. 26: I/O numbers

Digits	Description	Value range
12	Prefix 1	
NN	Bus node ID, ENN	01 … 99
00	Prefix 2	
XX	Position of the module within the station	02 … 33
ZZ	Module-specific I/O number	01 … 16

8.5 Option model

Model

The JC-440EXT offers a variety of additional options for customizing firmware features to individual needs. The licensing scheme incorporated in the operating system allows users to enable JCF options (such as motion control) or communication features (such as OPC UA) by means of licensing keys. All licensing keys are stored in the license file [▸ 85].

JC-440EXT-MAX

The JC-440EXT-MAX model variant comes with all available options and supports the maximum number of axes. The JC-440EXT-MAX does not require a license file. If a license file has been uploaded, it will be ignored. This means that individual license files cannot be deleted.

NOTICE

Minimum OS version for the full range of functions

To be able to use the full range of functions of the JC-440EXT-MAX, use at least OS version 1.15.0.16.

Ordering options

You can include any option when purchasing a device from Bucher Automation or upgrade at a later time (Available firmware functions [▶ 84]).

NOTICE



Validity of options

Firmware features are assigned to the device's serial number. An option may only be used for a single device.

► When ordering an option, always mention the serial number of the respective device.

If you include a firmware option in your initial device purchase, the corresponding license file is already stored on the device.
If you retrofit your device with a firmware option, you will receive a new license file, including all license keys, which you will need to transfer to your device via JetSym, FTP or AutoCopy.

8.5.1 Available firmware functions

Available JCF options

JCF option	Description	Item number
JCF4-C_ETH_(PRIM)	User-programmable Ethernet function	10001752
JCF4-C_ETHERCAT_MASTER	EtherCAT® master (JX3-BN-EC, JetMove)	10001744
JCF4-C_FTP_CLIENT	FTP client file dispatch from STX	10001751
JCF4-C_HTTP	HTTP server (web server)	10001749
JCF4-C_MODBUS/TCP	MODBUS/TCP client and server	10001748
JCF4-C_MQTT	MQTT client	10001753
JCF4-C_OPCUA_CLIENT	OPC UA client	10001746
JCF4-C_OPCUA_SERVER	OPC UA server	10001747
JCF4-C_SMTP	SMTP client (sending of e-mails)	10001750
JCF4-M_AX	1 physical axis (incl. PtP function)	10001741
JCF4-M_PATH	MCX path group	10001743
JCF4-M_SV1	SW positioning fct. 16 axes	10001757
JCF4-M_TECHNO	MCX technology group	10001742

Example

Your machine should have the following functions:

– 4 servo axes with point-to-point positioning function
– JetMove 3000 as servo amplifier
– Additional access via OPC UA

For this, you will need the following:

– 1x JC-440EXT
– 4x JCF4-M_AX
– 1x JCF4-C_ETHERCAT_MASTER (JM-3000 axes are EtherCAT® slaves)
– 1x JCF4-C_OPCUA_SERVER (for the connection to the visualization device which includes an OPC UA client)

ⓘ Info

JCF License Configurator

The *JCF License Configurator* helps you engineer the project to your requirements.

To use the *License Configurator* open www.bucherautomation.com and go to the *product page JC-440EXT > Downloads*.

8.5.2 License File

NOTICE

Corruption of the license file

Changes to the license file may corrupt the file and render it unusable. That is, the JCFoptions will no longer work.

► Do **not** change the contents of the license file!

To be able to use license-based firmware functions (JCFoptions), a valid license file must be available. All licenses are combined in a single license file. There can only be **one** license file on a device, because it is linked to the serial number of the device.

Name of the license file

The name of the license file is composed of the serial number of the device and the file extension *.lic*:
Serial_number.lic

Location

The license file must be located in the file system of the device in the **/System** folder.

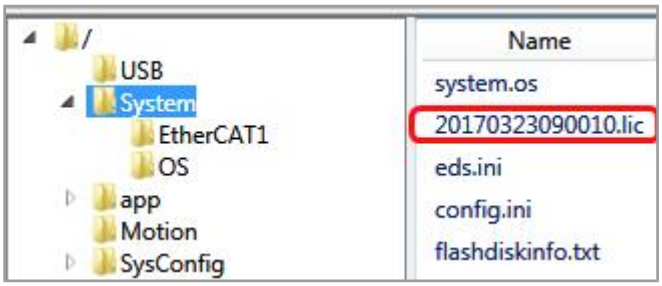


Fig. 27: License file - Storage location

Activation

The validity of the license file and the license key it contains is checked by the operating system of the controller when the device is started. The corresponding JCF options are then activated.

Example

Example content of a license file:

```
!;# Controller option licence file

[IDENTIFICATION]
Controller = JC-440EXT-AX6-PTP-ECM-FTC-..
SerialNo = 20170323090010
Itemno = 10001541
Id = 5aaa5ea4fa


[JCF4-M_AX]
Id = 1
Value      = 6
Time = 2147483647
Key = 86da66075cfc1b8104686097ae2bb53…

[JCF-C_ETHERCAT_MASTER]
Id = 5
Value = 1
Time = 2147483648
Key = 6c64be219b794e9dff295e289d48513…
```

8.6 System commands

The controller supports system commands and system registers.

ⓘ Info

Further information

For in-depth information, see the *System Registers* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.7 Real-time clock

The controller is equipped with a real-time clock (RTC) that continues to work for a certain duration after the controller was de-energized (power reserve [▶ 20]).

Usage

Take advantage of the RTC when using the following feature:

– File date and time when creating a log file with time stamp

ⓘ Info

Restrictions

When using the real-time clock, the following restrictions apply:

– When the device is de-energized the power reserve is limited.

– The real-time clock has no automatic daylight savings time function.

Factory settings

At the end of the controller manufacturing process, the real-time clock is set to the actual date and time. As the power reserve corresponds to the typical delivery time, the as delivered condition is undefined.

ⓘ Info

Further information

For in-depth information, see the *System Registers* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.8 Startup delay time

The controller supports a time delay of the boot process. You can enter the delay time in a register.

ⓘ Info

Further information

For in-depth information, see the *System Registers* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.9 System runtime registers

The controller has several system runtime registers. The operating system of the controller increments the register value at fixed time intervals.

Application

The system runtime registers let you easily carry out time measurements in the application program.

ⓘ Info

Further information

For in-depth information, see the *System Registers* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.10 Monitoring interface activities

The controller supports the function *Monitoring of interface activity*. This feature allows the application program to determine if the serial and Ethernet interfaces are communicating with the servers.

Monitored interface activities

The following interface activities can be monitored:

– pcomX server via serial interface
– JetIP server via Ethernet interface
– STX debug server via Ethernet interface

Purpose

The monitoring function for interface activities can be used, amongst others, for the following scenarios:

– Plants requiring process visualization to ensure safe operation. They can be transferred into a save state if communication fails.
– When the service technician connects an HMI, the application program automatically displays additional status information.

ⓘ Info

Further information

For in-depth information, see the *System Registers* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.11 Ethernet system bus

The controller uses the Ethernet system bus as interface. The bus is based on TCP, UDP/IP and can therefore be used in parallel with other TCP, UDP/IP protocols.

Application

The Ethernet system bus has been designed for data exchange between the following devices via standard Ethernet:

– Programming unit
– Controllers
– Bus node
– Communication modules

Functions

The following functions of the bus are implemented in the controller:

– Acyclic (explicit) data exchange
– Cyclic (implicit) data exchange
– Error handling
– NetConsistency
– JetIPScan
– Connection management

ⓘ Info

Further information

For in-depth information, see the *Ethernet System Bus* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.12 Control of alphanumeric displays and HMIs

Connecting

HMIs connect to the serial interface (port X11) on the controller.

Control of HMIs

The controller provides the following display options:

– Displaying text strings
– Displaying the contents of variables
– Scanning the HMI keys
– Switching the HMI LEDs
– Monitor function

Display functions

The display features are part of the STX language set.

ⓘ Info

Further information

For in-depth information, see the *Controlling Alphanumeric HMIs (LCD) and Printers* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.13 Controlling printer and serial interfaces

Connecting

The devices connect to the serial interface (port X11) on the controller.

Controlling

The controller provides the following display options:

– Displaying text strings
– Displaying the contents of variables

Display functions

The display features are part of the STX language set.

ⓘ Info

Further information

For in-depth information, see the *Controlling Alphanumeric HMIs (LCD) and Printers* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.14 Project Engineering of a JX3 Station

JX3 station

A JX3 station consists of a JetControl controller or a JX3-BN-xxx bus node and JX3-IO modules connected to it.

Configuration

Access to- IO modules is completely transparent, as configuration of the JX3 system bus is not required. The controller or the bus node automatically detects connected modules and commissions them.

Modules to connect

You can connect all JX3-IO modules except JX3-COM-xxxx modules to a JX3 station.

ⓘ Info

Further information

For in-depth information, see the *JX3 System* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.15 JCF-SV1 "simple servo function"

The JCF-SV1 function allows the user to implement a simple, yet convenient positioning of servo drives or frequency inverter drives using analog set values.

It is possible to operate up to 16 axes independently of each other.

Type	Servo axis count	Minimum HW revision	From OS version
JC-440EXT	16	1.05	1.08.0.00

Activating the function

To activate the JCF-SV1 function in the controller, the following prerequisite must be met:

– The JCF option **JCF4-M_SV1** is enabled (Available firmware functions [▶ 84]).

Configuration

Access to process variables, such as target position, actual position, reference switch and limit switch, is provided by the JX3-IO modules. They connect either directly via the local JX3 system bus of the controller, or via the JX3-BN-ETH bus node in a distributed setup.

Engineering environment

To create the application program, use JetSym version 5.x and higher.

JCF-SV1 feature

The register interface provides access to the JCF-SV1 feature.

Commands, such as POS, and AXARR, or a Motion API are not available.

ⓘ Info

Further information

For in-depth information, see *JCF-SV1 OS Function* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.16 E-mail feature

The user creates template files for emails, where the controller enters any variables when they are being sent. This allows for automated transfer of reports or other production or maintenance information via email.

The controller sends emails to an email server that will then forward the message to the addressee.

Activating the email feature

To activate the email feature in the controller, the following requirements must be met:

– A valid email configuration file **/EMAIL/email.ini** exists while the controller is booting.

– The JCF option **JCF4-C_SMTP** is enabled (Available firmware functions [▶ 84]).

If this requirement has been met, the corresponding bit in the web status register is set and the email feature is available.

R 202930

Web status

The registers shows available features in a bit-coded way.

Property	Description	
Type of access	Read	
Meaning of the bits		
Bit 0	FTP server	
	1 =	available
Bit 1	HTTP server	
	1 =	available
Bit 2	Email	
	1 =	available
	Bit 2 is set only if the **/EMAIL/email.ini** configuration file is available.	
Bit 3	Data file function	
	1 =	available
Bit 4	Modbus/TCP	
	1 =	available
Bit 5	Modbus/TCP	
	1 =	available
Bit 7	FTP client	
	1 =	available

Tab. 51: Web status

ⓘ Info

Further information

For in-depth information, see the *File System* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.17 Modbus/TCP

Enabling the Modbus/TCP feature

To enable the Modbus/TCP feature in the controller, the following requirement must be met:

– The JCF option **JCF4-C_MODBUS/TCP** is activated (Available firmware functions [▶ 84])

This permanently sets bits 4 and 5 in the Web Status register 202930.

R 202930

Web status

The registers shows available features in a bit-coded way.

Property	Description	
Type of access	Read	
Meaning of the bits		
Bit 0	FTP server	
	1 =	available
Bit 1	HTTP server	
	1 =	available
Bit 2	Email	
	1 =	available
	Bit 2 is set only if the **/EMAIL/email.ini** configuration file is available.	
Bit 3	Data file function	
	1 =	available
Bit 4	Modbus/TCP	
	1 =	available
Bit 5	Modbus/TCP	
	1 =	available
Bit 7	FTP client	
	1 =	available

Tab. 52: Web status

Modbus/TCP server

With the Modbus/TCP feature enabled and the Modbus/TCP server launched, an external client can access registers, flags, inputs and outputs.

Modbus/TCP client

The Modbus/TCP client included in the device supports only Class 0 Conformance. This class uses commands for reading and writing multiple registers. One frame can transmit up to 125 registers with a width of 16 bits.

The protocol ID is "0". Assignment of sent and received frames is carried out using the transaction ID.

8.17.1 Modbus/TCP server

If a valid license exists, the Modbus/TCP function is activated and the Modbus/TCP server has been started, registers, flags, inputs and outputs can be accessed by an external client.

Number of possible connections

4 connections can be open at the same time.

Info

Restriction

Modbus/TCP only supports transmission of registers with a width of 16 bits. From this follows, that only the 16 least significant bits are transmitted when 32-bit registers are sent. When assigning incoming register values to the internal 32-bit registers no sign extension will be carried out.

Addressing

The addresses which have been received via Modbus/TCP can be modified locally in the Modbus/TCP server. There are 3 registers for this purpose. The basic addresses for accessing registers, inputs and outputs are entered into these registers. Then, the address contained in the Modbus/TCP frame specifies the address with reference to the basic address.

R 272702

Register offset

The basic address for accessing registers via Modbus/TCP is entered into R 272702.

Property	Description
Value after reset	1000000

Tab. 53: Register offset

R 272704

Input offset

The basic address for accessing inputs via Modbus/TCP is entered into register 272704.

Property	Description
Value after reset	100000000

Tab. 54: Input offset

R 272705

Output offset

The basic address for accessing outputs via Modbus/TCP is entered into R 272705.

Property	Description
Value after reset	100000000

Tab. 55: Output offset

Example 1

The Modbus/TCP server on the controller receives from a Modbus/TCP client the command **read multiple registers** starting from register number 100. The number of registers to be read is 5. Register 272702 *Register Offset* contains the value 1000000. Hence, registers 1000100 through 1000104 will be read.

Example 2

The Modbus/TCP server of the controller receives from a Modbus/TCP client the Modbus/TCP command **read input discretes** with the input number 210 and the instruction to read this input. Register 272704 *Input offset* contains the value 100000000. Hence, input 100000210 of a peripheral module, such as JX3-DI16, will be read.

Example 3

The Modbus/TCP server on the JC-440EXT receives from a Modbus/TCP client the command **write coils** specifying output number 205 and the instruction to enable this output. Register 272705 *Output offset* contains the value 100000000.

Hence, output 100000205, for example of a peripheral module JX3-DO16, will be activated.

Supported commands

Class 0

Command	Description
fc 3	**read multiple registers**
	Reading register sets The starting register number within the controller is calculated as follows: Add the register number specified in the command to the content of R 272702 *Register Offset*.
fc 16	**write multiple registers**
	Writing register sets The starting register number within the controller is calculated as follows: Add the register number specified in the command to the content of R 272702 *Register Offset*.

Tab. 56: Supported commands – Class 0

Class 1

Command	Description
fc 1	**read coils**
	Reading outputs The output register number within the controller is calculated as follows: Add the output number specified in the command to the content of R 272705 *Output offset*.
fc 2	**read input discretes**
	Reading inputs The input register number within the controller is calculated as follows: Add the input number specified in the command to the content of R 272704 *Input offset*.

Command	Description
fc 4	**read input registers**
	Reading inputs blockwise in 16-bit words The starting register number within the controller is calculated as follows: Add the register number specified in the command to the content of R 272702 *Register Offset*.
fc 5	**write coil**
	Enabling/disabling an individual output The output register number within the controller is calculated as follows: Add the output number specified in the command to the content of R 272705 *Output offset*.
fc 6	**write single register**
	Entering values into the 16 least significant bits of a register The starting register number within the controller is calculated as follows: Add the register number specified in the command to the content of R 272702 *Register Offset*.

Tab. 57: Supported commands – Class 1

Class 2

Command	Description
fc 15	**force multiple coils**
	Enabling/disabling several outputs The output register number within the controller is calculated as follows: Add the output number specified in the command to the content of R 272705 *Output offset*.
fc 23	**read/write registers**
	Reading/writing registers simultaneously The starting register number within the controller is calculated as follows: Add the register number specified in the command to the content of R 272702 *Register Offset*.

Tab. 58: Supported commands – Class 2

8.17.2 Modbus/TCP client with STX functions

The Modbus/TCP client integrated in the controller supports Class 0 Conformance along with the Class 2 fc 23 command.
This class uses commands for reading and writing multiple registers. One frame transmits up to 125 registers of 16 bits width.
The protocol ID is "0". Assignment of sent and received frames is carried out using the transaction ID.

This chapter describes how to carry out noncyclical or cyclical transmission to a Modbus/TCP server using STX functions.

ⓘ Info

Obsolete system functions

As of JetSym 5.0, the system functions are outdated. Instead, use the corresponding JetSym STX functions.

Number of possible connections

Connections to 11 different Modbus/TCP servers can be open at the same time.

Noncyclical data transmission

The functions `ModbusReadReg()` and `ModbusWriteReg()` let you establish a noncyclical transmission channel to a Modbus/TCP server.
These functions copy data between registers of a Modbus/TCP server and STX variables. They establish a connection to the specified Modbus/TCP server, transmit the desired data and clear down the connection again.
If RemoteScan has already established a connection for cyclical data transmission, this connection will be used. Setting-up and clearing-down the connection is, therefore, not required.

Cyclical data transmission

Cyclical data transmission is made through the configurable function `RemoteScanConfig()`. The data are cyclically transmitted from and to the Modbus/TCP servers by means of STX variables.
To each Modbus/TCP server (IP address and port) a connection is established. The connection is established independent of how many communication units are configured on this server.
If several communication units are configured on one Modbus/TCP server, the accesses are serialized. This is because the servers often do not support **command pipelining**. If several servers have been configured, communication is carried out in parallel.

Unit ID

Converters from Modbus/TCP to Modbus RTU use the *Unit ID* for addressing the Modbus RTU servers. For this reason, the *Unit ID* can be set.

JetSym STX functions

This is a comparison between the system functions and the corresponding JetSym STX functions.

System function	Corresponding JetSym STX function
60	Function ModbusCRCgen(FramePtr: Int, Length: int): Int;
61	Function ModbusCRCcheck(FramePtr: Int, Length: int): Int;
65/67	Function ModbusReadReg(Const Ref MbParam: MODBUS_PARAM): Int;
66/68	Function ModbusWriteReg(Const Ref MbParam: MODBUS_PARAM): Int;
80/85	Function RemoteScanConfig(Protocol: RSCAN_PROTOCOL, Elements: Int, Const Ref Configuration: RSCAN_DSCR): Int;
81	Function RemoteScanStart(Protocol: int): Int;
82	Function RemoteScanStop(Protocol: int): Int;

Tab. 59: System functions vs. JetSym STX functions

ⓘ Info

Further information

For more information on this subject, refer to the JetSym Online Help.

8.18 User-programmable serial interface

The controller has a serial interface (mini DIN socket X11) which can be addressed from the application program to send and receive characters.

Applications

The user-programmable serial interface lets you connect devices which use communication protocols that are not supported by the OS of the controller. Fields of application, for example, are:

– Scales
– Scanners
– Display elements
– Frequency inverters
– Temperature controllers
– etc.

ⓘ Info

Further information

For in-depth information, see the *User-programmable Interface* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.19 User-programmable IP interface

The user-programmable IP interface lets you send or receive any data via Ethernet interface (jacks X14 and X15) using TCP/IP or UDP/IP. The data is processed in the application program entirely.

Activating the interface

To enable the interface in the controller, the following requirement must be met:

– The JCF option **JCF4-C_ETH_(PRIM)** is activated (Available firmware functions [▶ 84])

Applications

The user-programmable IP interface allows for data exchange via Ethernet connections which do not use standard protocols, such as FTP, HTTP, JetIP or Modbus/TCP. The following applications are possible:

– Server
– Client
– TCP/IP
– UDP/IP

ⓘ Info

Further information

For in-depth information, see the *User-programmable Interface* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.20 User-programmable CAN interface

CAN interface

The user-programmable CAN interface lets you send and receive CAN messages. The CAN messages are completely processed in the application program.

Advantage of CAN

This feature is not only apt for CANopen devices. It lets the user communicate with third-party devices which are based on a CAN protocol.

Applications

The user-programmable CAN interface can be used for the following applications:

– Devices which are equipped with a CAN interface can be controlled via proprietary protocols
– Controlling CANopen-capable devices

If your device supports the CANopen protocol, you should prefer to use the CANopen STX API for [▶ 101] communication.

Hardware requirements

The hardware required is a JC controller with CAN interface and/or JX2 system bus.

ⓘ Info

Further information

For in-depth information, see the *User-programmable Interface* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.21 CANopen STX API

The CANopen STX API provides a software platform that lets the user send and receive CANopen messages via STX functions.

The CANopen standard

CANopen is an open standard for networking and communication in the automation sector. The CANopen protocol is being further developed by CiA e.V. (CAN in Automation) and is based on the physical layer with CAN high-speed according to ISO 11898.

Specifications

The CANopen specifications can be obtained from the **CiA e.V.** homepage at http://www.can-cia.org.
The key specification documents are:

– CiA DS 301 - This document is also known as the communication profile and describes the fundamental services and protocols used under CANopen.
– CiA DS 302 - Framework for programmable devices (CANopen Manager, SDO Manager)
– CiA DR 303 - Information on cables and connectors
– CiA DS 4xx - These documents describe the behavior of a number of device classes in, what are known as, device profiles.

ⓘ Info

Further information

For in-depth information, see the *CANopen STX API* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.22 Motion control

Motion control is programmed in the Motion API interface in the programming language STX.

Seamless integration of axis functions into the controller is an essential feature of Bucher Automation AG control systems. This allows for easy implementation of point-to-point (PtP) positioning, technology functions (MC), path control and certain robot functions. This universal motion control system is called **motion control eXtended (MCX).**

MCX features

- Centralized generation of all command positions for single axes and axis groups
- Seamless integration into the controller
- Jerk control to minimize machine vibration
- Online generation of cam discs
- Combination of technology and path groups
- Cascading of axis groups
- Programming using SI units
- Consideration of mechanical parameters

MCX features

The following MCX features can be added to the JC-440EXT (see Optionsmodell [▶ 83]):

Option	Description	Required count
JCF4-M_AX	Up to 24 servo axes (point-to-point)	1 … 24
JCF4-M-PATH	Up to 4 active path groups	Servo axis count + 1
JCF4-M_TECHNO	Up to 6 active technology groups operating up to 24 cam discs with 100 segments each	Servo axis count + 1

Technology group

- Virtual leading axis
- External encoder as leading axis
- Cascaded groups
- Programming the whole group via leading axis
- Dynamic coupling and decoupling of following axes
- Print mark for high-precision position correction
- Up to 6 active technology groups operating up to 24 cam discs with 100 segments each

Electronic gearing

- Gear ratio can be changed dynamically
- Superimposed motions in the electronic gearbox

Electronic cam disc

– Segments: Polynomials 1, 3, 5, 7 (jerk-free transition); sine
– Definition via coefficients or marginal conditions
– Flexible enabling of segments depending on the positions of the leading and following axes or immediate
– Scaling and shifting the areas of definition during operation

Path group (Tool Center Point programming)

– Cartesian (3 spatial axes, 2 axes for orientation)
– SCARA (4 axes)
– 2D delta
– Buffered operation (total of buffers: 96)
– Look-ahead function
– Smoothened coupling (optimum velocity profile)
– Block-synchronous events
– Coupling an axis group to a leading axis
– Linear
– 2D circle
– 3D circle
– Helix
– Spline interpolation
– Gantry axis pair
– Shifting in axial direction via offset
– Up to 4 active path groups

ⓘ Info

Further information

For more information on Motion Control programming, refer to the JetSym Online Help.

8.23 FTP server

The controller supports the *FTP server* feature. The FTP server handles directories and files using an FTP client.

The files can be stored to the following storage media:

– Internal flash drive
– USB flash drive

Enabling the FTP server feature

On this device, the *FTP server* feature is permanently enabled. This is due to the device configuration upon purchase.

Bit 0 in the Web Status register 202930 is permanently set.

R 202930

Web status

The registers shows available features in a bit-coded way.

Property	Description	
Type of access	Read	
Meaning of the bits		
Bit 0	FTP server	
	1 =	available
Bit 1	HTTP server	
	1 =	available
Bit 2	Email	
	1 =	available
	Bit 2 is set only if the **/EMAIL/email.ini** configuration file is available.	
Bit 3	Data file function	
	1 =	available
Bit 4	Modbus/TCP	
	1 =	available
Bit 5	Modbus/TCP	
	1 =	available
Bit 7	FTP client	
	1 =	available

Tab. 60: Web status

Info

admin user login

As of OS version 1.13.0.22, advanced safety precautions require the *admin* user to log into the system via FTPS protocol rather FTP.

ⓘ Info

Further information

For in-depth information, see the *File System* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.24 HTTP server

The controller supports the *HTTP server* feature. A standard browser is sufficient for accessing the HTTP server.

The browser is for reading and displaying files which have been downloaded to the controller via FTP.

Using SSI (Server Side Includes) allows for register content and state information on inputs, outputs, and flags to be integrated into HTML pages at runtime.

Enabling the HTTP server feature

On this device, the *HTTP server* feature is permanently enabled. This is due to the device configuration upon purchase.

Bit 1 in the Web Status register 202930 is permanently set.

R 202930

Web status

The registers shows available features in a bit-coded way.

Property	Description	
Type of access	Read	
Meaning of the bits		
Bit 0	FTP server	
	1 =	available
Bit 1	HTTP server	
	1 =	available
Bit 2	Email	
	1 =	available
	Bit 2 is set only if the **/EMAIL/email.ini** configuration file is available.	
Bit 3	Data file function	
	1 =	available
Bit 4	Modbus/TCP	
	1 =	available
Bit 5	Modbus/TCP	
	1 =	available
Bit 7	FTP client	
	1 =	available

Tab. 61: Web status

Info

Further information

For in-depth information, see the *File System* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.24.1 Device Dashboard

The Device Dashboard is a browser-based software application designed to display in a user-friendly way key information and settings of a JC-4xx generation Bucher Automation control system. The purpose of this application is to provide machine manufacturers and operators with additional first-level support resources.

Info

Further information

For further information see the *Device Dashboard* application manual at www.bucher-automation.com.

8.25 FTP client

The FTP client allows a remote network device to access files and directories from within the application program by communicating with the FTP server of this network device.

Enabling the FTP client feature

To enable the FTP client feature in the controller, the following requirements must be met:

– The JCF **JCF9-C_FTP_CLIENT** option has been enabled (Available firmware functions [▶ 84]).

Bit 7 in the Web Status register 202930 is permanently set.

R 202930

Web status

The registers shows available features in a bit-coded way.

Property	Description	
Type of access	Read	
Meaning of the bits		
Bit 0	FTP server	
	1 =	available
Bit 1	HTTP server	
	1 =	available
Bit 2	Email	
	1 =	available
	Bit 2 is set only if the **/EMAIL/email.ini** configuration file is available.	
Bit 3	Data file function	
	1 =	available
Bit 4	Modbus/TCP	
	1 =	available

Property	Description	
Bit 5	Modbus/TCP	
	1 =	available
Bit 7	FTP client	
	1 =	available

Tab. 62: Web status

Info

Further information

For in-depth information, see the *File System* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.26 Automatic copying of controller data (AutoCopy)

The controller supports the AutoCopy function which automatically copies controller data. The AutoCopy function lets you copy data within the controller and/or between the controller and an FTP server, the connected expansion modules and a controller within the network.

Use cases

AutoCopy can be used to copy a new application program or operating system from the USB flash drive to the controller.

Prerequisites

AutoCopy is only executed when booting the JC-440EXT. Before switching on, the following conditions must be met:

– The mode selector S11 is in the *LOAD* position.
– A USB flash drive is inserted in the USB port X61.
– The USB flash drive contains a valid command file with the corresponding copy commands.

Info

Further information

For in-depth information, see the *File System* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.27 MQTT client

The controller JC-440EXT can be used as an MQTT client. The MQTT client is programmed exclusively via the STX application program.

MQTT protocol

The MQTT protocol is an open message protocol that has established itself as a standard in machine-to-machine communication and the Internet of Things. It is based on the publisher/subscriber architecture and enables clients to provide messages about specific topics via a broker.

Enabling the MQTT function

To enable the MQTT function in the controller, the following requirement must be met:

– The JCF option **JCF4-C_MQTT** is enabled (Available firmware functions [▶ 84]).

System requirements

As regards the software, the following minimum requirements must be met:

Software	Software version (or higher)
Operating system JC-440EXT	1.8.0.0
Application program JetSym	6.0.0

ⓘ Info

Further information

For more information on this subject, refer to the JetSym Online Help.

8.28 OPC UA server

By means of an OPC UA client, the OPC UA server lets you access the following objects of a controller:

– Selected system registers
– Globally declared STX variables (not localized)
– Globally declared STX variables (localized in the user register area of the controller)
– Method call

Enabling the OPC UA server

To enable the OPC UA server function in the controller, the following requirement must be met:

– The JCF option **JCF4-C_OPCUA_SERVER** must be activated (Available firmware functions [▶ 84]).

System requirements

As regards the software, the following minimum requirements must be met:

Software	Software version (or higher)	Comment
Operating system JC-440EXT	1.8.0.0	As of OS version 1.9.x.14 JetSym version 5.6.1 is required.
Application program JetSym	5.6.0	

ⓘ Info

Further information

For in-depth information, see the *OPC UA* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.29 OPC UA client

Access to the OPC UA server is ensured via the OPC UA client. It is possible to configure the client as STX program in JetSym. It is based on the PLCopen standard.

Enabling the OPC UA client feature

To enable the OPC UA client feature in the controller, the following requirements must be met:

– The JCF **JCF4-C_OPCUA_CLIENT** option has been enabled (Available firmware functions [▶ 84]).

Hardware Requirements

The following hardware requirements must be met:

Hardware	Software version (or higher)
JC-440EXT	0.05

System requirements

The following software requirements must be met:

Software	Software version (or higher)
JC-440EXT operating system	1.10.0.00
JetSym application program	5.6.3

ⓘ Info

Further information

For in-depth information, see the *OPC UA* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

8.30 Simple firewall

The *simple firewall* feature allows for Ethernet UDP and TCP ports to be opened and closed via registers during runtime. Configuring the settings requires admin credentials. The settings are remanent.

System requirements

The following software requirements must be met:

Software	Software version (or higher)
JC-440EXT operating system	1.13.0.20

ⓘ Info

Further information

For in-depth information, see the *System Registers* application-oriented manual.

For application-oriented manuals open www.bucherautomation.com and go to *product page JC-440EXT > Product-independent documentation*.

9 Registers - Overview

This register overview gives a condensed summary of the registers and flags of the JC-440EXT device.

Default address on the CANopen bus

The pre-set default address on the CANopen bus is:

Node ID	127 (0x7F)

Maximum number of CANopen interfaces

– Maximum number of CAN interfaces (CANopen-STX-API): 2
– CANMAX: 1

General overview - Registers

Register range	Description
100000 ... 100999	Electronic Data Sheet (EDS)
101000 … 101999	Configuration
102000 … 102999	Real-time clock
103000 … 103999	Serial port
104000 ... 104999	Ethernet
106000 ... 106499	CAN
107500 ... 107599	Flash disk
108000 ... 108999	CPU/backplane
109000 ... 109999	USB flash drive
200000 ... 209999	General system registers
210000 ... 219999	Application program
220000 ... 229999	HMI control
230000 ... 239999	Networking via JetIP
240000 ... 249999	JetSync
250000 ... 259999	Ethernet system bus
260000 ... 269999	RemoteScan
270000 ... 279999	Modbus/TCP
290000 ... 299999	E-mail
310000 ... 319999	File system/data files
320000 ... 324999	FTP client
350000 ... 359999	User-programmable IP interface
380000 ... 389999	Error history
390000 ... 399999	I/O networking
400000 ... 409999	CANopen
470000 ... 479999	NetConsistency
490000 ... 499999	DeviceManager
500000 ... 509999	Bus system
510000 ... 519999	DNS server/DNS cache
520000 ... 529999	JetIPScan
530000 ... 539999	SyncMaster
6yy000 … 6yy999	SW option JCF-SV1 Number of axes: yy = 00 … 16
1000000 ... 1119999	JC-440EXT: Application registers (non-volatile; integer/float)
50000000 ... 59999999	MotionControl

Register range	Description
100xx0000 ... 100xx9999	JX3 modules (xx: 02 ... 17)
500000000 ... 500999999	EtherCAT® system bus
1nnn020000 ... 1nnn179999	JX3 module register
1nnn810000 ... 1nnn819999	JetMove registers
1nnn980000 ... 1nnn980199	Indirect access via local R 236xxx
1nnn990000 ... 1nnn999999	Indirect access with variable destination window

I/Os - General overview

I/O numbers	Description
20001 ... 36000	Virtual I/Os for RemoteScan
10000mm01 ... 10000mm16	JX3 modules (mm = 01 ... 16)
1Nnn010201 ... 1nnn011716	JX3 modules on the JX3-BN-ETH (GNN: nnn = 000 ... 199)
12nn000201 … 12nn003316	JX3 modules on the JX3-BN-EC (ENN: nn = 01 … 99)

Flags - General overview

Flag	Description
0 ... 255	Application flags (non-volatile)
256 ... 2047	Overlaid by registers R 1000000 through 1000055
2048 ... 2303	Special flags

Configuration

Registers	Description
From file /system/ config.ini	
101100	IP address
101101	Subnet mask
101102	Default gateway
101103	DNS server
101132	Host name suffix type
101133 ... 101151	Host name (register string)
101164	Port number JetIP
101165	Port number for STX debugger
101180 ... 101198	File name for AutoCopy
Used by the system	
101200	IP address
101201	Subnet mask
101202	Default gateway
101203	DNS server
101232	Host name suffix type
101233 … 101251	Host name (register string)
101264	Port number JetIP
101265	Port number for STX debugger
101280 ... 101298	File name for AutoCopy
101299	Saving the settings (0x77566152)
101908	CRC of ModConfig.da

Real-time clock

Registers	Description
102910 … 102917	**Direct access**
102910	Milliseconds
102911	Seconds
102912	Minutes
102913	hours
102914	Day of the week (0 = Sunday)
102915	Day

Registers	Description
102916	Month
102917	Year
102920 … 102928	**Buffer access**
102920	Milliseconds
102921	Seconds
102922	Minutes
102923	hours
102924	Day of the week (0 = Sunday)
102925	Day
102926	Month
102927	Year
102928	Read/write trigger

Serial port

Registers	Description
103000	**Error state (bit-coded)**
Bit 14 = 1	Framing error
Bit 13 = 1	Parity error
Bit 12 = 1	Overflow
103001	**Protocol**
1	System logger
2	Prim
3	pcomX
103002	Baud rate (1,200 … 115,200)
103003	Bits per character (5 ... 8)
103004	Stop bits (1, 2)
103005	**Parity**
0	None
1	Odd
2	Even
3	1
4	0
103006	0 = RS-232, 1 = RS-422, 3 = RS-485/2
103010	Sending buffer
103011	Sending buffer filling level
103012	Receiving buffer (without immediate clearing)
103013	Receiving buffer (with immediate clearing)
103014	Receive buffer filling level
103015	Receive buffer, 16-bit, little endian
103016	Receive buffer; 16-bit; big endian
103017	Receive buffer, 32-bit, little endian
103018	Receive buffer; 32-bit; big endian
103019	Error counter

Ethernet

Registers	Description
Ethernet	
104111	MAC address X14/X15 (CPU manufacturer)
104112	MAC address X14/X15 (device)
104121	MAC address of the EtherCAT® interface (Bucher Automation)
104122	MAC address of the EtherCAT® interface (device)
104150 ... 104199	MIB counter
104350	GNN
IP	
104531	Current IP address (rw)
104532	Current subnet mask (rw)
104533	Current default gateway (rw)
104534	IP address of DNS server (rw)

Flash disk

Register range	Description
107500	Status
107501	**Command**
30	Read statistics
107510 … 107513	**Sector statistics**
107510	Total

Register range	Description
107511	Used
107512	Blocked
107513	Free
107520 … 107523	**Byte statistics**
107520	Total
107521	Used
107522	Blocked
107523	Free

LEDs

Registers	Description
108002	**All LEDs ON/OFF (bit-coded)**
Bit 0	"R" LED
Bit 1	"E" LED
Bit 2	LED D1
Bit 3	LED D2
108003	"R" LED
108004	"E" LED
108005	LED D1
108006	LED D2
Values	
0	OFF
1	Flashing slowly
2	Flashing fast
3	ON
108007	**LED USB**
0	OFF
3	ON
108008	**LED U1 ... U4 on/off (bit-coded)**
Bit 0	LED U1
Bit 1	LED U2
Bit 2	LED U3
Bit 3	LED U4

CPU/backplane module

Registers	Description
108010	DIP switch - All sliders
108011	DIP switch - Address
108012	DIP switch - Mode
108015	**Mode selector**
1	LOAD
2	RUN
3	STOP
108020	Backplane revision
108021	CPU revision
108099	Clear EEPROM (0x12345678)
108100 ... 108227	EEPROM registers on backplane

USB flash drive

Registers	Description
109000	**Status**
Bit 0 = 1	USB flash drive is plugged
Bit 1= 1	USB flash drive is ready
109002	Memory size in MB
109003	FAT type

General system registers

Register	Description
200000	OS version (major * 100 + minor)
200001	**Application program is running (bit 0 = 1)**
0/2	Stops program
1	Starts program
3	Resumes program
200008	**Error register 1 (identical with 210004)**
Bit 0	Error on flash drive
Bit 1	Error on JX3 system bus
Bit 3	Error on Ethernet system bus
Bit 7	Error in extended error register
Bit 8	Illegal jump
Bit 9	Illegal call

Register	Description
Bit 10	Illegal index
Bit 11	Illegal opcode
Bit 12	Division by zero
Bit 13	Stack overflow
Bit 14	Stack underflow
Bit 15	Illegal stack
Bit 16	Error while loading the application program
Bit 17	Memory protection violated
Bit 24	Cycle time timeout
Bit 25	Task lock timeout
Bit 31	Unknown error
200009	**Enhanced error register 1 (bit-coded)**
Bit 1	Error in the bus system
Bit 2	Error in the Device Manager
Bit 3	Error in ModConfig.da
Bit 4	RPC error
Bit 5	JetVM error
Bit 10	A bus node (publish/subscribe client) has reported an error
Bit 12	JetIPScan has reported an error
Bit 16	NetConsistency has reported an error
Bit 20	Internal memory error
Bit 21	Application program error
Bit 22	The system logger is active
Bit 30	Error when accessing JX3 IO module registers on JX3-BN-EC. Typically, this error results from an invalid register no.
200010	**Enhanced error register 2 (bit-coded)**
Bit 1	Error in the MC object
Bit 7	File system error
Bit 16	Error during EtherCAT® initialization
Bit 17	Error message prompted by EtherCAT® master
Bit 18	Error in EtherCAT® cycle

Register	Description
200051	JetIPScan **error numbers**
0	No error or warning
5	The user has terminated the function
1001	The response received first does not match responses 2 and 3
1002	The response received second does not match responses 1 and 3
1003	The response received third does not match responses 2 and 3
-1	All three responses are dissimilar
-2	The IP settings of at least one node are dissimilar
-3	The JetIPScan function was called while already active
-10	The length of the set value list is <1 or >255, or the pointer to the list is invalid
-11	A GNN of the set value list is <1 or >255, or exists multiple times
-20 ... -40	Internal error
-1001 ... -1199	The node has reported the wrong CtrlID or CtrlIDopt
-2001 ... -2199	The node has not called
-3001 ... -3199	Several nodes of the same GNN have called
200061	Error numbers of NetConsistency, see R 470040
200169	OS version (IP format)
200170	Controller model
200300	Currently available heap
200301	Available heap at system launch
200302	Available heap ahead application program boot-up
201000	Runtime register in milliseconds (rw)
201001	Runtime register in seconds (rw)
201002	Runtime register in register 201003
201003	10 ms units for register 201002 (rw)
201004	Runtime register in milliseconds (ro)

Register	Description
201005	Runtime registers in microseconds (ro)
202930	**Web status (bit-coded)**
Bit 0 = 1	FTP server is available
Bit 1 = 1	HTTP server is available
Bit 2 = 1	Email is available
Bit 3 = 1	Data file function is available
Bit 4 = 1	Modbus/TCP has been licensed
Bit 5 = 1	Modbus/TCP is available
Bit 6	Reserved
Bit 7 = 1	FTP client is available
202936	**Control register – file system**
0xc4697a4b	Format the flash drive
202960	Password for system command register (0x424f6f74)
202961	**System command register**
102	Controller restart (reboot)
103	Application register test
104	Reset non-volatile parameters
122	Wait for communication – OFF
123	Wait for communication – ON
160	Task switch on I/O access OFF
161	Task switch on I/O access ON
170	Resume task time slice OFF
171	Resume task time slice ON
301	Save the flash drive
310	Load the configuration files
311	Load the module configuration
312	Load process data configuration for Ethernet system bus
313	Stop process data configuration for Ethernet system bus
330	JetIPScan client OFF
331	JetIPScan client ON
202962	**System status register**
Bit 0 = 1	Task switch on I/O access
Bit 1 = 1	Without waiting for communication
Bit 2 = 1	JetIPScan client ON
Bit 3 = 1	Resume task time slice ON
202970	Password for start delay (0x424f6f74)
202971	Start delay in steps of 100 ms
203000	Interface monitoring: JetIP
203001	Interface monitoring: SER
203005	Interface monitoring: STX debug server
203100 ... 203107	32-bit overlaying – Flag 0 ... 255
203108 ... 203123	16-bit overlaying – Flag 0 ... 255
203124 ... 203131	32-bit overlaying – Flag 2048 ... 2303
203132 ... 203147	16-bit overlaying – Flag 2048 ... 2303
209700	System logger: Global enable
209701 ... 209754	System components enable

Application program

Registers	Description
210000	**Application program is running (bit 0 = 1)**
0/2	Stop program
1	Start program
2	Continue program
210001	JetVM version
210004	**Error register (bit-coded)**
Bit 1	Error JX3 system bus
Bit 3	Error on Ethernet system bus
Bit 7	Error in extended error register
Bit 8	Illegal jump
Bit 9	Illegal call
Bit 10	Illegal index
Bit 11	Illegal opcode
Bit 12	Division by 0
Bit 13	Stack overflow
Bit 14	Stack underflow

Registers	Description
Bit 15	Illegal stack
Bit 16	Error when loading the application program
Bit 24	Timeout - Cycle time
Bit 25	Timeout - Task lock
Bit 31	Unknown error
210006	Highest task number
210007	Minimum program cycle time
210008	Maximum program cycle time
210009	Current program cycle time
210011	Current task number
210050	Current program position within an execution unit
210051	ID of the execution unit being processed
210056	Desired total cycle time in µs
210057	Calculated total cycle time in µs
210058	Maximum time slice per task in µs
210060	Task ID (for R210061)
210061	Priority for task [R210060]
210063	Length of scheduler table
210064	Index in scheduler table
210065	Task ID in scheduler table
210070	Task ID (for R210071)
210071	Timer number (0 ... 31)
210072	Manual triggering of a timer event (bit-coded)
210073	End of cyclic task (task ID)
210074	Command for cyclic tasks
210075	Number of timers
210076	Timer number (for R210077)
210077	Timer value in milliseconds
210091	Debugging - STX variable address
210093	Debugging - STX variable value
210100 ... 210199	Task state Please use the STX function TaskGetInfo() as described in the JetSym online help.
210400 ... 210499	Task - Program address
210600	Task ID of a cyclical task (for R210601)
210601	Processing time of a cyclical task in per mil figure
210609	**Task lock timeout in ms**
-1	Monitoring disabled
210610	Timeout (bit-coded, bit 0 → timer 0 etc.)
TCP auto-close for the STX debug server	
212000	Number of open connections
212001	Mode
212002	Time

HMI control

Registers	Description
222804	Total number of display characters
222805	Number of characters per line
222806	Text selection (DisplayText2)
222808	Number of decimal places (UserInput)
222810	Number of decimal places (DisplayValue)
222811	Max. number of decimal places (UserInput)
222812	Field length (DisplayValue)
222813	Field length (UserInput)
222814	Indirect cursor position
222815	Default value for UserInput (Integer/Float)
222816	Displaying the sign
222817	Status UserInput
222818	Enable/disable monitor functions
222819	Display text - monitor function
222820	Switching over to monitor display
222821	Dialog language
222824	Indirect buffer number

Registers	Description
Multi-display mode	
222825	Text buffer for display 1
222826	Text buffer for display 2
222827	Text buffer for display 3
222828	Text buffer for display 4
222829	Basic flag number for display 1
222830	Basic flag number for display 2
222831	Basic flag number for display 3
222832	Basic flag number for display 4
222833	Register number - LED display 1
222834	Register number - LED display 2
222835	Register number - LED display 3
222836	Register number - LED display 4
222837	Module number of PRN (display re-direction)
222838	Module number of SER (display re-direction)
222839	Character code for *Delete display*
222840	Character code for *Delete to end of line*

Networking via JetIP

Register	Description
TCP Autoclose for JetIP**/TCP server**	
230000	Number of open connections
230001	Mode
230002	Time
Other registers for networking via JetIP	
232708	Timeout in milliseconds
232709	Response time in milliseconds
232710	Amount of network errors
232711	**Error code of last access**
0	No error
1	Timeout
3	Error message from remote station
5	Illegal network address
6	Invalid amount of registers
7	Illegal interface number
232717	Maximum number of retries
232718	Number of retries
Network registers	
235000 ... 235399	IP addresses
235400 ... 235799	Port numbers
236000 ... 236399	Indirect register numbers GNN: nnn = 000 ... 199
1nnn020000 ... 1nnn179999	JX3 module register
1nnn810000 ... 1nnn819999	JetMove registers
1nnn980000 ... 1nnn980199	Indirect access via local register 236xxx
1nnn990000 ... 1nnn999999	Indirect access with variable destination window

Ethernet system bus

Register	Description
Subscriber	
250000	**Status (bit-coded)**
Bit 0 = 1	No CRC
Bit 1 = 1	Error in connection with a subscription
Bit 7 = 1	Subscriber is running
250001	**Command**
102	Restart
105	Stop
110	Acknowledge error
250002	Subscription ID of the last error
250003	Number of subscriptions
250004	CRC of configuration file
250005	Start of communication (timeout reg. [ms])
250010	Selection via command

Register	Description
250011	Selection via ID
Subscription	
250020	Status
250021	Mode
250022	Number of elements
250023	Multicast group
250024	Hash
250025	Current sequence number
250026	Size (bytes)
250027	Timeout
250028	Number of received publications
250029	Number of timeout errors
250030	Number of sequence number errors
250100 ... 250999	9 more subscriber register blocks
Address of the bus node (or controller) exceeding the timeout time	
254001	GNN
254002	IP address
254003	Port number
Publisher	
255000	**Status (bit-coded)**
Bit 0 = 1	No CRC
Bit 1 = 1	Error in connection with a publication
Bit 7 = 1	Subscriber is running
255001	**Command**
102	Restart
105	Stop
110	Acknowledge error
255002	Publication ID of the last error
255003	Number of publications
255004	CRC of configuration file
255010	Selection via command
255011	Selection via ID
Publication	
255020	Status
255021	Mode
255022	Number of elements
255023	Multicast group
255024	Hash
255025	Current sequence number
255026	Size (bytes)
255027	Cycle time
255028	Number of publications sent
255029	Number of retries
255030	Number of transmit errors
255100 ... 255999	9 more publisher register blocks

RemoteScan

Registers	Description
262965	Protocol type
262966	Amount of configuration blocks
262967	Status

Modbus/TCP

Registers	Description
272702	Register offset
272704	Input offset
272705	Output offset
278000 ... 278999	16-bit I/O registers overlaid by virtual I/Os 20001 ... 36000

E-mail

Registers	Description
292932	IP address of the SMTP server
292933	IP address of the POP3 server
292934	Port number of SMTP server
292935	Port number of POP3 server
292937	Status of e-mail processing
292938	Task ID - E-mail

File system/data file function

Register	Description
312977	Status of file operation
312978	Task ID

FTP client

Registers	Description
320000	Number of open connections
320001	Command
320002	Timeout
320003	Server port
320004	Selection via number
320005	Selection via handle
320006	Server socket: IP address
320007	Server socket: Port
320008	Client socket: IP address
320009	Client socket: Port
320100	Access status
320101	Task ID

User-programmable IP interface

Registers	Description
Reading out the connection list	
350000	Last result (-1 = no connection selected)
350001	1 = Client; 2 = Server
350002	1 = UDP; 2 = TCP
350003	IP address
350004	Port number
350005	Connection state
350006	Number of sent bytes
350007	Number of received bytes
350008	Number of discarded bytes
350009	Number of discarded packets

Error history

Register	Description
380000	**Status**
Bit 0 = 1	Recording
Bit 1 = 1	Stop if buffer is full
Bit 2 = 1	Stop on error code
Bit 3 = 1	Non-volatile memory
380001	**Command**
1	Clear error log
2	Start error log
3	Stop error log
4	Stop if error buffer is full
5	Circular buffer
6	Stop on error code ON
7	Stop on error code OFF
10	Non-volatile memory
11	Dynamic memory
380002	Buffer length
380003	Maximum buffer length
380004	Number of error entries
380005	Index to error list
380006	Error entry
380007	Error stop code
380008	Number of codes until stop
380029	Group index to error list
380030 ... 380093	64 error entries

I/O networking

Registers	Description
Status register	
390000 + node * 10	Error register
390001 + node * 10	Enhanced error register 1
390002 + node * 10	Enhanced error register 2
390003 + node * 10	JetSync status

Registers	Description
390004 + node * 10	Subscriber status
390005 + node * 10	Subscription ID of the last error
Address of a bus node (not of a controller) having reported an error	
394001	GNN
394002	IP address
394003	Port number
Control register	
395000 + node * 10	Command

NetConsistency function

Registers	Description
Basic drivers	
470000 ... 470008	Cookie
470009	Version
470010	**Status**
Bit 0 = 1	Error
Bit 1 = 1	Alarms
Bit 2 = 1	Basic driver initialized
470011	**Command**
0	There are no commands
470020	Maximum possible number of instances
470021	Number of instances ready for operation
470030	Max. number of error messages for the logger
470031	Number of error messages transmitted to the logger
470032	Max. number of warnings for the logger
470033	Number of warnings forwarded to the logger
470034	Max. possible number of error history entries
470035	Number of entries in the error history
470040	Error numbers
470041	Time of the error in ms
470042	Instance, at which the error occurred
470043	Number of error parameters
470044 ... 470048	Error parameters 1 through 5
470049	Number of characters of the error message
470050 ... 470157	Text of the error message
First instance	
471010	**Status**
Bit 0 = 1	Error
Bit 1 = 1	Alarms
Bit 2 = 1	An instance has been initialized
Bit 3 = 1	Execution in process
471011	**Command**
0	There are no commands

JetIPScan

Registers	Description
Global status information	
520000	Summary of status messages
520010	State of execution - corresponds to the return value *State*
520011	Number of cycles - corresponds to the return value *Count*
520012	Number of changes - corresponds to the return value *Changed*
520013	Result of the function - corresponds to the return value *Result*
Warnings and errors	
521000 ... 521006	All 3 responses are different
521010 ... 521016	Response 1 is different
521020 ... 521026	Response 2 is different

Registers	Description
521030 ... 521036	Response 3 is different
521100 ... 521106	Wrong CtrlID or CtrlIDopt
521200 ... 521206	The node has not called
521300 ... 521306	Multiple call
521400 ... 521406	The IP settings could not be changed
Configuration	
522000	GNN
522010 ... 522015	Set configuration
522110 ... 522123	Actual configuration 1
522210 ... 522223	Actual configuration 2
522310 ... 522323	Actual configuration 3

SW function JCF-SV1

Register range	Description
Initializing the JCF-SV1 SW function	
600000	Status register
600001	Activation of instances
600002	Call interval
600003	Cycle time of all instances
600004 … 600009	Reserve
Configuring the JCF-SV1 SW function for individual axes	
600010 … 600029	**Axis 1**
600010	Source register number of the actual position
600011	Target register number of the manipulated variable
600012	Input number: Negative HW limit switch
600013	Input number: Positive HW limit switch
600014	Input number: Reference switch
600015	Output number: Dig. neg. direction preset
600016	Output number: Dig. pos. direction preset
600017	Output number: Dig. ENABLE for the amplifier
600018 … 600029	Reserve
600030 … 600049	**Axis 2**
600030	Source register number of the actual position
600031	Target register number of the manipulated variable
…	…
600038 … 600049	Reserve
600050 … 600069	**Axis 3** → see axis 1
600070 … 600089	**Axis 4** → see axis 1
600090 … 600109	**Axis 5** → see axis 1
600110 … 600129	**Axis 6** → see axis 1
600130 … 600149	**Axis 7** → see axis 1
600150 … 600169	**Axis 8** → see axis 1
600170 … 600189	**Axis 8** → see axis 1
600190 … 600209	**Axis 10** → see axis 1
600210 … 600229	**Axis 11** → see axis 1

Register range	Description
600230 … 600249	**Axis 12** → see axis 1
600250 … 600269	**Axis 13** → see axis 1
600270 … 600289	**Axis 14** → see axis 1
600290 … 600309	**Axis 15** → see axis 1
600310 … 600329	**Axis 16** → see axis 1
Operation of individual axes	
6yyzzz **6= prefix** **yy = axis number 01 … 16** **zzz = module register number 000 … 999**	
601000 … 601999	Axis 1
602000 … 602999	Axis 2
…	…
616000 … 616999	Axis 16

Application registers

Registers	Description
1000000 ... 1119999	32-bit integer or floating point number (non-volatile)

EtherCAT® system bus

Registers	Description
500002000	Software version of the EtherCAT® system bus driver
500002002	**State of the EtherCAT® master**
1	INIT
2	PREOP
4	SAFEOP
8	OP

Registers	Description	
500002008	**Error register (bit-coded)**	
Bit 0 = 1	Error when initializing	
Bit 1 = 1	Error message from the EtherCAT® master	
Bit 2 = 1	Error during cyclic data exchange	
500002009	Error mask If this bit is set, the corresponding error bit is transferred from register 500002008 to system error register 200010. Assignment:	
	Reg. 500002008	**Reg. 200010**
	Bit 0 →	Bit 16
	Bit 1 →	Bit 17
	Bit 2 →	Bit 18
500002011	Parameters of the recent error in reg. 500002012	
500002012	**Type of the recent error**	
155002 … 155005	Configuration file cannot be read in (EtherCAT® not configured in Hardware Manager of JetSym or file invalid) Content of reg. 500002011 = 0	
155007	Bus could not be launched Content of reg. 500002011 = 0	
155008	Bus configuration does not match the connected modules (incorrect configuration in JetSym, module not connected or not switched on) Content of reg. 500002011 = Number of detected modules	
155207	Bus no longer synchronous Content of reg. 500002011 = -1	
155208	At least one module has changed its bus state Content of reg. 500002011 = State (1, 2, 4, 8)	
155209 … 155210	Error when accessing parameter data of a module Content of reg. 500002011 = Error code	
155214	Emergency message from a module Content of reg. 500002011 = Error code	

Registers	Description
155215	Error during firmware update Content of reg. 500002011 = Error code
155247	Not all modules are in OP state Content of reg. 500002011 = -1
155248	No network connection (EtherCAT® cable not connected) Content of reg. 500002011 = -1
155251	Error message from a module Content of reg. 500002011 = Module address
155400	Error while receiving cyclic data (EtherCAT® cable not connected) Content of reg. 500002011 = Negative value
155401 … 155403	Error when sending cyclic data Content of reg. 500002011 = -1
500002013	Number of EtherCAT® modules detected
500002015	Index to module array
500002016	Module array: Type
500002017	Module array: Product ID
500002018	Module array: Vendor ID
500002019	Index to submodule array
500002020	Submodule array: Type

JX3 system bus registers

Registers	Description
100000000	**Bus status**
Bit 15 = 1	Data exchange takes place via JX3 system bus.
100002000	JX3 system bus hardware revision
100002008	**Error (bit-coded)**
Bit 3 =1	Error at module access
Bit 16 = 1	Fatal irrecoverable error has occurred. Data interchange has been aborted.
100002011	I/O module number where error has occurred
100002013	Number of detected I/O modules
100002015	Index to module array
100002016	Module array
100002023	Dummy modules
100002034	Number of retries
100002072	Version of the JX3 system bus driver
100002111	Module register number where error has occurred
100002764	Timeout period for register access [ms]
100003xx0 ... 100003xx9	Registers on I/O modules (compatibility mode) xx: Module number - 2 (00 ... 15)
100004000 ... 100004367	Inputs/outputs mapped to registers
100xx0000 … 100xx9999	Registers on I/O modules (direct access) xx: Module number (02 ... 17)

Addressing inputs/outputs

I/O numbers	Description
20001 ... 36000	Virtual I/Os for RemoteScan
10000xx01 ... 10000xx16	JX3 modules (xx: 02 ... 17)
1nnn01xx01 ... 1nnn01xx16	JX3 modules via JX3-BN-ETH GNN: 000 ... 199 xx: 02 ... 24)

User-programmable CAN interface

Registers	Description
200010500	Status register
Bit 1 = 1	CAN message has been received
Bit 2 = 0	11-bit CAN ID
Bit 2 = 1	29-bit CAN ID
200010501	**Command register**
Direct access	
7	Clearing the Fifo buffer
8	Setting CAN ID to 11 bits
9	Setting CAN ID to 29 bits
10	Checking boxes for received messages

Registers	Description
Indirect access	
1	Enabling the message box
2	Disabling the message box
3	Sending CAN messages
4	Clearing the NEW DAT bit
5	Clearing the OVERRUN bit
6	Clearing the sending error bit
7	Clearing the Fifo buffer
8	Setting CAN ID to 11 bits
9	Setting CAN ID to 29 bits
10	Checking boxes for received messages
200010502	Message box number (indirect access)
200010503	FIFO buffer occupancy
200010504	FIFO data
200010506	Global receive mask
200010507	Global receive ID
200010509	Version of the user-programmable CAN interface (IP)
Indirect access	
200010510	Message box status register
200010511	Message box configuration register
200010512	CAN-ID
200010513	Number of data bytes
200010514 ... 200010521	Data bytes 0 through 7
Direct access	
200010530 + box number * 20	Message box status register
200010531 + box number * 20	Message box configuration register
200010532 + box number * 20	CAN-ID
200010533 + box number * 20	Number of data bytes
200010534 ... 200010541 + box number * 20	Data bytes
200010542 + box number * 20	CAN-ID mask
200010543 + box number * 20	Box command register
200010544 + box number * 20	Received CAN-ID

32 combined inputs

Register	Description			
System bus JX3: Register + 100000000 / Network: + 1GNN910000				
Example	Register number 100004002 lets you access inputs 1 ... 8 and 9 ... 16 of the JX3 modules at positions 2 and 3.			
4000	101 ... 108	109 ... 116	201 ... 208	209 ... 216
4001	109 ... 116	201 ... 208	209 ... 216	301 ... 308
4002	201 ... 208	209 ... 216	301 ... 308	309 ... 316
4003	209 ... 216	301 ... 308	309 ... 316	401 ... 408
4004	301 ... 308	309 ... 316	401 ... 408	409 ... 416
4005	309 ... 316	401 ... 408	409 ... 416	501 ... 508
4006	401 ... 408	409 ... 416	501 ... 508	509 ... 516
4007	409 ... 416	501 ... 508	509 ... 516	601 ... 608
4008	501 ... 508	509 ... 516	601 ... 608	609 ... 616
4009	509 ... 516	601 ... 608	609 ... 616	701 ... 708

Register	Description			
4010	601 ... 608	609 ... 616	701 ... 708	709 ... 716
4011	609 ... 616	701 ... 708	709 ... 716	801 ... 808
4012	701 ... 708	709 ... 716	801 ... 808	809 ... 816
4013	709 ... 716	801 ... 808	809 ... 816	901 ... 908
4014	801 ... 808	809 ... 816	901 ... 908	909 ... 916
4015	809 ... 816	901 ... 908	909 ... 916	1001 ... 1008
4016	901 ... 908	909 ... 916	1001 ... 1008	1009 ... 1016
4017	909 ... 916	1001 ... 1008	1009 ... 1016	1101 ... 1108
4018	1001 ... 1008	1009 ... 1016	1101 ... 1108	1109 ... 1116
4019	1009 ... 1016	1101 ... 1108	1109 ... 1116	1201 ... 1208
4020	1101 ... 1108	1109 ... 1116	1201 ... 1208	1209 ... 1216
4021	1109 ... 1116	1201 ... 1208	1209 ... 1216	1301 ... 1308
4022	1201 ... 1208	1209 ... 1216	1301 ... 1308	1309 ... 1316
4023	1209 ... 1216	1301 ... 1308	1309 ... 1316	1401 ... 1408
4024	1301 ... 1308	1309 ... 1316	1401 ... 1408	1409 ... 1416
4025	1309 ... 1316	1401 ... 1408	1409 ... 1416	1501 ... 1508
4026	1401 ... 1408	1409 ... 1416	1501 ... 1508	1509 ... 1516
4027	1409 ... 1416	1501 ... 1508	1509 ... 1516	1601 ... 1608
4028	1501 ... 1508	1509 ... 1516	1601 ... 1608	1609 ... 1616
4029	1509 ... 1516	1601 ... 1608	1609 ... 1616	1701 ... 1708
4030	1601 ... 1608	1609 ... 1616	1701 ... 1708	1709 ... 1716

Register	Description			
4031	1609 ... 1616	1701 ... 1708	1709 ... 1716	1801 ... 1808
4032	1701 ... 1708	1709 ... 1716	1801 ... 1808	1809 ... 1816
4033	1709 ... 1716	1801 ... 1808	1809 ... 1816	1901 ... 1908
4034	1801 ... 1808	1809 ... 1816	1901 ... 1908	1909 ... 1916
4035	1809 ... 1816	1901 ... 1908	1909 ... 1916	2001 ... 2008
4036	1901 ... 1908	1909 ... 1916	2001 ... 2008	2009 ... 2016
4037	1909 ... 1916	2001 ... 2008	2009 ... 2016	2101 ... 2108
4038	2001 ... 2008	2009 ... 2016	2101 ... 2108	2109 ... 2116
4039	2009 ... 2016	2101 ... 2108	2109 ... 2116	2201 ... 2208
4040	2101 ... 2108	2109 ... 2116	2201 ... 2208	2209 ... 2216
4041	2109 ... 2116	2201 ... 2208	2209 ... 2216	2301 ... 2308
4042	2201 ... 2208	2209 ... 2216	2301 ... 2308	2309 ... 2316
4043	2209 ... 2216	2301 ... 2308	2309 ... 2316	2401 ... 2408
4044	2301 ... 2308	2309 ... 2316	2401 ... 2408	2409 ... 2416

16 combined inputs

Register	Description	
System bus JX3: Register + 100000000 / Network: + 1GNN910000		
Example	Register number 100004062 lets you access inputs 1 ... 8 and 9 ... 16 of the JX3 module at position 2.	
4060	101 … 108	109 … 116
4061	109 … 116	201 … 208
4062	201 … 208	209 … 216
4063	209 … 216	301 … 308
4064	301 … 308	309 … 316

Register	Description	
4065	309 … 316	401 … 408
4066	401 … 408	409 … 416
4067	409 … 416	501 … 508
4068	501 … 508	509 … 516
4069	509 … 516	601 … 608
4070	601 … 608	609 … 616
4071	609 … 616	701 … 708
4072	701 … 708	709 … 716
4073	709 … 716	801 … 808
4074	801 … 808	809 … 816
4075	809 … 816	901 … 908
4076	901 … 908	909 … 916
4077	909 … 916	1001 … 1008
4078	1001 … 1008	1009 … 1016
4079	1009 … 1016	1101 … 1108
4080	1101 … 1108	1109 … 1116
4081	1109 … 1116	1201 … 1208
4082	1201 … 1208	1209 … 1216
4083	1209 … 1216	1301 … 1308
4084	1301 … 1308	1309 … 1316
4085	1309 … 1316	1401 … 1408
4086	1401 … 1408	1409 … 1416
4087	1409 … 1416	1501 … 1508
4088	1501 … 1508	1509 … 1516
4089	1509 … 1516	1601 … 1608
4090	1601 … 1608	1609 … 1616
4091	1609 … 1616	1701 … 1708
4092	1701 … 1708	1709 … 1716
4093	1709 … 1716	1801 … 1808
4094	1801 … 1808	1809 … 1816
4095	1809 … 1816	1901 … 1908
4096	1901 … 1908	1909 … 1916
4097	1909 … 1916	2001 … 2008
4098	2001 … 2008	2009 … 2016
4099	2009 … 2016	2101 … 2108
4100	2101 … 2108	2109 … 2116
4101	2109 … 2116	2201 … 2208
4102	2201 … 2208	2209 … 2216
4103	2209 … 2216	2301 … 2308
4104	2301 … 2308	2309 … 2316
4105	2309 … 2316	2401 … 2408
4106	2401 … 2408	2409 … 2416

8 combined inputs

Register	Description
System bus JX3: Register + 100000000 / Network: + 1GNN910000	
Example	Register number 100004122 lets you access inputs 1 ... 8 of the JX3 module at position 2.
4120	101 ... 108
4121	109 ... 116
4122	201 ... 208
4123	209 ... 216
4124	301 ... 308
4125	309 ... 316
4126	401 ... 408
4127	409 ... 416
4128	501 ... 508
4129	509 ... 516
4130	601 ... 608
4131	609 ... 616
4132	701 ... 708
4133	709 ... 716
4134	801 ... 808
4135	809 ... 816
4136	901 ... 908
4137	909 ... 916
4138	1001 ... 1008
4139	1009 ... 1016
4140	1101 ... 1108
4141	1109 ... 1116

Register	Description
4142	1201 ... 1208
4143	1209 ... 1216
4144	1301 ... 1308
4145	1309 ... 1316
4146	1401 ... 1408
4147	1409 ... 1416
4148	1501 ... 1508
4149	1509 ... 1516
4150	1601 ... 1608
4151	1609 ... 1616
4152	1701 ... 1708
4153	1709 ... 1716
4154	1801 ... 1808
4155	1809 ... 1816
4156	1901 ... 1908
4157	1909 ... 1916
4158	2001 ... 2008
4159	2009 ... 2016
4160	2101 ... 2108
4161	2109 ... 2116
4162	2201 ... 2208
4163	2209 ... 2216
4164	2301 ... 2308
4165	2309 ... 2316
4166	2401 ... 2408
4167	2409 ... 2416

32 combined outputs

Register	Description			
System bus JX3: Register + 100000000 / Network: + 1GNN910000				
Example	Register number 100004202 lets you access outputs 1 ... 8 and 9 ... 16 of the JX3 modules at positions 2 and 3.			
4200	101 ... 108	109 ... 116	201 ... 208	209 ... 216
4201	109 ... 116	201 ... 208	209 ... 216	301 ... 308
4202	201 ... 208	209 ... 216	301 ... 308	309 ... 316
4203	209 ... 216	301 ... 308	309 ... 316	401 ... 408
4204	301 ... 308	309 ... 316	401 ... 408	409 ... 416
4205	309 ... 316	401 ... 408	409 ... 416	501 ... 508
4206	401 ... 408	409 ... 416	501 ... 508	509 ... 516
4207	409 ... 416	501 ... 508	509 ... 516	601 ... 608
4208	501 ... 508	509 ... 516	601 ... 608	609 ... 616
4209	509 ... 516	601 ... 608	609 ... 616	701 ... 708
4210	601 ... 608	609 ... 616	701 ... 708	709 ... 716
4211	609 ... 616	701 ... 708	709 ... 716	801 ... 808
4212	701 ... 708	709 ... 716	801 ... 808	809 ... 816
4213	709 ... 716	801 ... 808	809 ... 816	901 ... 908
4214	801 ... 808	809 ... 816	901 ... 908	909 ... 916
4215	809 ... 816	901 ... 908	909 ... 916	1001 ... 1008
4216	901 ... 908	909 ... 916	1001 ... 1008	1009 ... 1016
4217	909 ... 916	1001 ... 1008	1009 ... 1016	1101 ... 1108
4218	1001 ... 1008	1009 ... 1016	1101 ... 1108	1109 ... 1116
4219	1009 ... 1016	1101 ... 1108	1109 ... 1116	1201 ... 1208
4220	1101 ... 1108	1109 ... 1116	1201 ... 1208	1209 ... 1216
4221	1109 ... 1116	1201 ... 1208	1209 ... 1216	1301 ... 1308

Register	Description			
4222	1201 ... 1208	1209 ... 1216	1301 ... 1308	1309 ... 1316
4223	1209 ... 1216	1301 ... 1308	1309 ... 1316	1401 ... 1408
4224	1301 ... 1308	1309 ... 1316	1401 ... 1408	1409 ... 1416
4225	1309 ... 1316	1401 ... 1408	1409 ... 1416	1501 ... 1508
4226	1401 ... 1408	1409 ... 1416	1501 ... 1508	1509 ... 1516
4227	1409 ... 1416	1501 ... 1508	1509 ... 1516	1601 ... 1608
4228	1501 ... 1508	1509 ... 1516	1601 ... 1608	1609 ... 1616
4229	1509 ... 1516	1601 ... 1608	1609 ... 1616	1701 ... 1708
4230	1601 ... 1608	1609 ... 1616	1701 ... 1708	1709 ... 1716
4231	1609 ... 1616	1701 ... 1708	1709 ... 1716	1801 ... 1808
4232	1701 ... 1708	1709 ... 1716	1801 ... 1808	1809 ... 1816
4233	1709 ... 1716	1801 ... 1808	1809 ... 1816	1901 ... 1908
4234	1801 ... 1808	1809 ... 1816	1901 ... 1908	1909 ... 1916
4235	1809 ... 1816	1901 ... 1908	1909 ... 1916	2001 ... 2008
4236	1901 ... 1908	1909 ... 1916	2001 ... 2008	2009 ... 2016
4237	1909 ... 1916	2001 ... 2008	2009 ... 2016	2101 ... 2108
4238	2001 ... 2008	2009 ... 2016	2101 ... 2108	2109 ... 2116
4239	2009 ... 2016	2101 ... 2108	2109 ... 2116	2201 ... 2208
4240	2101 ... 2108	2109 ... 2116	2201 ... 2208	2209 ... 2216
4241	2109 ... 2116	2201 ... 2208	2209 ... 2216	2301 ... 2308
4242	2201 ... 2208	2209 ... 2216	2301 ... 2308	2309 ... 2316
4243	2209 ... 2216	2301 ... 2308	2309 ... 2316	2401 ... 2408
4244	2301 ... 2308	2309 ... 2316	2401 ... 2408	2409 ... 2416

16 combined outputs

Register	Description	
System bus JX3: Register + 100000000 / Network: + 1GNN910000		
Example	Register number 100004262 lets you access outputs 1 ... 8 and 9 ... 16 of the JX3 module at position 2.	
4260	101 ... 108	109 ... 116
4261	109 ... 116	201 ... 208
4262	201 ... 208	209 ... 216
4263	209 ... 216	301 ... 308
4264	301 ... 308	309 ... 316
4265	309 ... 316	401 ... 408
4266	401 ... 408	409 ... 416
4267	409 ... 416	501 ... 508
4268	501 ... 508	509 ... 516
4269	509 ... 516	601 ... 608
4270	601 ... 608	609 ... 616
4263	209 ... 216	301 ... 308
4271	609 ... 616	701 ... 708
4272	701 ... 708	709 ... 716
4273	709 ... 716	801 ... 808
4274	801 ... 808	809 ... 816
4275	809 ... 816	901 ... 908
4276	901 ... 908	909 ... 916
4277	909 ... 916	1001 ... 1008
4278	1001 ... 1008	1009 ... 1016
4279	1009 ... 1016	1101 ... 1108
4280	1101 ... 1108	1109 ... 1116
4281	1109 ... 1116	1201 ... 1208
4282	1201 ... 1208	1209 ... 1216
4283	1209 ... 1216	1301 ... 1308

Register	Description	
4284	1301 ... 1308	1309 ... 1316
4285	1309 ... 1316	1401 ... 1408
4286	1401 ... 1408	1409 ... 1416
4287	1409 ... 1416	1501 ... 1508
4288	1501 ... 1508	1509 ... 1516
4289	1509 ... 1516	1601 ... 1608
4290	1601 ... 1608	1609 ... 1616
4291	1609 ... 1616	1701 ... 1708
4292	1701 ... 1708	1709 ... 1716
4293	1709 ... 1716	1801 ... 1808
4294	1801 ... 1808	1809 ... 1816
4295	1809 ... 1816	1901 ... 1908
4296	1901 ... 1908	1909 ... 1916
4297	1909 ... 1916	2001 ... 2008
4298	2001 ... 2008	2009 ... 2016
4299	2009 ... 2016	2101 ... 2108
4300	2101 ... 2108	2109 ... 2116
4301	2109 ... 2116	2201 ... 2208
4302	2201 ... 2208	2209 ... 2216
4303	2209 ... 2216	2301 ... 2308
4304	2301 ... 2308	2309 ... 2316
4305	2309 ... 2316	2401 ... 2408
4306	2401 ... 2408	2409 ... 2416

8 combined outputs

Register	Description
System bus JX3: Register + 100000000 / Network: + 1GNN910000	
Example	Register number 100004322 lets you access outputs 1 ... 8 of the JX3 module at position 2.
4320	101 ... 108
4321	109 ... 116
4322	201 ... 208
4323	209 ... 216
4324	301 ... 308
4325	309 ... 316
4326	401 ... 408
4327	409 ... 416
4328	501 ... 508
4329	509 ... 516
4330	601 ... 608
4331	609 ... 616
4332	701 ... 708
4333	709 ... 716
4334	801 ... 808
4335	809 ... 816
4336	901 ... 908
4337	909 ... 916
4338	1001 ... 1008
4339	1009 ... 1016
4340	1101 ... 1108
4341	1109 ... 1116
4342	1201 ... 1208
4343	1209 ... 1216
4344	1301 ... 1308
4345	1309 ... 1316
4346	1401 ... 1408
4347	1409 ... 1416
4348	1501 … 1508
4349	1509 ... 1516
4350	1601 … 1608
4351	1609 ... 1616
4352	1701 ... 1708
4353	1709 … 1716
4354	1801 … 1808
4355	1809 … 1816
4356	1901 … 1908
4357	1909 … 1916
4358	2001 … 2008
4359	2009 … 2016
4360	2101 … 2108

Regis-ter	Description
4361	2109 ... 2116
4362	2201 … 2208
4363	2209 … 2216
4364	2301 … 2308
4365	2309 … 2316
4366	2401 … 2408
4367	2409 … 2416

Special flags for networks

Flag	Description
2075	Error in networking via JetIP
2080	Ethernet system bus error in R 200008
2081	Ethernet system bus error

Special flags - Interface monitoring

Flag	Description
2088	OS flag – JetIP
2089	User flag – JetIP
2090	OS flag - SER
2091	User flag - SER
2098	OS flag - Debug server
2099	User flag - Debug server

Special flags - HMIs

Flag	Description
does not apply to LCD 27	
2160	[0]
2161	[1]
2162	[2]
2163	[3]
2164	[4]
2165	[5]
2166	[6]
2167	[7]
2168	[8]
2169	[9]
2170	[SHIFT]+[0]
2171	[SHIFT]+[1]
2172	[SHIFT]+[2]
2173	[SHIFT]+[3]
2174	[SHIFT]+[4]
2175	[SHIFT]+[5]
2176	[SHIFT]+[6]
2177	[SHIFT]+[7]
2178	[SHIFT]+[8]
2179	[SHIFT]+[9]
2181	[SHIFT]+[F1]
2182	[SHIFT]+[F2]
2183	[SHIFT]+[F3]
2184	[SHIFT]+[F4]
2185	[SHIFT]+[F5]
2186	[SHIFT]+[F6]
2187	[SHIFT]+[F7]
2188	[SHIFT]+[F8]
2189	[SHIFT]+[F9]
2190	[SHIFT]+[F10]
2191	[SHIFT]+[F11]
2192	[SHIFT]+[F12]
2193	[SHIFT]+[←]
2194	[SHIFT]+[→]
2195	[SHIFT]+[R]
2196	[SHIFT]+[I/O]
2197	[SHIFT]+[=]
2198	[SHIFT]+[C]
2199	[SHIFT]+[ENTER]
2200	[SHIFT]
2201	[F1]
2202	[F2]
2203	[F3]
2204	[F4]
2205	[F5]

Flag	Description
2206	[F6]
2207	[F7]
2208	[F8]
2209	[F9]
2210	[F10]
2211	[F11]
2212	[F12]
2213	[→]
2214	[←]
2215	[R]
2216	[I/O]
2217	[=]
2218	[C]
2219	[ENTER]
2220	[-]
2221	[SHIFT]+[-]
2222	[.]
2223	[SHIFT]+[.]
2224	LED of [F1]
2225	LED of [F2]
2226	LED of [F3]
2227	LED of [F4]
2228	LED of [F5]
2229	LED of [F6]
2230	LED of [F7]
2231	LED of [F8]
2232	LED of [F9]
2233	LED of [F10]
2234	LED of [F11]
2235	LED of [F12]

Special flags for HMI LCD 27

Flag	Description
2209	[↑]
2210	[↓]
2211	[C]
2212	[ENTER]

Special flags for HMI NUM 25

Flag	Description
2186	[SHIFT]+[S1]
2187	[SHIFT]+[S2]
2188	[SHIFT]+[S3]
2189	[SHIFT]+[S4]
2190	[SHIFT]+[S5]
2206	[S1]
2207	[S2]
2208	[S3]
2209	[S4]
2210	[S5]

32 combined flags

Registers	Description
203100	0 ... 31
203101	32 ... 63
203102	64 ... 95
203103	96 ... 127
203104	128 ... 159
203105	160 ... 191
203106	192 ... 223
203107	224 ... 255

16 combined flags

Registers	Description
203108	0 ... 15
203109	16 ... 31
203110	32 ... 47
203111	48 ... 63
203112	64 ... 79
203113	80 ... 95
203114	96 ... 111
203115	112 ... 127
203116	128 ... 143
203117	144 ... 159
203118	160 ... 175
203119	176 ... 191

Registers	Description
203120	192 ... 207
203121	208 ... 223
203122	224 ... 239
203123	240 ... 255

32 combined special flags

Registers	Description
203124	2048 ... 2079
203125	2080 ... 2111
203126	2112 ... 2143
203127	2144 ... 2175
203128	2176 ... 2207
203129	2208 ... 2239
203130	2240 ... 2271
203131	2272 ... 2303

16 combined special flags

Registers	Description
203132	2048 ... 2063
203133	2064 ... 2079
203134	2080 ... 2095
203135	2096 ... 2111
203136	2112 ... 2127
203137	2128 ... 2143
203138	2144 ... 2159
203139	2160 ... 2175
203140	2176 ... 2191
203141	2192 ... 2207
203142	2208 ... 2223
203143	2224 ... 2239
203144	2240 ... 2255
203145	2256 ... 2271
203146	2272 ... 2287
203147	2288 ... 2303

Application registers with overlaid flags

Registers	Description
1000000	256 ... 287
1000001	288 ... 319
1000002	320 ... 351
1000003	352 ... 383
1000004	384 ... 415
1000005	416 ... 447
1000006	448 ... 479
1000007	480 ... 511
1000008	512 ... 543
1000009	544 ... 575
1000010	576 ... 607
1000011	608 ... 639
1000012	640 ... 671
1000013	672 ... 703
1000014	704 ... 735
1000015	736 ... 767
1000016	768 ... 799
1000017	800 ... 831
1000018	832 ... 863
1000019	864 ... 895
1000020	896 ... 927
1000021	928 ... 959
1000022	960 ... 991
1000023	992 ... 1023
1000024	1024 ... 1055
1000025	1056 ... 1087
1000026	1088 ... 1119
1000027	1120 ... 1151
1000028	1152 ... 1183
1000029	1184 ... 1215
1000030	1216 ... 1247
1000031	1248 ... 1279
1000032	1280 ... 1311
1000033	1312 ... 1343

Registers	Description
1000034	1344 ... 1375
1000035	1376 ... 1407
1000036	1408 ... 1439
1000037	1440 ... 1471
1000038	1472 ... 1503
1000039	1504 ... 1535
1000040	1536 ... 1567
1000041	1568 ... 1599
1000042	1600 ... 1631
1000043	1632 ... 1663
1000044	1664 ... 1695
1000045	1696 ... 1727
1000046	1728 ... 1759
1000047	1760 ... 1791
1000048	1792 ... 1823
1000049	1824 ... 1855
1000050	1856 ... 1887
1000051	1888 ... 1919
1000052	1920 ... 1951
1000053	1952 ... 1983
1000054	1984 ... 2015
1000055	2016 ... 2047

System Functions

For reasons of compatibility, the system functions are listed below.
In JetSym STX, use the corresponding JetSym STX functions instead of the system functions.

System function	Description
4	Converting BCD to HEX
5	Converting HEX to BCD
20	Square root
21	Sine
22	Cosine
23	Tangent
24	Arc sine
25	Arc cosine
26	Arc tangent
27	Exponential function
28	Natural logarithm
29	Absolute value
30	Separation of digits before and after the decimal point
50	Sorting register values
60	CRC generation for Modbus RTU
61	CRC check for Modbus RTU
65/67	Reading register block via Modbus/TCP
66/68	Writing register block via Modbus/TCP
80/85	Initializing RemoteScan
81	Starting RemoteScan
82	Stopping RemoteScan
90	Writing a data file
91	Appending a data file
92	Reading a data file
96	Deleting a data file
150	Configuring NetCopyList
151	Deleting NetCopyList
152	Sending NetCopyList

System function	Corresponding JetSym STX function
4	Function Bcd2Hex(Bcd: int): Int;
5	Function Hex2Bcd(Hex: int): Int;
50	Function QSort(DataPtr: Int, ElementCnt: Int, ElementSize: Int, SortOffset: Int, SortType: STXBASETYPE, SortMode: QSORTMODE): Int;
60	Function ModbusCRCgen(FramePtr: Int, Length: int): Int;
61	Function ModbusCRCcheck(FramePtr: Int, Length: int): Int;
65/67	Function ModbusReadReg(Const Ref MbParam: MODBUS_PARAM): Int;
66/68	Function ModbusWriteReg(Const Ref MbParam: MODBUS_PARAM): Int;
80/85	Function RemoteScanConfig(Protocol: RSCAN_PROTOCOL, Elements: Int, Const Ref Configuration: RSCAN_DSCR): Int;
81	Function RemoteScanStart(Protocol: int): Int;
82	Function RemoteScanStop(Protocol: int): Int;
90/91	Function FileDAWrite(Const Ref FileName: String, Const Ref Mode: String, VarType: DAWRITE_TYPE, First: Int, Last: int): Int;
92	Function FileDARead(Const Ref FileName: String): Int;
110	Function EmailSend(Const Ref FileName: String): Int;
150	Function NetCopyListConfig(IPAddr: Int, IPPort: Int, Const Ref List: TNetCopyLinstL): Int;
151	Function NetCopyListSend(Handle: int): Int;
152	Function NetCopyListDelete(Handle: int): Int;

10 Maintenance

This device is maintenance free. Therefore, for the operation of the device, no inspection or maintenance is required.

10.1 Repairs

Defective components could cause dangerous malfunctions and could compromise safety.
Only the manufacturer is allowed to repair the device.
It is forbidden to open the device.

Modifications to the device

Modifications and alterations to the device and its functions are not allowed. In the case of modifications to the device, any liability is excluded.

The original parts are specifically designed for the device. Parts and equipment from other manufacturers must, therefore, not be used.

Any liability for any damages resulting from the use of non-original parts and equipment is excluded.

10.2 Storage and Shipment

Storage

When storing the device observe the environmental conditions given in chapter “Technical specifications”.

Shipment and packaging

The device contains electrostatically sensitive components which can be damaged if not handled properly. Damages to the device may impair its reliability.

To protect the device from impact or shock, it must be shipped in its original packaging, or in an appropriate protective ESD packaging.
In case of damaged packaging inspect the device for any visible damage, and inform your freight forwarder and the Bucher Automation AG of the damage caused during shipment. If the device is damaged or has been dropped, it is strictly forbidden to use it.

10.3 Return and Disposal

Disposal options

Return your Bucher Automation AG product to us for proper disposal. Find detailed information along with the required Return Delivery Form on our website.

Meaning of WEEE icon



Fig. 28: WEEE icon – crossed out trash can

The product is waste electronic equipment and must be disposed of by a certified waste management facility. Do not dispose of the product with normal household waste. Applicable local environmental directives and regulations must be complied with.

Batteries

Prior to disposing of waste electronics, remove any batteries where this is possible in a safe and non-destructive way. Dispose of batteries properly.

Personal data

It is the responsibility of the customers to delete any personal data stored on waste electric and electronic equipment prior to disposal.

11 Service

11.1 Technical support

In case of questions, suggestions, or issues, please contact our experts from Technical Support. You may reach out by phone or through the contact form on our homepage:

Technical Support | www.bucherautomation.com

Or email us:

support@bucherautomation.com

Please supply the following information when contacting Technical Support:

– Hardware revision and serial number
  The hardware revision and serial number is printed on the nameplate of the product.
– OS version
  To determine the operating system version, use the functions of the development environment.

12 Spare parts and accessories

NOTICE



Inadequate accessories might cause damage to the product

Parts and equipment from other manufacturers might impede the function of the device and cause damage to the product.

► Only use accessories recommended by Bucher Automation AG.

12.1 Spare Parts

Component	Item number
Terminal labels	60870411
Key	60870410
Male connector in spring-cage technology, 2-pin	60870409

Tab. 63: Spare parts

12.2 Accessories

ⓘ Info

Ordering Accessories

The accessories are not part of the scope of delivery.

Suitable accessories can be obtained from Bucher Automation AG.

Component	Item number
Screwdriver	60871712
End clamp for DIN rail	60863970

Tab. 64: Accessories

12.2.1 CAN bus cable

Component	Item number
Cable assy # 530 0.2 m	10309001
Cable assy # 530 0.5 m	10309002
Cable assy # 530 1.0 m	10309003
Cable assy # 530 1.5 m	10309004
Cable assy # 530 2.0 m	10309006
Cable assy # 530 2.5 m	10309016
Cable assy # 530 3.0 m	10309015
Cable assy # 530 4.0 m	10309007
Cable assy # 530 5.0 m	10309008

Component	Item number
Y-cable KAY_Breakout_Cable-second_CAN	60880710

12.2.2 Ethernet/EtherCAT® cable

Component	Item number
Patch cable 1:1, 1 m, gray, Hirose, Cat 5e, shielded	60537500
Patch cable 1:1, 2 m, gray, Hirose, Cat 5e, shielded	60854512
Patch cable 1:1, 5 m, gray, Hirose, Cat 5e, shielded	60854514
Patch cable 1:1, 10 m, gray, Hirose, Cat 5e, shielded	60854515

12.2.3 Cable for the serial interface

Controller to modem

Component	Description	Item number
KAY_0576-0050	From controller to modem 9-pin Sub-D, length 0.5 m	60867209

From controller to PC

Component	Description	Item number
Cable assy no.196 2.5M	From controller to PC 9-pin Sub-D, length 2.5 m	60868359
Cable assy no.196 5M	From controller to PC 9-pin Sub-D, length 5 m	60860013
Cable assy no.196 8M	From controller to PC 9-pin Sub-D, length 8 m	60868956

Controller to LCD 16, 23, 25, 27, 110

Component	Description	Item number
Cable assy no. 192 2.5M	From controller to HMI 15-pin Sub-D, length 2.5 m	60860011
Cable assy no. 193 5M	From controller to HMI 15-pin Sub-D, length 5 m	60860012

Controller to LCD 60

Component	Description	Item number
KAY_0386-0250	From controller to LCD 60 15-pin Sub-D, length 2.5 m	60864359
KAY_0386-0500	From controller to LCD 60 15-pin Sub-D, length 5 m	60864360

Controller to LCD 52/54(Z)

Component	Description	Item number
KAY_0533-0025	From controller to LCD 52/54(Z) 15-pin Sub-D, length 0.25 m	60864897

Controller to JetView 200/300

Component	Description	Item number
Cable assy no. 197 5M	From controller to 200/300 9-pin Sub-D, length 5 m	60864257
Cable assy no. 197 12M	From controller to 200/300 9-pin Sub-D, length 12 m	60871930

12.2.4 USB flash drives

Component	Item number
USB flash drive XMORE, 4 GB, XQC8	60876836

Tab. 65: Accessories – USB flash drives

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